

Matrix Inverses

Geometric Algorithms

Lecture 10

Objectives

1. Define a few more important matrix operations
2. Motivate and define matrix inverses
3. Application: Adjacency Matrices

Keywords

Matrix Transpose

Inner Product

Matrix Power

Square Matrix

Matrix Inverse

Invertible Transformation

1-1 Correspondence

`numpy.linalg.inv`

determinant

Invertible Matrix Theorem

Recap Problem

Suppose that A , $B = [\mathbf{b}_1 \ \mathbf{b}_2 \ \mathbf{b}_3]$ and $C = [\mathbf{c}_1 \ \mathbf{c}_2 \ \mathbf{c}_3]$ are matrices such that

I : identity matrix

$$A(B + 5I) = C$$

Find a solution to the equation $A\mathbf{x} = \mathbf{c}_2$.

$$\begin{bmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{bmatrix}$$

hint: your solution should have \vec{e}_2 (the standard basis vector)

Answer: $\mathbf{b}_2 + 5\mathbf{e}_2$

$$\begin{aligned} A(B + 5I) &= A([\mathbf{b}_1, \mathbf{b}_2, \mathbf{b}_3] + 5[\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3]) \\ &= A([\mathbf{b}_1 + 5\mathbf{e}_1, \mathbf{b}_2 + 5\mathbf{e}_2, \mathbf{b}_3 + 5\mathbf{e}_3]) \end{aligned}$$

$$= \begin{bmatrix} \dots & A(\mathbf{b}_2 + 5\mathbf{e}_2) & \dots \end{bmatrix}$$

$$\underline{\underline{A(\mathbf{b}_2 + 5\mathbf{e}_2) = \mathbf{c}_2}}$$

Solution

$$= \begin{bmatrix} \mathbf{c}_1 & \mathbf{c}_2 & \mathbf{c}_3 \end{bmatrix}$$

More Matrix Operations

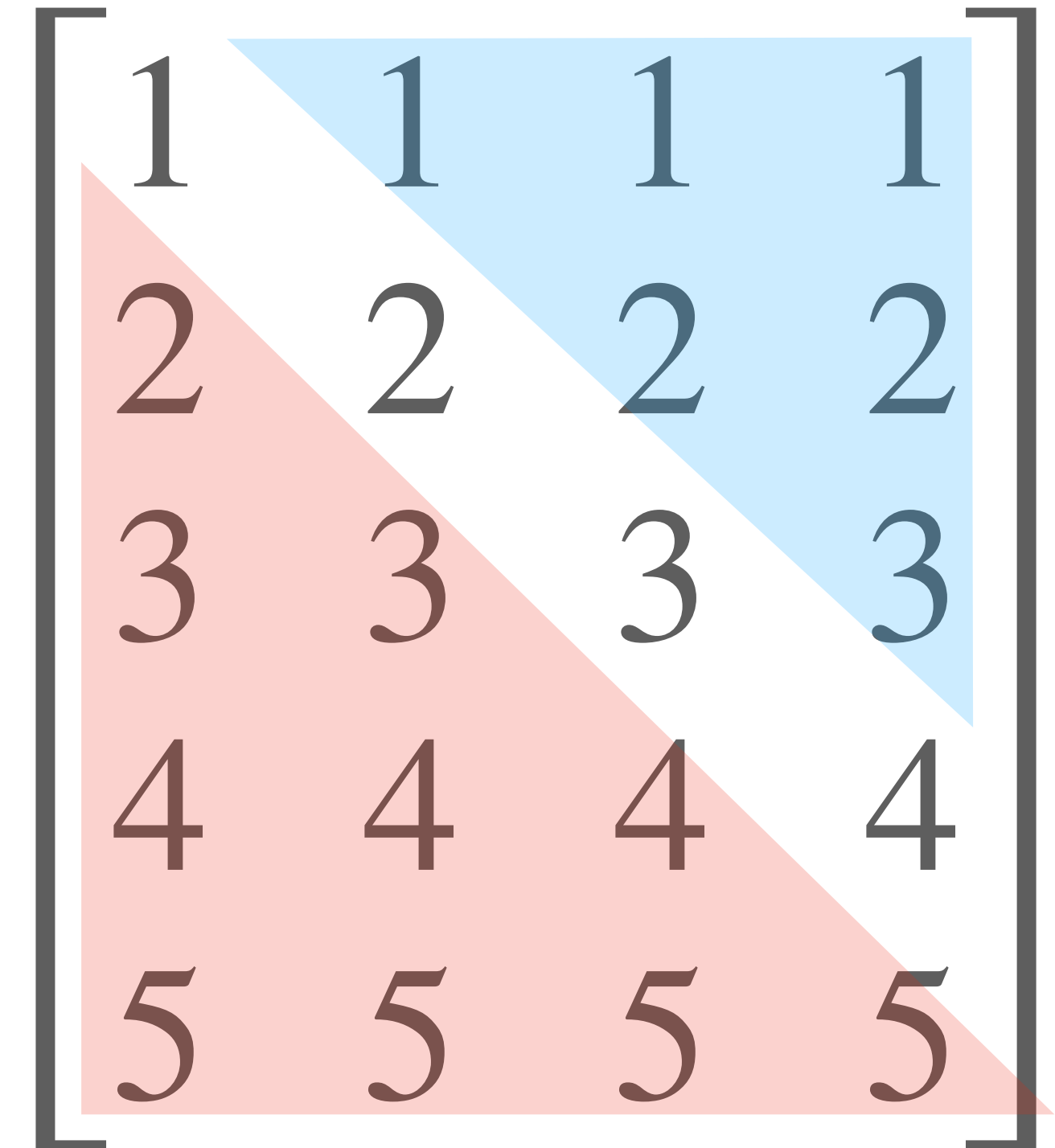
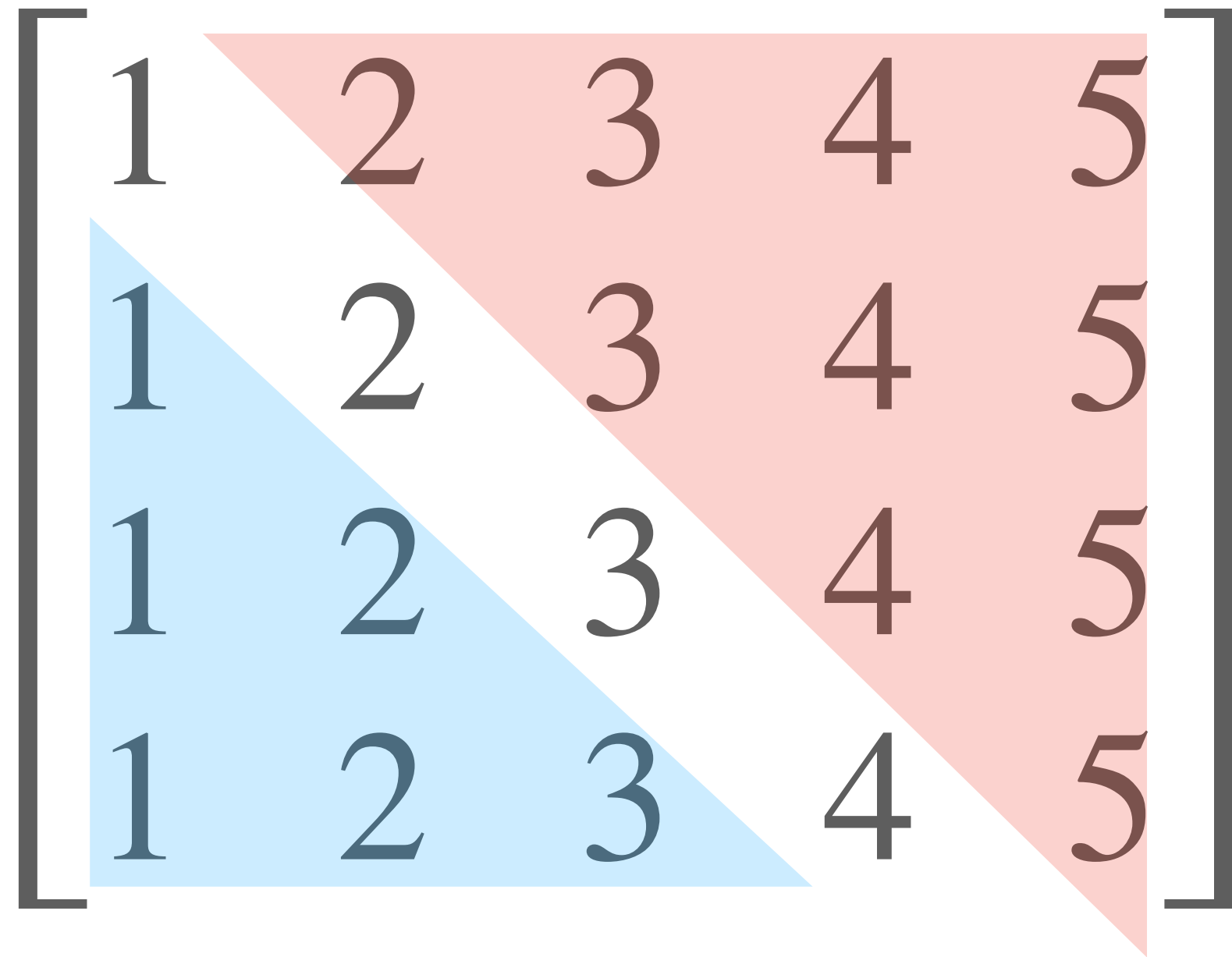
Transpose (Pictorially)

$$\begin{bmatrix} 1 & 2 & 3 & 4 & 5 \\ 1 & 2 & 3 & 4 & 5 \\ 1 & 2 & 3 & 4 & 5 \\ 1 & 2 & 3 & 4 & 5 \end{bmatrix}$$



$$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 2 & 2 & 2 & 2 \\ 3 & 3 & 3 & 3 \\ 4 & 4 & 4 & 4 \\ 5 & 5 & 5 & 5 \end{bmatrix}$$

Transpose (Pictorially)



Transpose

Definition. For a $m \times n$ matrix A , the **transpose** of A , written A^T , is the $n \times m$ matrix such that

$$(A^T)_{ij} = A_{ji}$$

Example.

$$\begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}^T = \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix}$$

Algebraic Properties (Transpose)

$$(A^T)^T = A \quad \left((A^T) \right)_{ij}^T = A^T_{ji} = A_{ij}$$

$$(A + B)^T = A^T + B^T$$

$$(cA)^T = cA^T \quad (\text{where } c \text{ is a scalar})$$

$$(AB)^T = B^T A^T$$

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$$(cA)^T = cA^T \text{ (where } c \text{ is a scalar)}$$

$$(AB)^T = B^T A^T \text{ Important: the order reverses!}$$

Challenge Problem (Not In-Class)

Show that $(AB)^T = B^T A^T$.

