Linear Equations Geometric Algorithms Lecture 1

CAS CS 132

Objectives

- 1. Motivation
- 2. Definitions
- 3. Solve systems of linear equations

Keywords

Systems of linear equations Solutions Coefficient matrix Augmented matrix Elimination and Back-substitution Replacement, interchange, scaling Row Equivalence (In)consistency

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Motivation

Lines and line intersections An example from chemistry

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Lines and line intersections An example from chemistry

Lines (Slope-Intercept Form)

y = mx + b

Lines (Slope-Intercept Form)

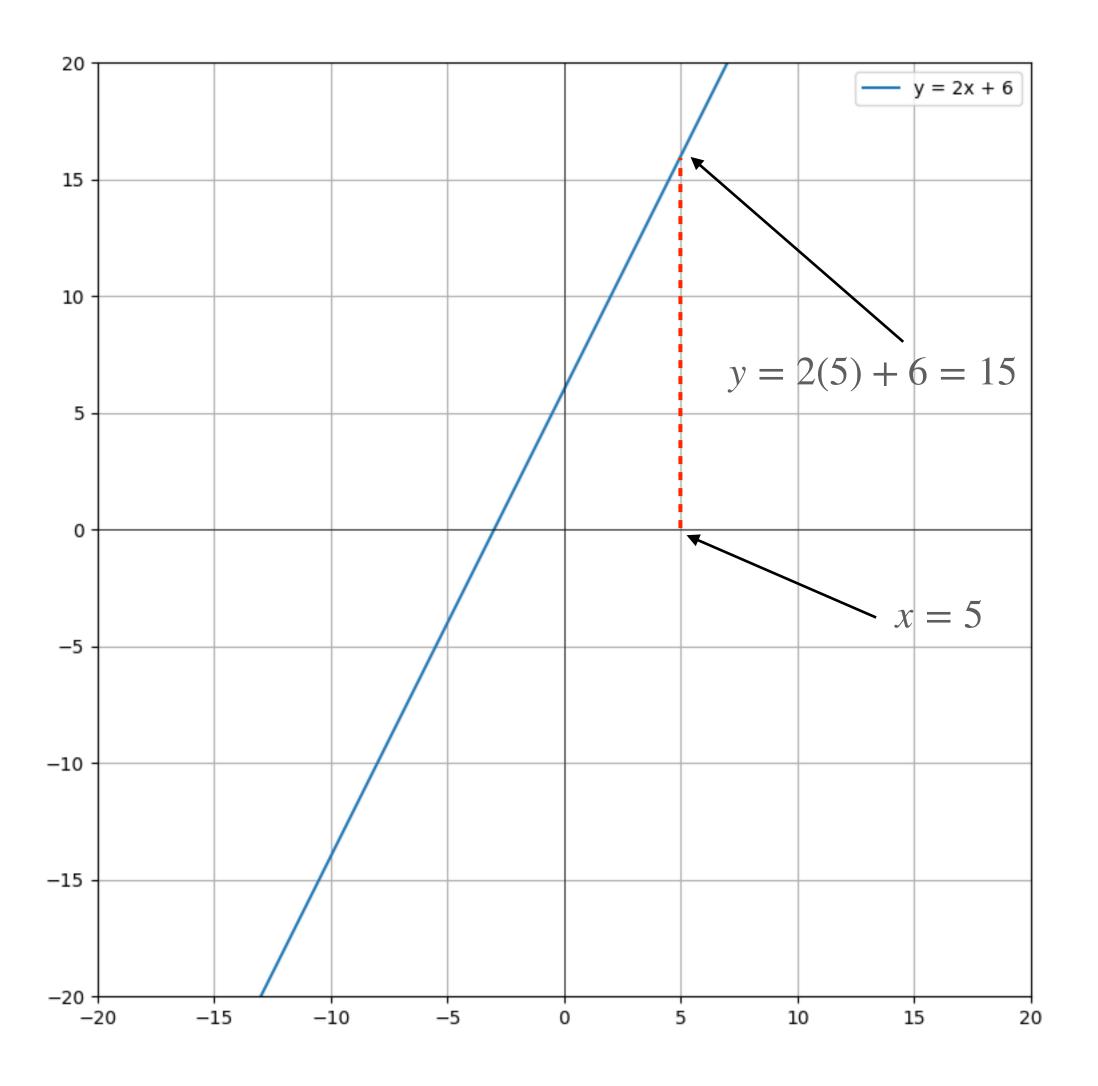
y = mx + bslope y-intercept

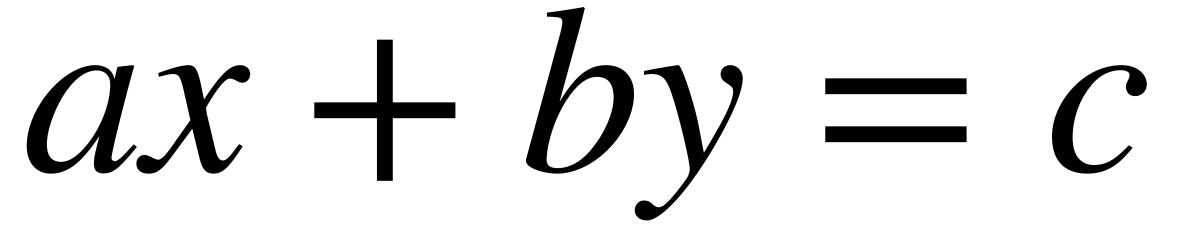
Lines (Slope-Intercept Form)

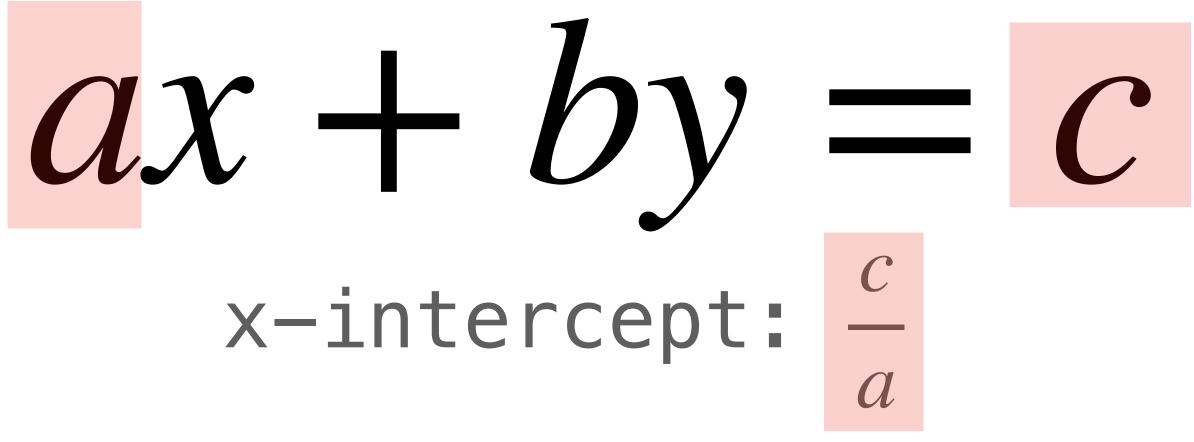
y = mx + bslope y-intercept

Given a value of x, I can compute a value of y

Lines (Graph)