Example: $\left(\begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} \right)^T$

$= \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} \cdot \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$

$\neq \begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix}$

$= \begin{pmatrix} 1(1) + 0(1) \\ 1(1) + 1(1) \\ 1 \\ 1 \end{pmatrix}^T$

$= \begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix}$

$\left. \begin{array}{l} 1(1) + 0(0) \\ 1(1) + 1(0) \end{array} \right\}^T$

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$[u_1 \ u_2 \ u_3 \ u_4]$

$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{bmatrix}$

=

?

Transposes and Inner Products

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It's a $1 \times n$ matrix.

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$$[u_1 \quad u_2 \quad u_3 \quad u_4] \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{bmatrix} = ?$$

Transposes and Inner Products

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$$[u_1 \quad u_2 \quad u_3 \quad u_4] \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{bmatrix} = u_1 v_1 + u_2 v_2 + u_3 v_3 + u_4 v_4$$

Transposes and Inner Products

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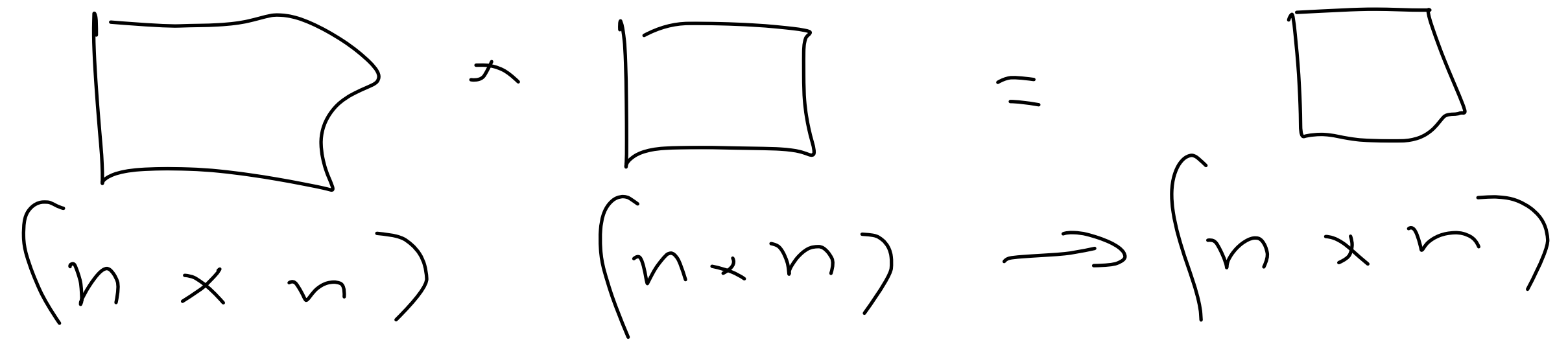
$[1 \quad 2 \quad 3]^T$

Definition. The **inner product** of two vectors \mathbf{u} and \mathbf{v} in \mathbb{R}^n is

$$\langle \mathbf{u}, \mathbf{v} \rangle = \mathbf{u} \cdot \mathbf{v} = \mathbf{u}^T \mathbf{v}$$

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(we want $A^0 A^k = A^{0+k} = A^k$)

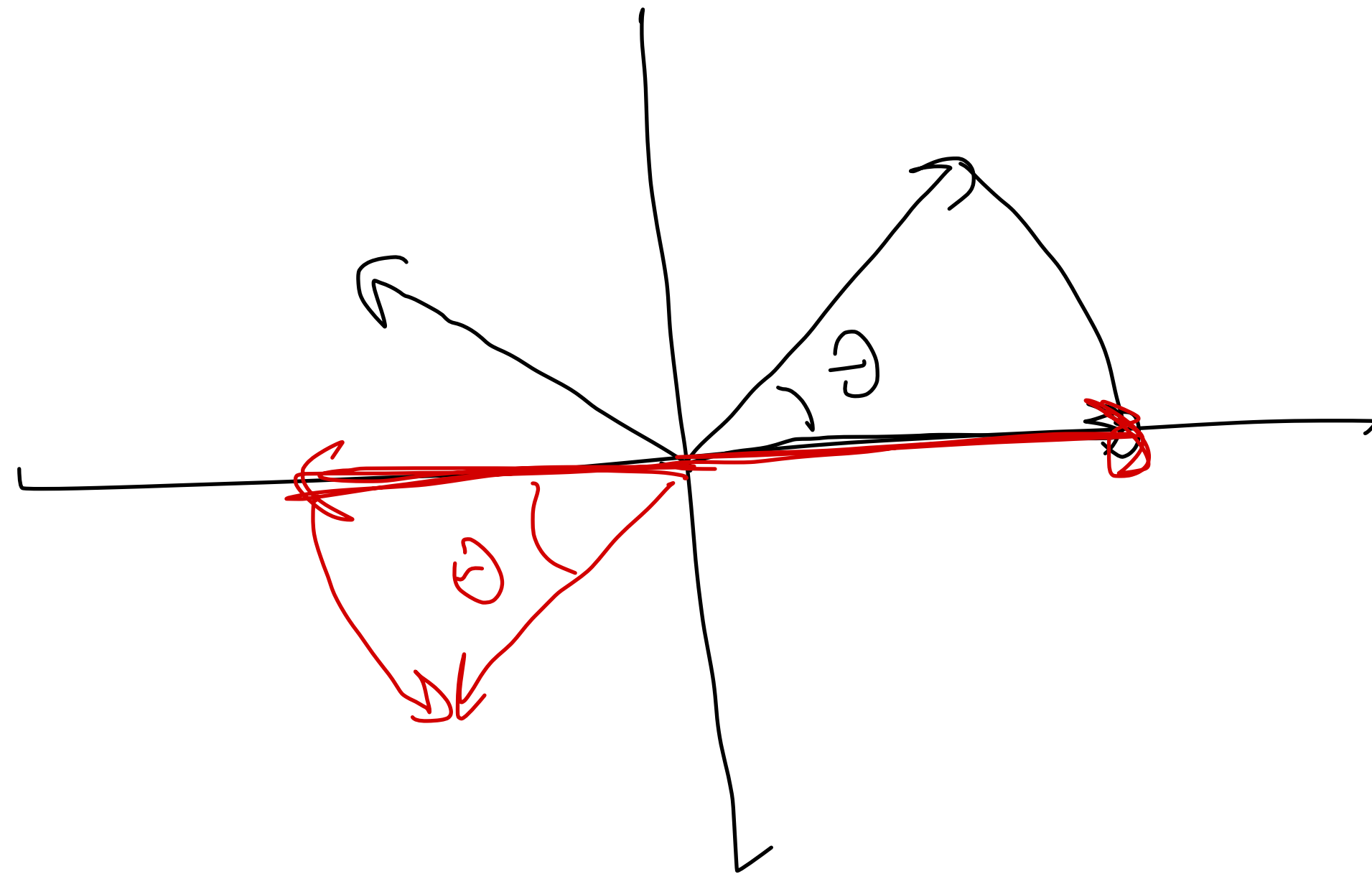
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1. AB is not necessarily equal to BA , even if both are defined.

rotation then reflection

refl. then rot.



Final Warnings about Matrix Multiplication

1. AB is not necessarily equal to BA , even if both are defined.

2. If $AB = AC$ then it is not necessary that $B = C$.

$$A = \mathcal{O}$$

$$\mathcal{O}B = \mathcal{O}C$$

$$B \neq C$$

Final Warnings about Matrix Multiplication

1. AB is not necessarily equal to BA , even if both are defined.
2. If $AB = AC$ then it is not necessary that $B = C$.
3. If $AB = 0$ (the zero matrix) it is not necessarily the case that $A = 0$ or $B = 0$.

Question

Find two nonzero 2×2 matrices A and B such that $AB = 0$.

Challenge. *Choose A and B such that they have all nonzero entries.*

Answer

$$\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$A \begin{bmatrix} \vec{b}_1 \\ \vec{b}_2 \end{bmatrix} = \vec{0}$$

$$\begin{aligned} A \vec{b}_1 &= \vec{0} \\ A \vec{b}_2 &= \vec{0} \end{aligned}$$

$$\begin{bmatrix} A \vec{b}_1 & A \vec{b}_2 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

$$B = \begin{bmatrix} 1 & 1 \\ -1 & -1 \end{bmatrix}$$

So Far: Matrix Operations

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transpose

A^T

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transpose

$$A^T$$

scaling

$$cA$$

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addition (subtraction)

$$A + B$$

$$A + (-1)B = A - B$$

So Far: Matrix Operations

transpose	A^T	
scaling	cA	
addition (subtraction)	$A + B$	$A + (-1)B = A - B$
multiplication (powers)	AB	A^k

So Far: Matrix Operations

transpose

A^T

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A^k

What's missing?

Matrix Inverses

Basic Algebra

$$2x = 10$$

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Multiply each side by $\frac{1}{2}$ a.k.a. 2^{-1} .

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Basic Algebra

$$2^{-1}(2x) = 2^{-1}(10)$$

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Basic Algebra

$$1x = 5$$

How do we solve this equation?

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Multiply each side by $\frac{1}{2}$ a.k.a. 2^{-1} .

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Basic Algebra

$$x = 5$$

How do we solve this equation?

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Multiply each side by $\frac{1}{2}$ a.k.a. 2^{-1} .

$\frac{1}{2}$ is the **reciprocal** or **multiplicative inverse** of 2.

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$$**Ax = b**$$

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$$\mathbf{Ax} = \mathbf{A}^{-1}\mathbf{b}$$

How do we solve this equation?

Multiply each side by \mathbf{A}^{-1} to get $\mathbf{x} = \mathbf{A}^{-1}\mathbf{b}$.

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Do all matrices have
inverses?

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inverses?

No.

When does a matrix have
an inverse?

Square Matrices

Definition. A $m \times n$ matrix A is **square** if $m = n$

$$\begin{bmatrix} * & * & * & * \\ * & * & * & * \\ * & * & * & * \\ * & * & * & * \end{bmatrix}$$

i.e., it has same number of rows as columns.

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» that can have inverses.

Dimension Tracking

$$\begin{array}{ccc} & \in \mathbb{R}^n & \\ & \swarrow & \\ \mathbf{A} & \mathbf{x} = & \mathbf{b} \\ & \nwarrow & \in \mathbb{R}^m \\ (m \times n) & (n \times 1) & (m \times 1) \end{array}$$

Dimension Tracking

$$\begin{array}{c} \mathbf{A}^{-1} \mathbf{A} \mathbf{x} = \mathbf{A}^{-1} \mathbf{b} \\ \begin{array}{c} (k \times m) \quad (m \times n) \quad (n \times 1) \end{array} \end{array} \quad \begin{array}{c} \overbrace{\hspace{10em}}^{k \times 1} \\ \underbrace{\hspace{10em}}_{(m \times 1)} \end{array} \quad k = m$$

The diagram illustrates the dimension tracking for the equation $\mathbf{A}^{-1} \mathbf{A} \mathbf{x} = \mathbf{A}^{-1} \mathbf{b}$. The dimensions of the matrices and vectors are indicated by handwritten annotations:

- \mathbf{A}^{-1} is $k \times m$.
- \mathbf{A} is $m \times n$.
- \mathbf{x} is $n \times 1$.
- $\mathbf{A}^{-1} \mathbf{b}$ is $m \times 1$.

Handwritten annotations also show that the product $\mathbf{A}^{-1} \mathbf{A} \mathbf{x}$ results in a $k \times 1$ vector, and that $k = m$.

Dimension Tracking

$$\mathbf{x} = \mathbf{A}^{-1} \mathbf{b}$$

Handwritten annotations:

- \mathbb{R}^n (above \mathbf{x})
- $n \times 1$ (below \mathbf{x})
- $k \times 1 = m \times 1$ (above \mathbf{A}^{-1})
- $n \times 1$ (below \mathbf{A}^{-1})
- $k = m = n$ (below \mathbf{A}^{-1})

Dimension Tracking

$$\mathbf{x} = A^{-1}\mathbf{b}$$

The only way for the dimensions to make sense is if A is square

Matrix Inverses

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Definition. For a $n \times n$ matrix A , an **inverse** of A is a $n \times n$ matrix B such that

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Example. $\begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}^{-1} = \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix}$

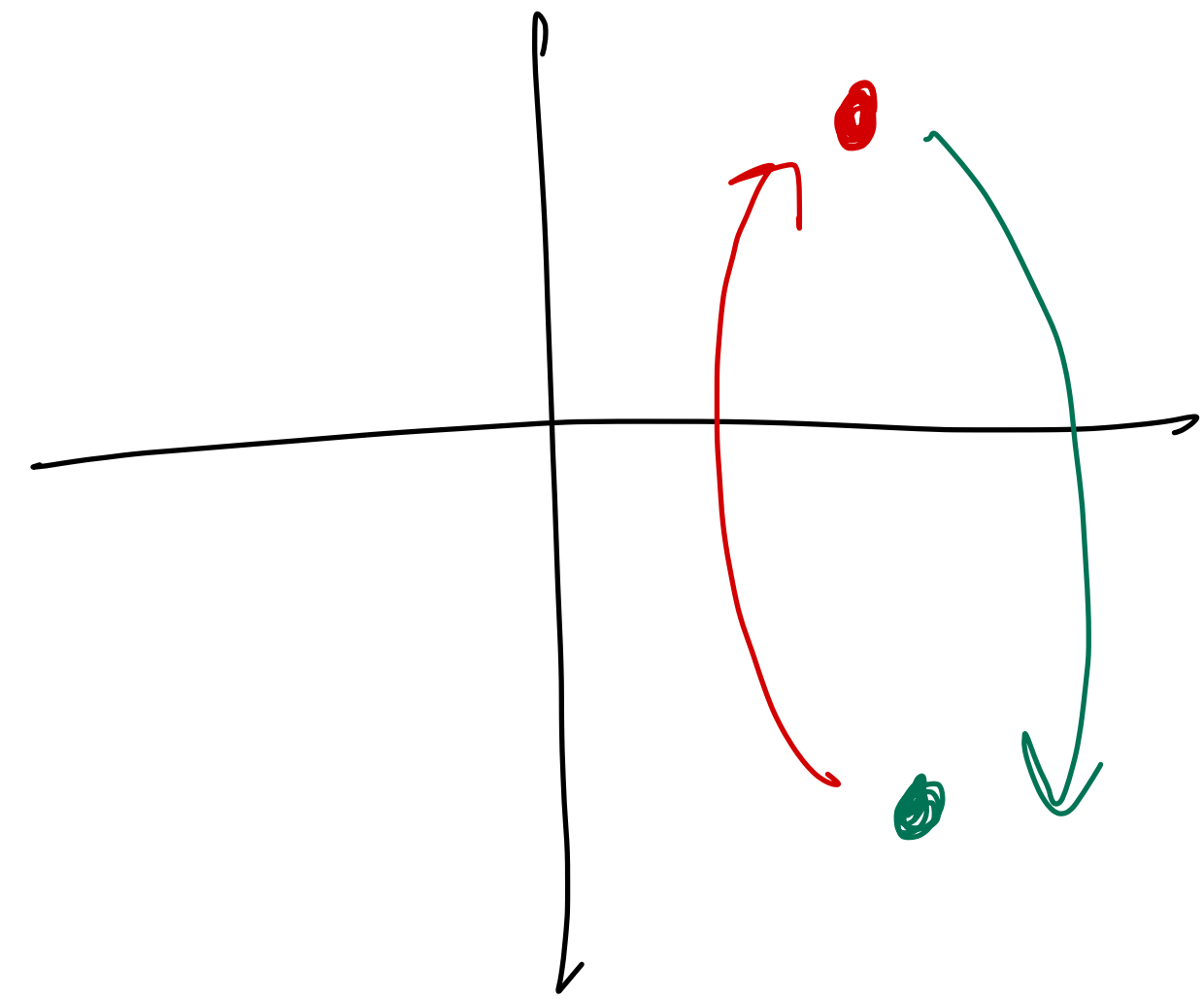
$$\begin{bmatrix} 1 & 0 \\ \vdots & \vdots \end{bmatrix} \begin{bmatrix} 1 & 0 \\ \vdots & \vdots \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Example: Geometric

Reflection across the x_1 -axis in \mathbb{R}^2 is its own inverse.

Verify:

$$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$



Example: No inverse

$$A = \begin{bmatrix} 1 & 2 & -1 \\ 0 & 3 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

Verify:

$$A \begin{bmatrix} \vec{b}_1 & \vec{b}_2 & \vec{b}_3 \end{bmatrix} = \begin{bmatrix} A\vec{b}_1 & A\vec{b}_2 & A\vec{b}_3 \end{bmatrix}$$
$$\begin{bmatrix} 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} \text{CS} \end{bmatrix} = \begin{bmatrix} \boxed{0} \end{bmatrix}$$

Inverses are Unique

Theorem. If B and C are inverses of A , then $B = C$.

Verify: $B = B I = B (A C) = (B A) C = I C = C$

Inverses are Unique

Theorem. If B and C are inverses of A , then $B = C$.

Verify:

If A is invertible, then we write A^{-1}
for *the* inverse of A .

Solutions for Invertible Matrix Equations

Theorem. For a $n \times n$ matrix A , if A is invertible then

$$Ax = b$$

has a unique solution for any choice of b .

Verify: $x = A^{-1}b$ is a solution

Suppose
 $A^{-1}b$

$$Ax = Ix = A^{-1}A x = A^{-1}b$$

Unique Solutions

If $A\mathbf{x} = \mathbf{b}$ has a unique solution for any choice of \mathbf{b} , then it has

» exactly one solution for any choice of \mathbf{b}

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If $A\mathbf{x} = \mathbf{b}$ has a unique solution for any choice of \mathbf{b} , then it has

- » at least one solution for any choice of \mathbf{b}
- » at most one solution for any choice of \mathbf{b}

Unique Solutions

If $A\mathbf{x} = \mathbf{b}$ has a unique solution for any choice of \mathbf{b} , then it has

» T is onto

» T is one-to-one

where T is implemented by A

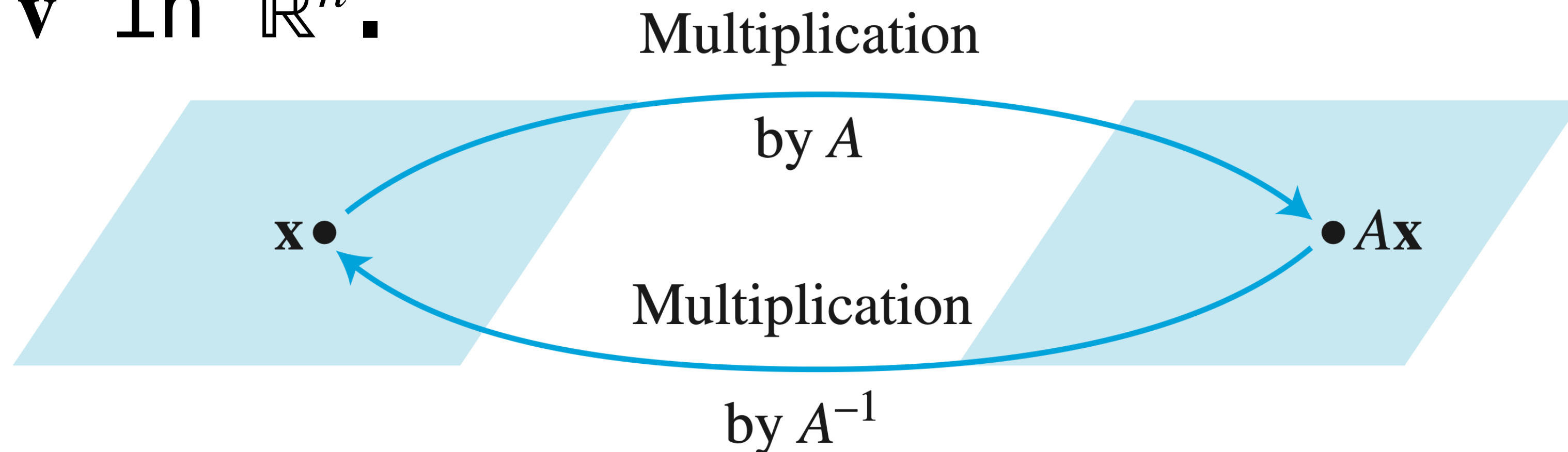
Connection to Transformations

Definition. A linear transformation $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is **invertible** if there is a linear transformation S such that

$$A^{-1}A\vec{x} = \vec{x} \quad A A^{-1}\vec{x} = \vec{x}$$

$$S(T(\mathbf{v})) = \mathbf{v} \quad \text{and} \quad T(S(\mathbf{v})) = \mathbf{v}$$

for any \mathbf{v} in \mathbb{R}^n .