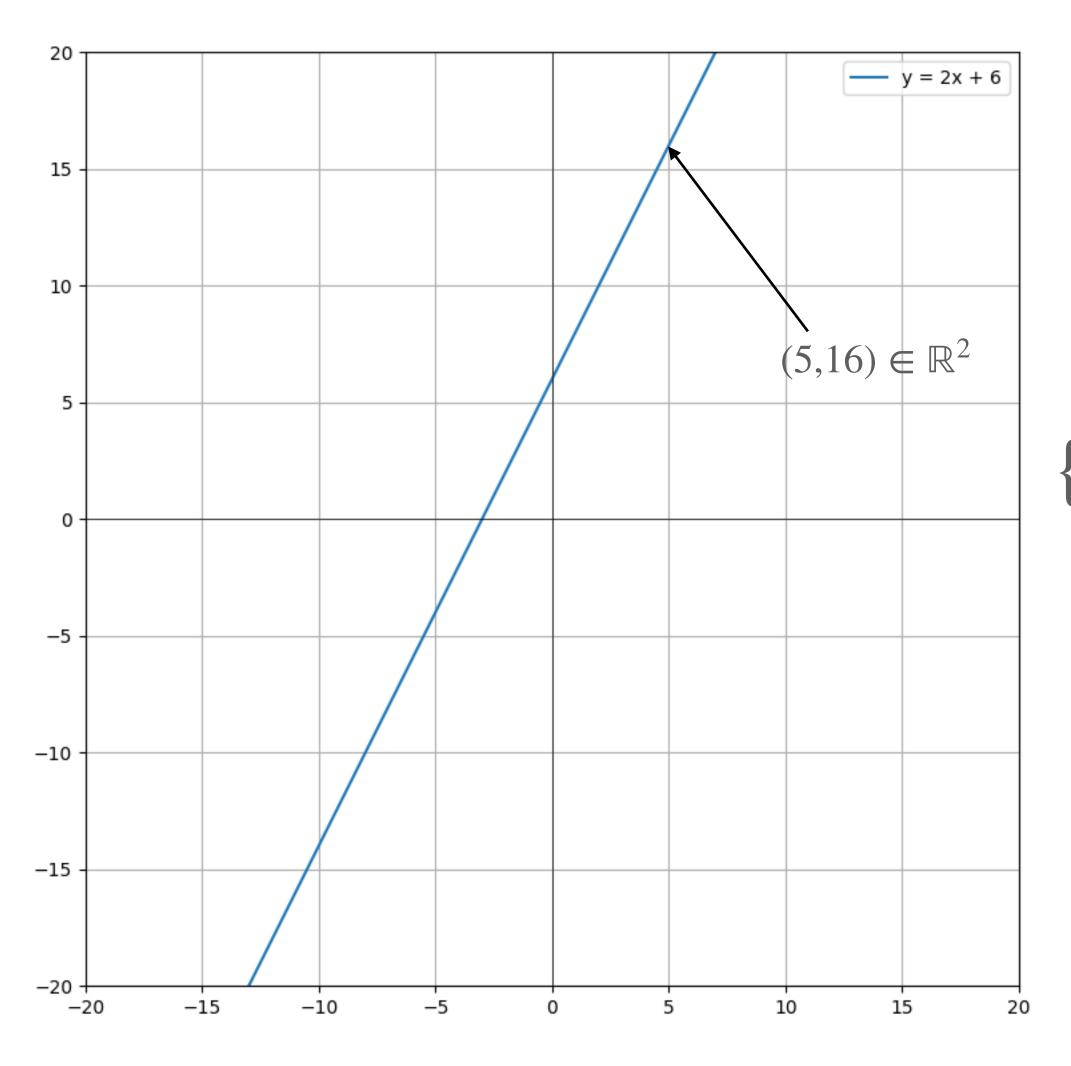
ax + by = cx-intercept: C $\boldsymbol{\mathcal{A}}$ y-intercept: $\frac{c}{b}$

ax + by = c

x-intercept: C y-intercept: $\frac{c}{b}$

What values of x and y make the equality hold?

Lines (Graph)