Connection to Transformations

Connection to Transformations

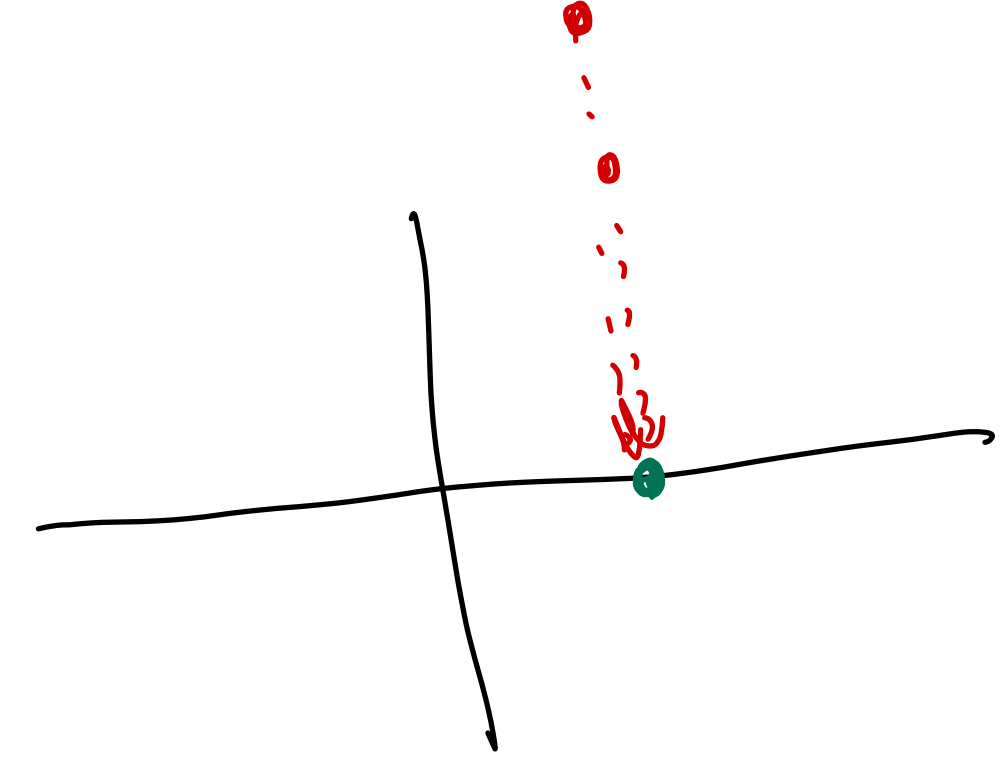
Theorem. A $n \times n$ matrix A is invertible if and only if the matrix transformation $\mathbf{x} \mapsto A\mathbf{x}$ is invertible.

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Non-Example. Projection onto the x_1 -axis.

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Definition. A transformation $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is a **one-to-one correspondence** (bijection) if any vector \mathbf{b} in \mathbb{R}^n is the **image of exactly one vector** \mathbf{v} in \mathbb{R}^n (where $T(\mathbf{v}) = \mathbf{b}$).

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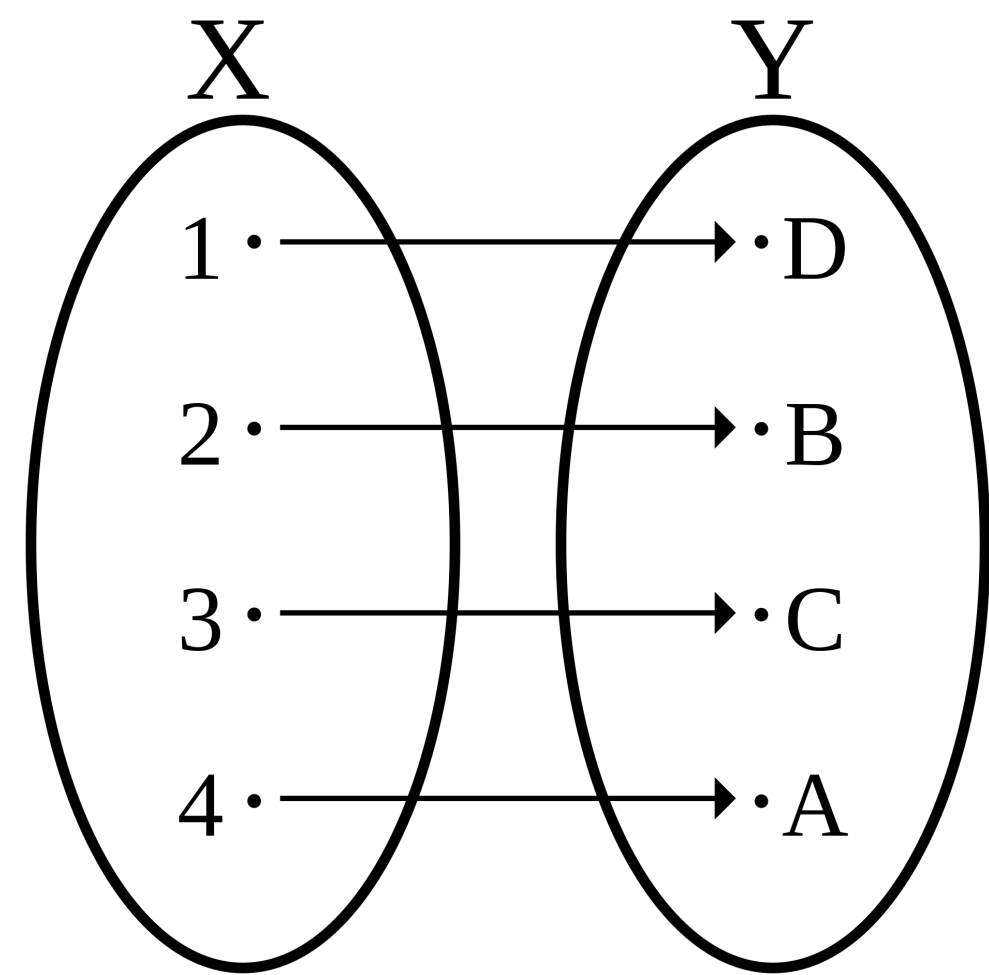
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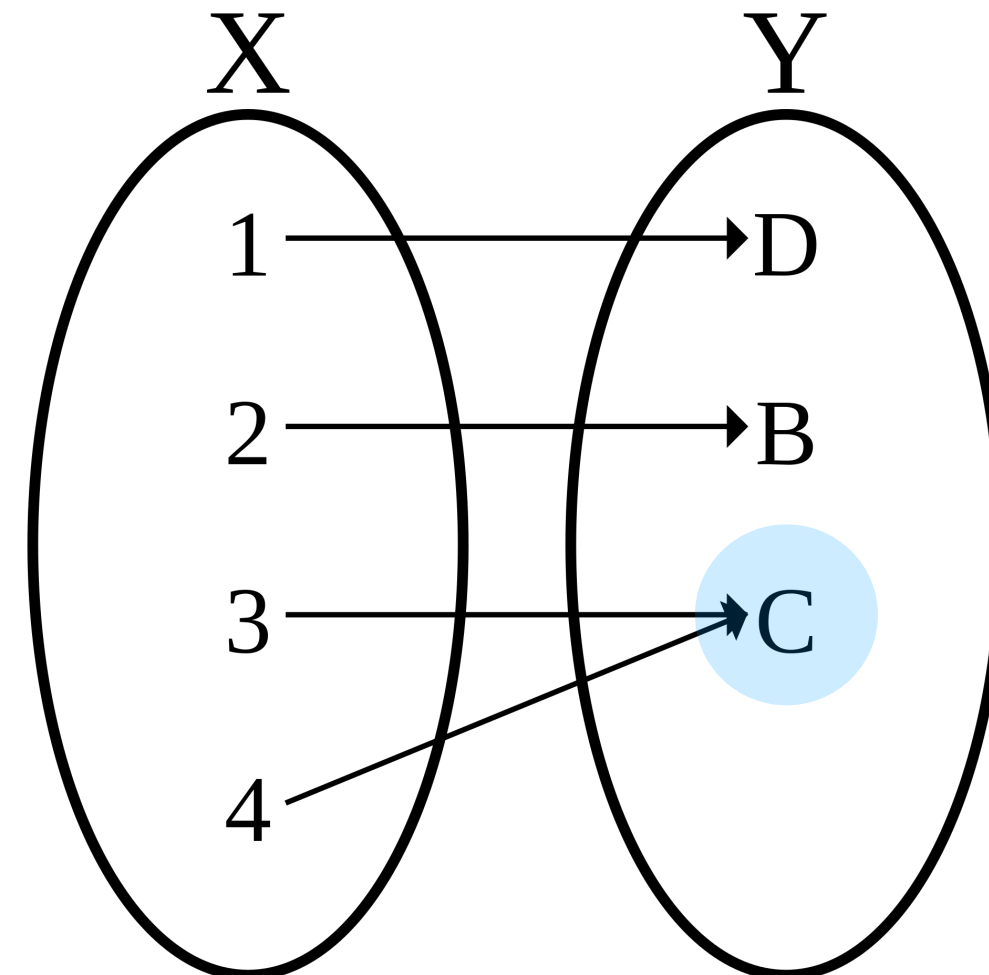
Invertible transformations are 1-1 correspondences.

Kinds of Transformations (Pictorially)



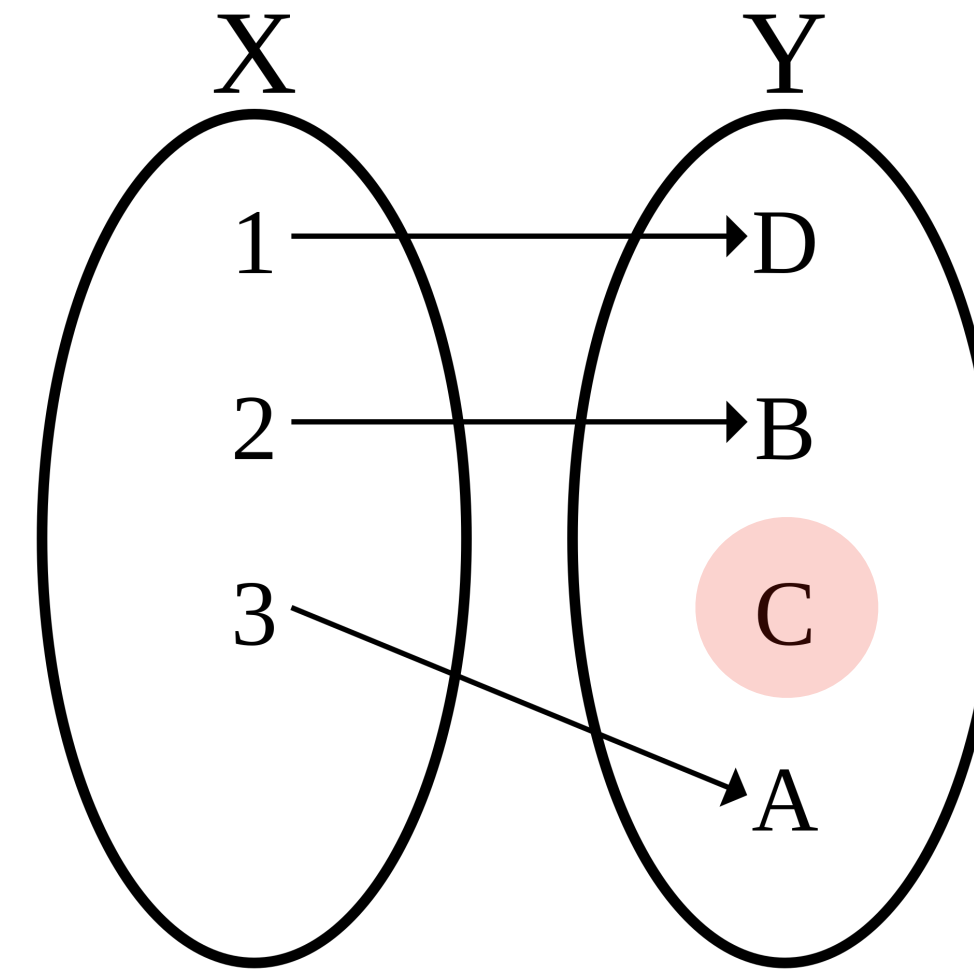
1-1 correspondence

collision



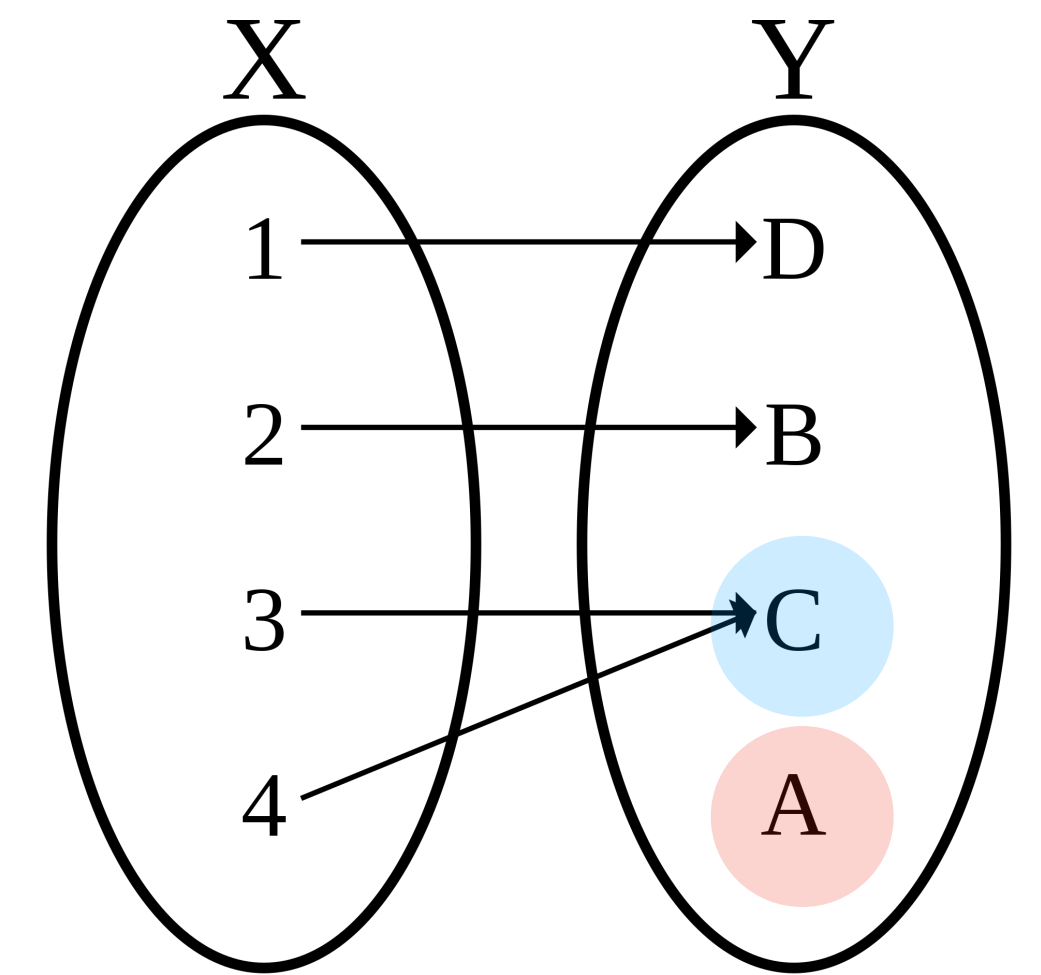
onto, not 1-1

not covered



1-1 not onto

not covered
collision



not 1-1, not onto

Computing Matrix Inverses

In General

$$A \begin{bmatrix} \mathbf{b}_1 & \mathbf{b}_2 & \mathbf{b}_3 \end{bmatrix} = I$$

Can we solve for each \mathbf{b}_i ?:

$$\begin{bmatrix} A\vec{b}_1 & A\vec{b}_2 & A\vec{b}_3 \end{bmatrix} = \begin{bmatrix} \vec{e}_1 & \vec{e}_2 & \vec{e}_3 \end{bmatrix}$$

$$A\vec{b}_1 = \vec{e}_1$$

How To: Matrix Inverses

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Question. Find the inverse of an invertible $n \times n$ matrix A .

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Solution. Solve the equation $A\mathbf{x} = \mathbf{e}_i$ for every standard basis vector. Put those solutions $\mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_n$ into a single matrix

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$$[\mathbf{s}_1 \quad \mathbf{s}_2 \quad \dots \quad \mathbf{s}_n]$$

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Solution. Row reduce the matrix $[A \ I]$ to a matrix $[I \ B]$. Then B is the inverse of A .

$$\begin{bmatrix} A \end{bmatrix}_{n \times n} = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix} \quad \begin{bmatrix} A & \begin{matrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{matrix} \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \mid A^{-1} \end{bmatrix}$$

How To: Matrix Inverses

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This is really the same thing. It's a simultaneous reduction.

How To: Matrix Inverse Computationally

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Warning: this only works if the matrix is invertible.

demo

Special Case: 2×2 Matrix Inverses

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(see the notes on linear transformations for more information about determinants)

Example

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No. The determinant is $(-6)(-7) - 14(3) = 42 - 42 = 0$

Algebra of Matrix Inverses

Algebraic Properties (Matrix Inverses)

Theorem. For a $n \times n$ invertible matrix A

$$(A^{-1})^{-1} = A$$

Verify:

Algebraic Properties (Matrix Inverses)

Theorem. For a $n \times n$ invertible matrix A , the matrix A^T is invertible and

$$(A^T)^{-1} = (A^{-1})^T$$

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Algebraic Properties (Matrix Inverses)

Theorem. For a $n \times n$ invertible matrices A and B , the matrix AB is invertible and

$$(AB)^{-1} = B^{-1}A^{-1}$$

Verify:

Question

Suppose that A is a $n \times n$ invertible matrix such that $A = A^T$ and B is a $m \times n$ matrix.

Simplify the expression $A(BA^{-1})^T$ using the algebraic properties we've seen.

Answer: B^T

$$A(BA^{-1})^T$$

$$A = A^T$$

Invertible Matrix Theorem

High Level

How do we know if a matrix is invertible?

By connecting everything we've said so far.

Invertible Matrix Theorem (IMT)

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We get a lot of information for free

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Theorem. If A is square, then

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Warning. Remember this only applies square matrices.