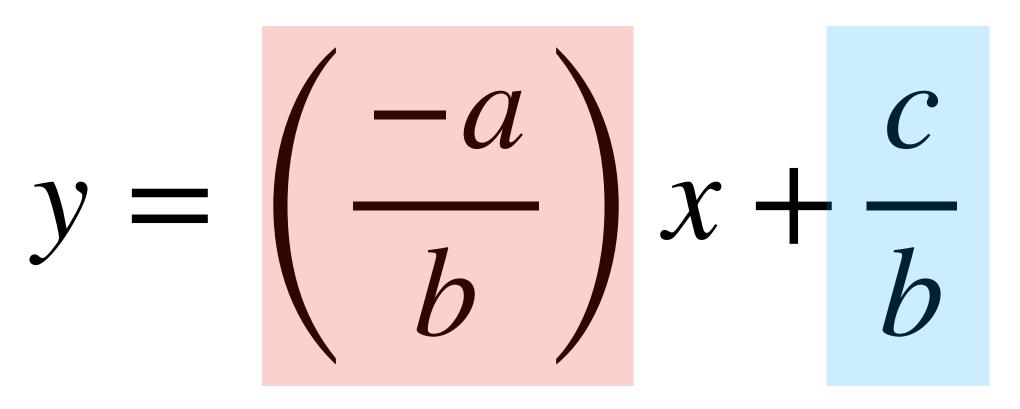


$\{(x, y) : (-2)x + y = 6\}$



Lines

slope-int \rightarrow general (-m)x + y = b



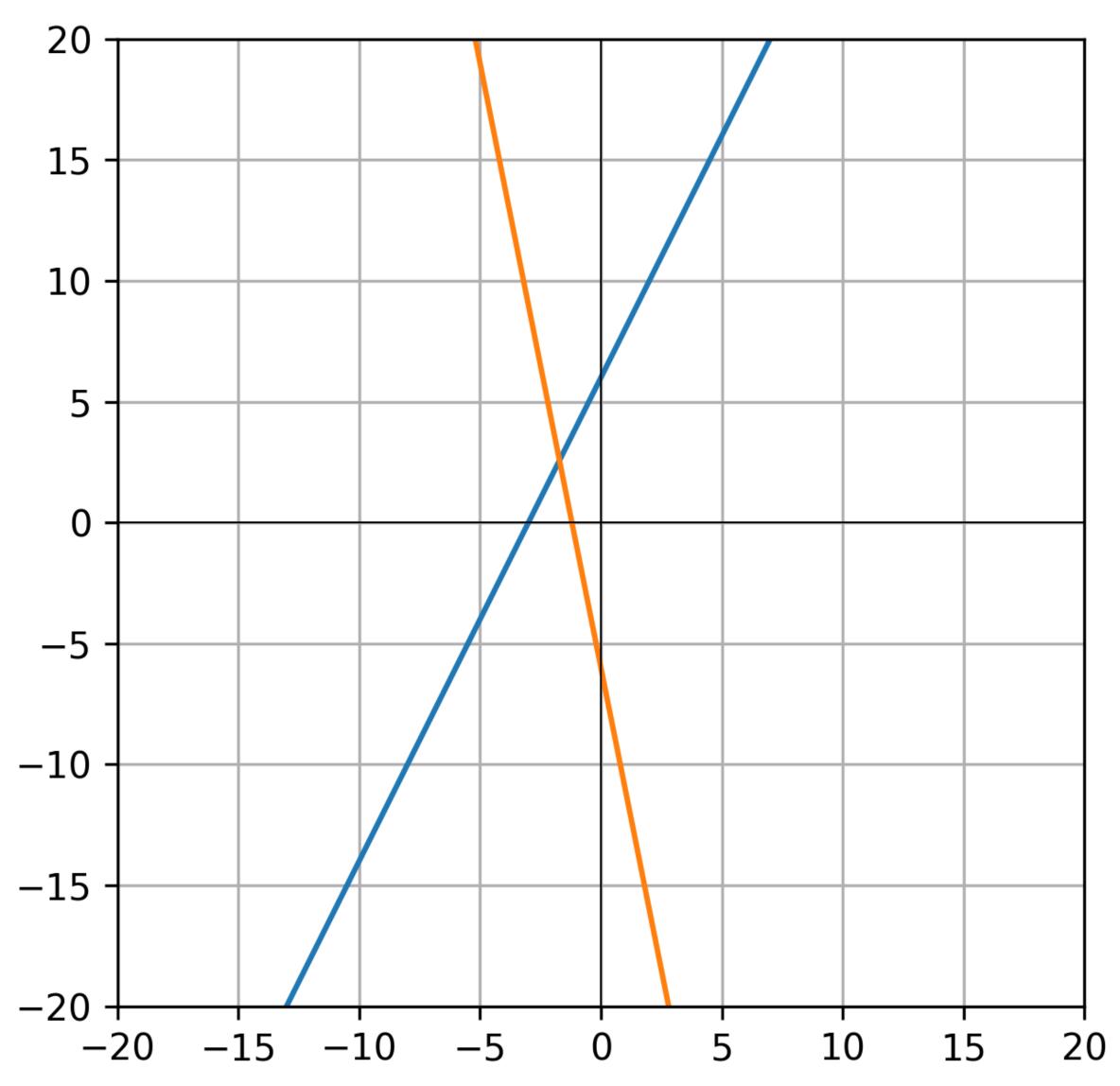
general \rightarrow slope-int

Line Intersection

Question. Given two lines, where do they intersect?