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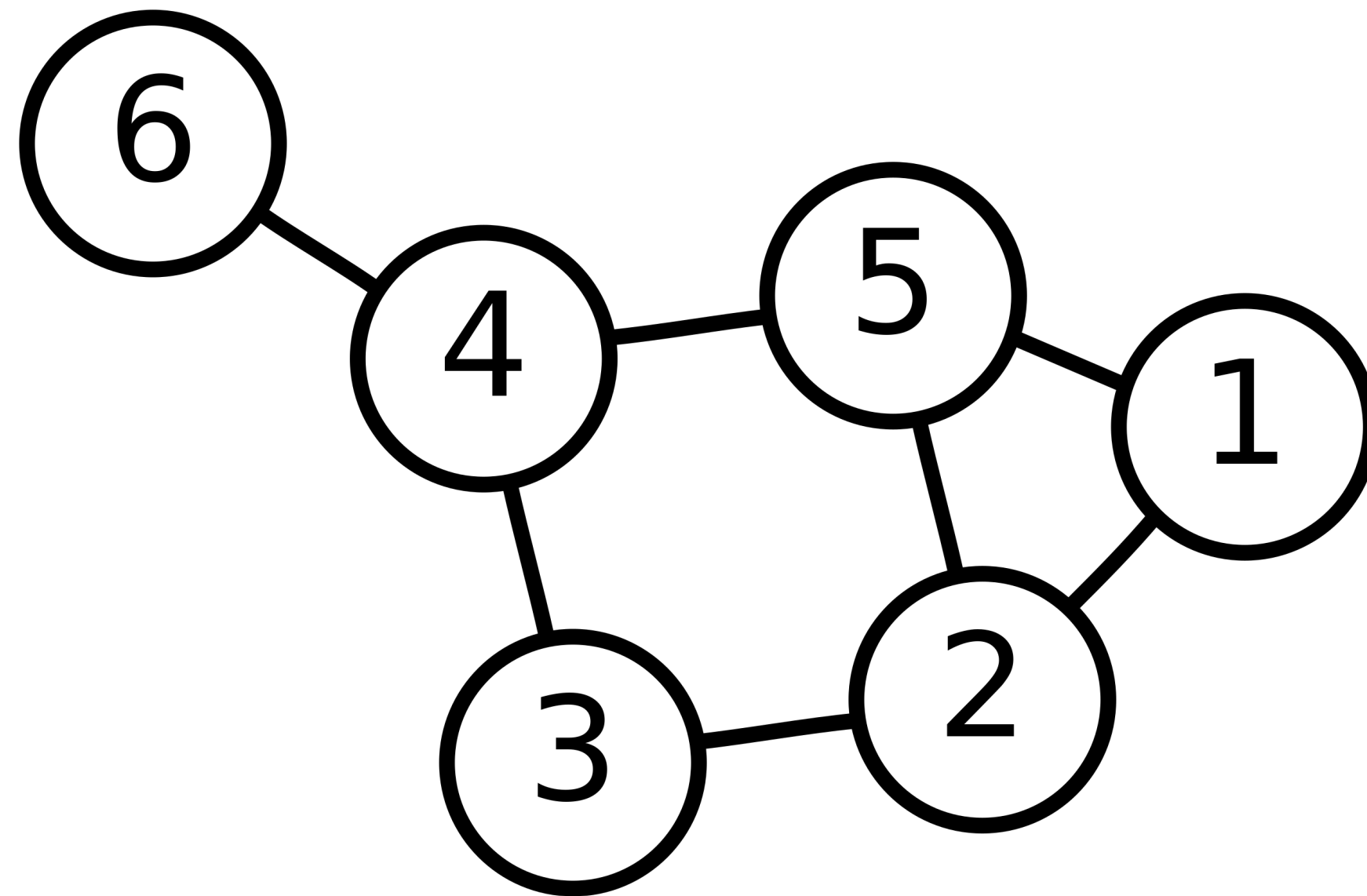
$$A \text{ is invertible} \quad \equiv \quad Ax = 0 \text{ implies } x = 0$$

Invertibility is completely determined by how A behaves on $\mathbf{0}$.

Application: Adjacency Matrices

Graphs

Definition (Informal). An **undirected graph** is a collection of nodes with edges between them.



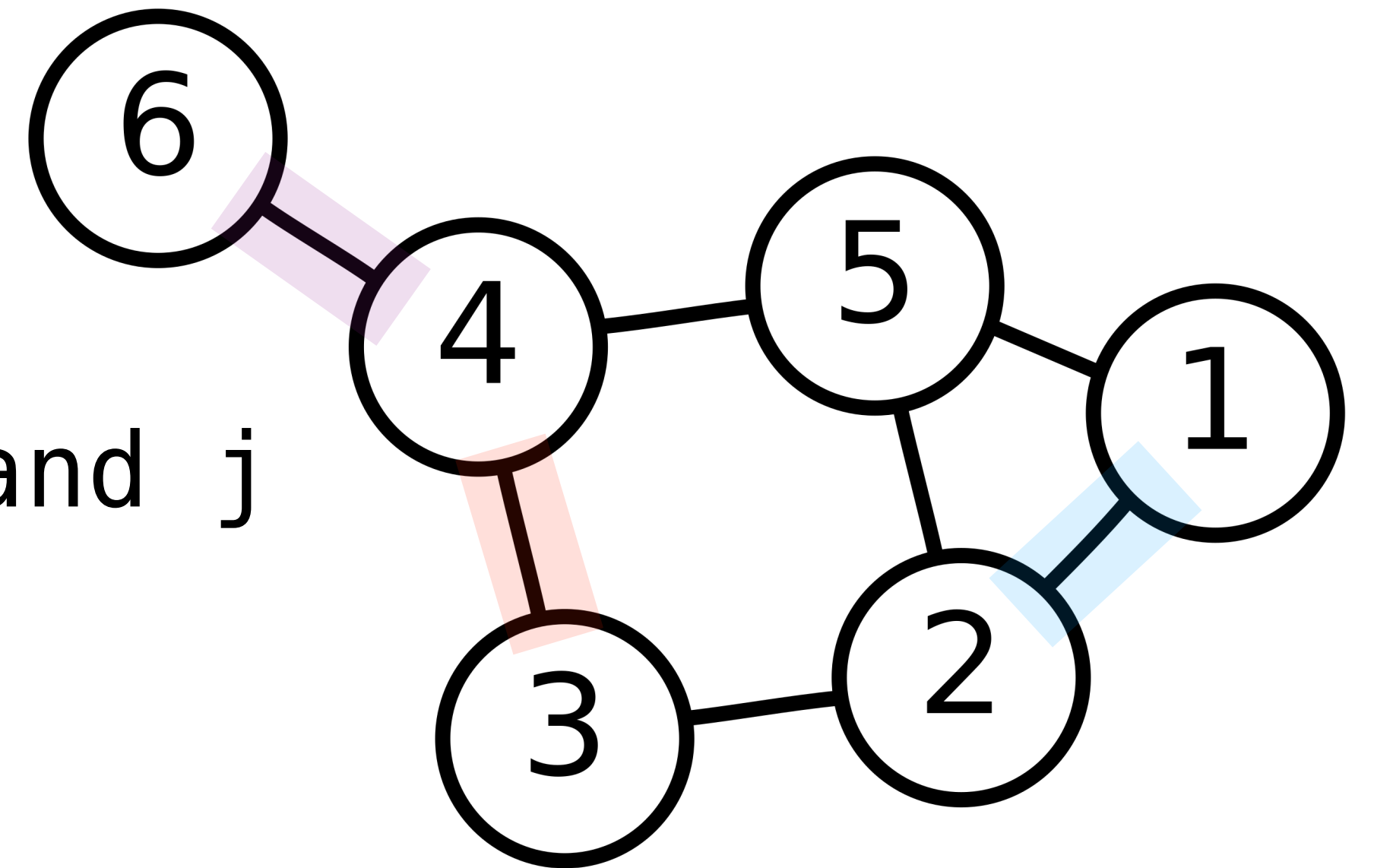
How do we represent these in computers?

Adjacency Matrices

For an undirected graph G we can create the **adjacency matrix** A for G where:

	A_{12}	A_{34}	A_{46}
A_{21}	1	0	0
A_{43}	0	1	0
A_{64}	0	0	1

$$A_{ij} = \begin{cases} 1 & \text{there is an edge between } i \text{ and } j \\ 0 & \text{otherwise} \end{cases}$$



Spectral Graph Theory

Once we have an adjacency matrix, we can do linear algebra on graphs.

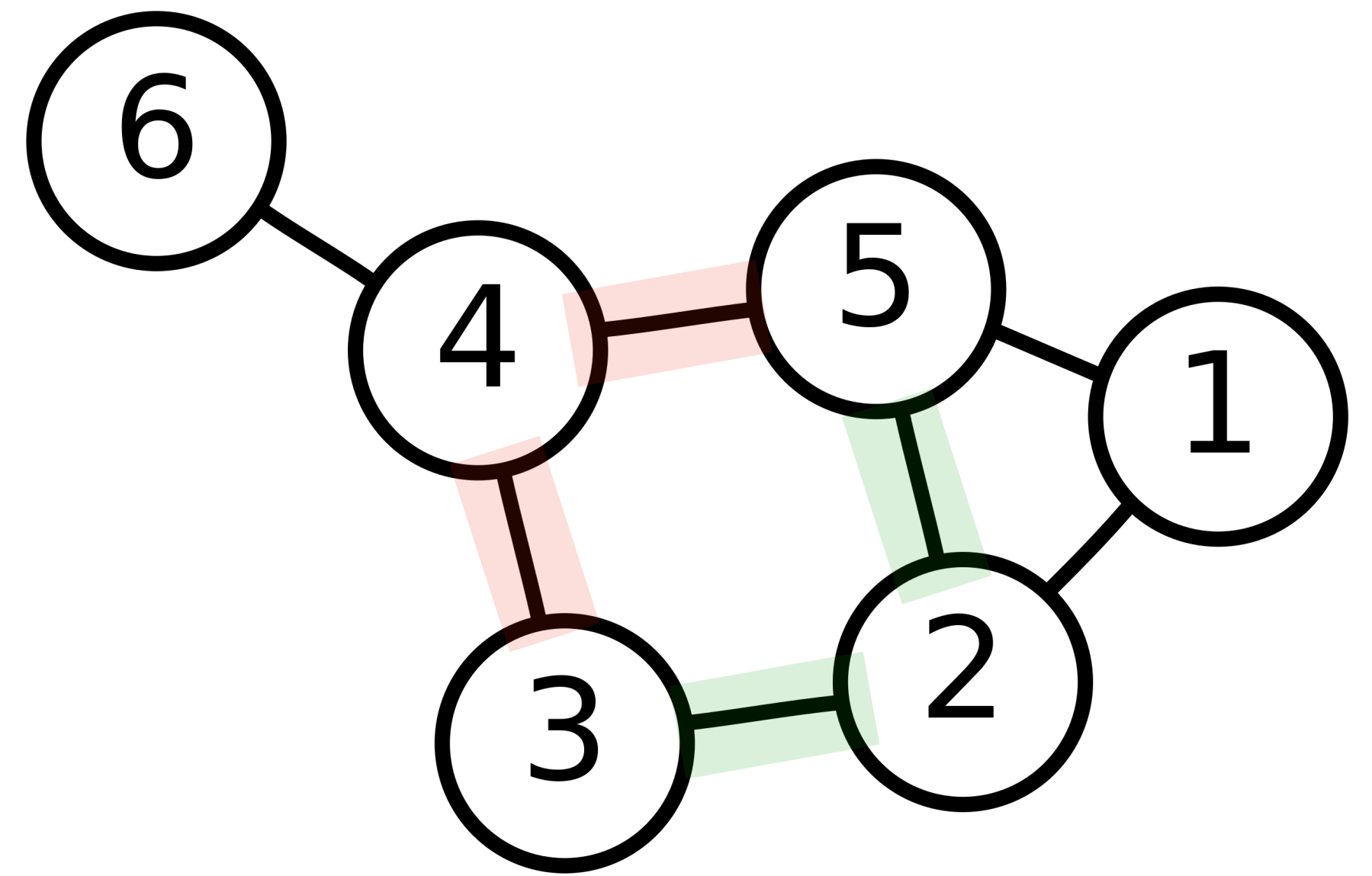
Example: Squared Adjacency Matrices

Given an adjacency matrix A

*Can we interpret anything
meaningful from A^2 ?*

Example: Squared Adjacency Matrices

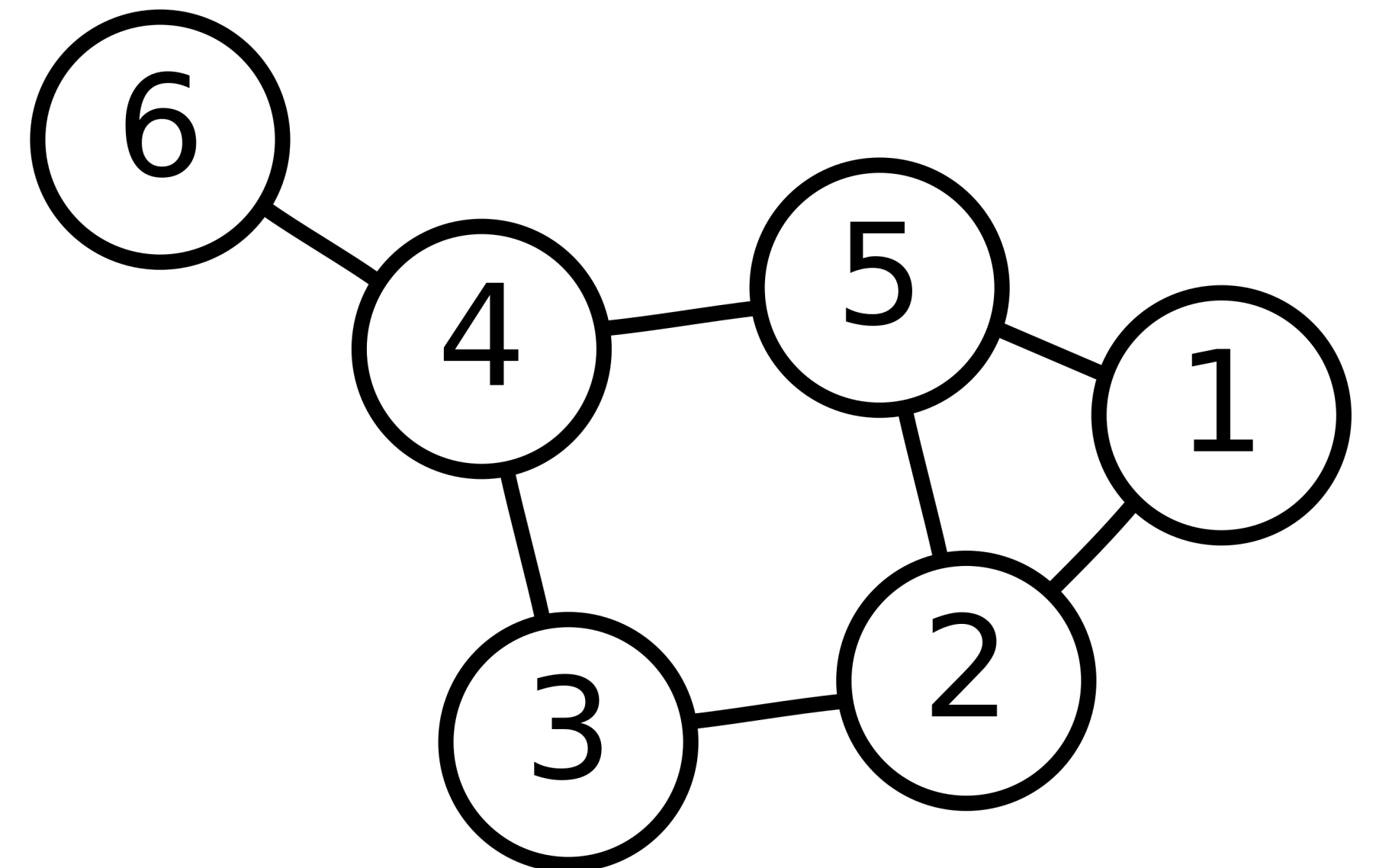
$$\begin{bmatrix} 0 & 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \end{bmatrix}$$



$$(A^2)_{53} = 1(0) + 1(1) + 0(0) + 1(1) + 0(0) + 0(0) = 2$$

Example: Squared Adjacency Matrices

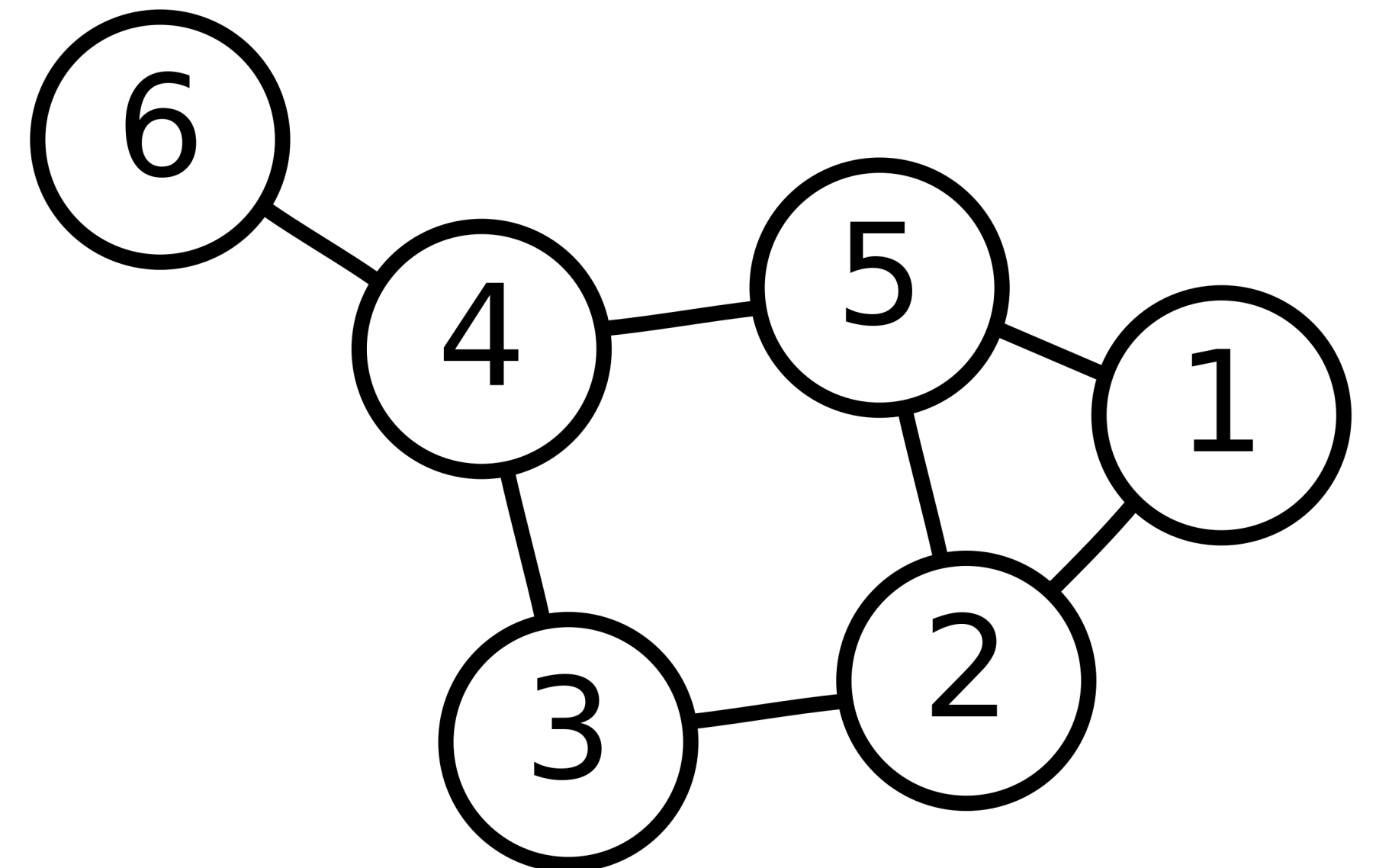
$$(A^2)_{ij} = A_{i1}A_{1j} + A_{i2}A_{2j} + \dots + A_{in}A_{nj}$$



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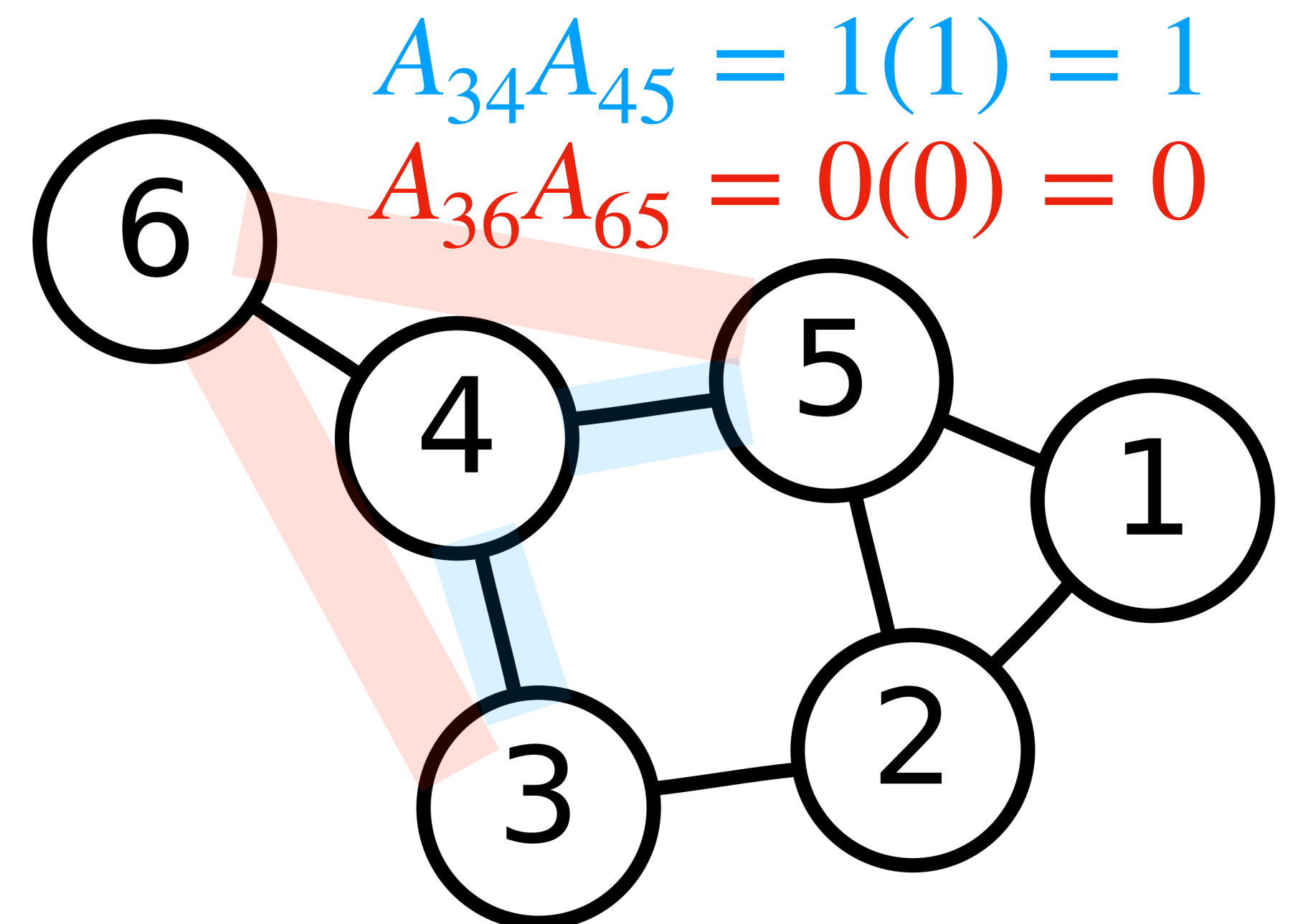
$$A_{ik}A_{kj} = \begin{cases} 1 & \text{there are edges from } i \text{ to } k \text{ and } k \text{ to } j \\ 0 & \text{otherwise} \end{cases}$$



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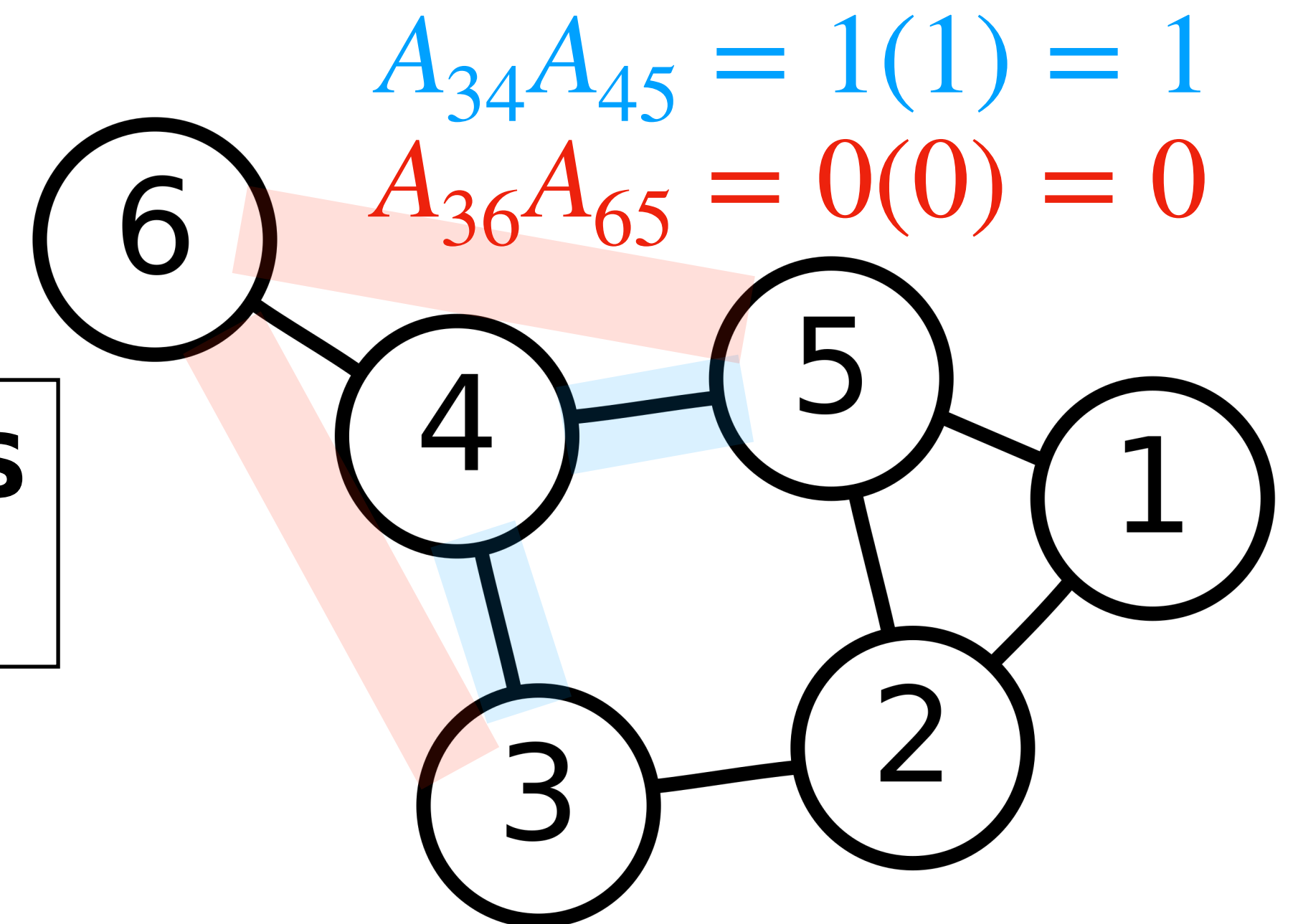


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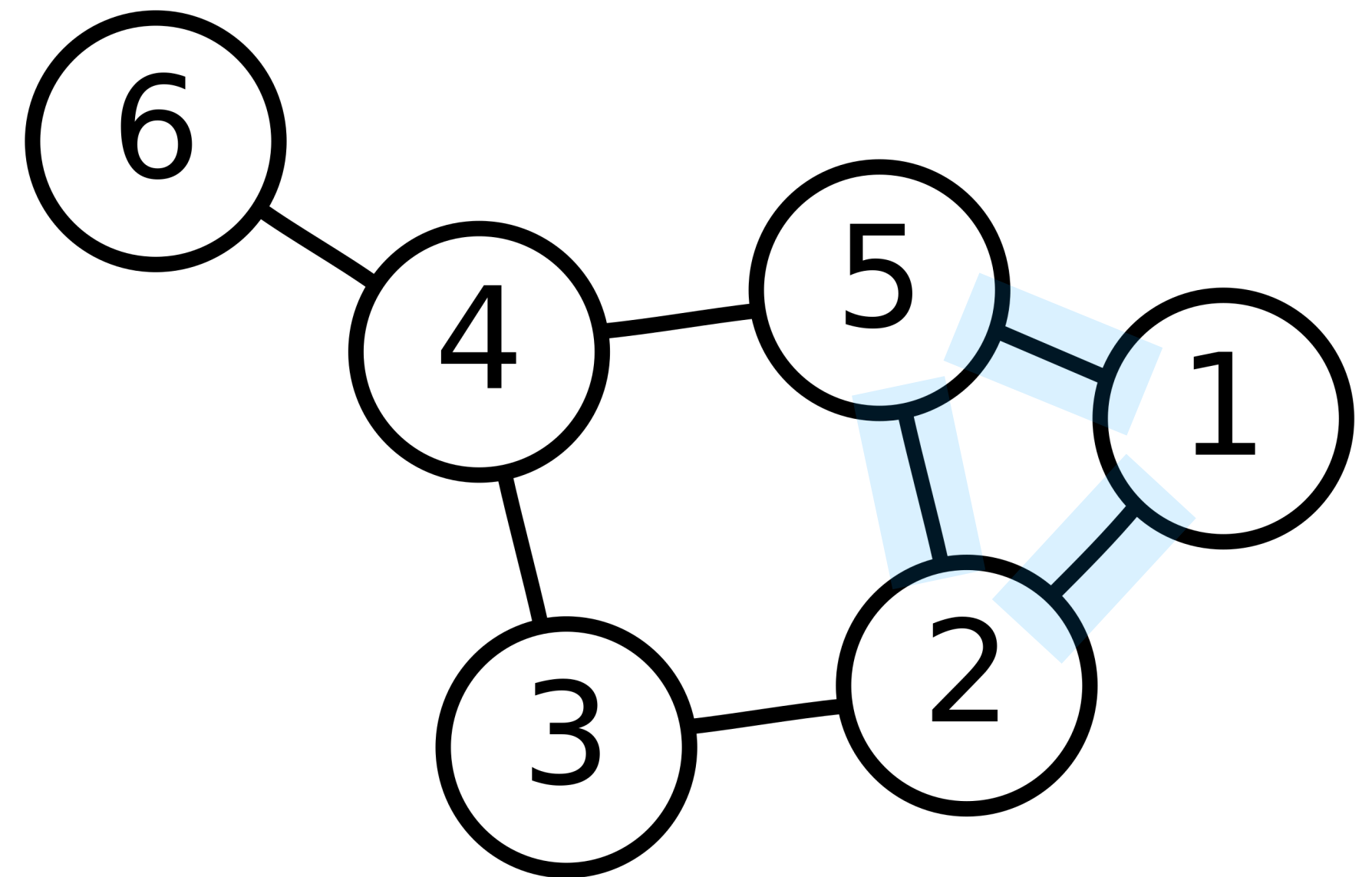
$$(A^2)_{ij} = \text{number of 2-step paths from } i \text{ to } j$$



Application: Triangle Counting

A **triangle** in an undirected graph is a set of three distinct nodes with edges between every pair of nodes.

Triangles in a social network represent mutual friends and tight cohesion (among other things)



Application: Triangle Counting

Theorem. For an adjacency matrix A , the number of triangle containing the edge (i,j) is

$$(A^2)_{ij}A_{ij}$$

Application: Triangle Counting

FUNCTION tri_count(A):

 compute A^2

 count \leftarrow sum of $(A^2)_{ij}A_{ij}$ for all distinct i and j

RETURN count / 6 # why divided by 6?

Summary

We can solve matrix equations by inverting the matrix, though not all matrices have inverses.

We can compute matrix inverses a simultaneous row reduction.

We can connect all the concepts we've defined so far by thinking about them in terms of invertibility (for square matrices).