$y = m_1 x + b_1$ $y = m_2 x + b_2$

Line Intersection (Graph)



Line Intersection (Alternative)

Question. Given two (general form) lines, what values of x and y satisfy **both** equations?

$a_1 x + b_1 y = c_1$ $a_{2}x + b_{2}y = c_{2}$

Line Intersection (Alternative)

Question. Given two (general form) lines, what values of x and y satisfy **both** equations? This is the same question

$a_1 x + b_1 y = c_1$ $a_{2}x + b_{2}y = c_{2}$

Motivation

Lines and line intersections An example from chemistry

Example: Balancing Chemical Equations

Example: Balancing Chemical Equations

We want to know how much ethanol is produced by fermentation (for science)

Example: Balancing Chemical Equations

$\begin{array}{ccc} C_6H_{12}O_6 \rightarrow C_2H_5OH + CO_2 \\ & & & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & \\ & & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & &$

We want to know how much ethanol is produced by fermentation (for science)

The number of atoms has to be preserved on each side of the equation

Balancing Chemical Equations

$\begin{array}{ll} \alpha C_{6}H_{12}O_{6} \rightarrow \beta C_{2}H_{5}OH + \gamma CO_{2} \\ & & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & \\ & & & &$

Balancing Chemical Equations

$\alpha C_6 H_{12}O_6 \rightarrow \beta C_2 H_5 OH + \gamma CO_2$ Ethanol Glucose

 $6\alpha = 2\beta + \gamma$ $12\alpha = 6\beta$ $6\alpha = \beta + 2\gamma \qquad (O)$

(C)

(H)

Balancing Chemical Equations

$\alpha C_6 H_{12}O_6 \rightarrow \beta C_2 H_5 OH + \gamma CO_2$ Glucose Ethanol

 $6\alpha - 2\beta - \gamma = 0$ $12\alpha - 6\beta = 0$ $6\alpha - \beta - 2\gamma = 0 \quad (O)$

(C)

(H)

Objectives

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Defining Systems of Linear Equations

- 1. Linear equations
- 2. Systems of linear equations
- 3. Consistency
- 4. Matrix representations

Defining Systems of Linear Equations

1. Linear equations

- 2. Systems of linear equations
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Linear Equations

Definition. A linear equation in the variables x_1, x_2, \dots, x_n is an equation of the form

where a_1, a_2, \ldots, a_n, b are real numbers (\mathbb{R})

$a_1x_1 + a_2x_2 + \ldots + a_nx_n = b$

Linear Equations

Definition. A linear equation in the variables x_1, x_2, \ldots, x_n is an equation of the form

coefficients

$a_1x_1 + a_2x_2 + \ldots + a_nx_n = b$

where a_1, a_2, \ldots, a_n, b are real numbers (\mathbb{R})

Linear Equations

Definition. A linear equation in the variables x_1, x_2, \dots, x_n is an equation of the form

where a_1, a_2, \ldots, a_n, b are real numbers (\mathbb{R})

unknowns

$a_1x_1 + a_2x_2 + \ldots + a_nx_n = b$

Examples

Linear Equations (Point sets)

Linear equations describe point sets:

$\{(s_1, s_2, \dots, s_n) \in \mathbb{R}^n : a_1s_1 + a_2s_2 + \dots + a_ns_n = b\}$



Linear Equations (Point sets)

Linear equations describe point sets:

$$\{(s_1, s_2, ..., s_n) \in \mathbb{R}^n : a$$

$l_1 s_1 + a_2 s_2 + \ldots + a_n s_n = b$ The collections of numbers such that the equation holds.





Examples

If a 2D linear equation is a *line* then a 3D linear equation is...

If a 2D linear equation is a *line* then a 3D linear equation is...

Not a line...

If a 2D linear equation is a *line* then a 3D linear equation is...

If a 2D linear equation is a *line* then a 3D linear equation is...

A plane(!)

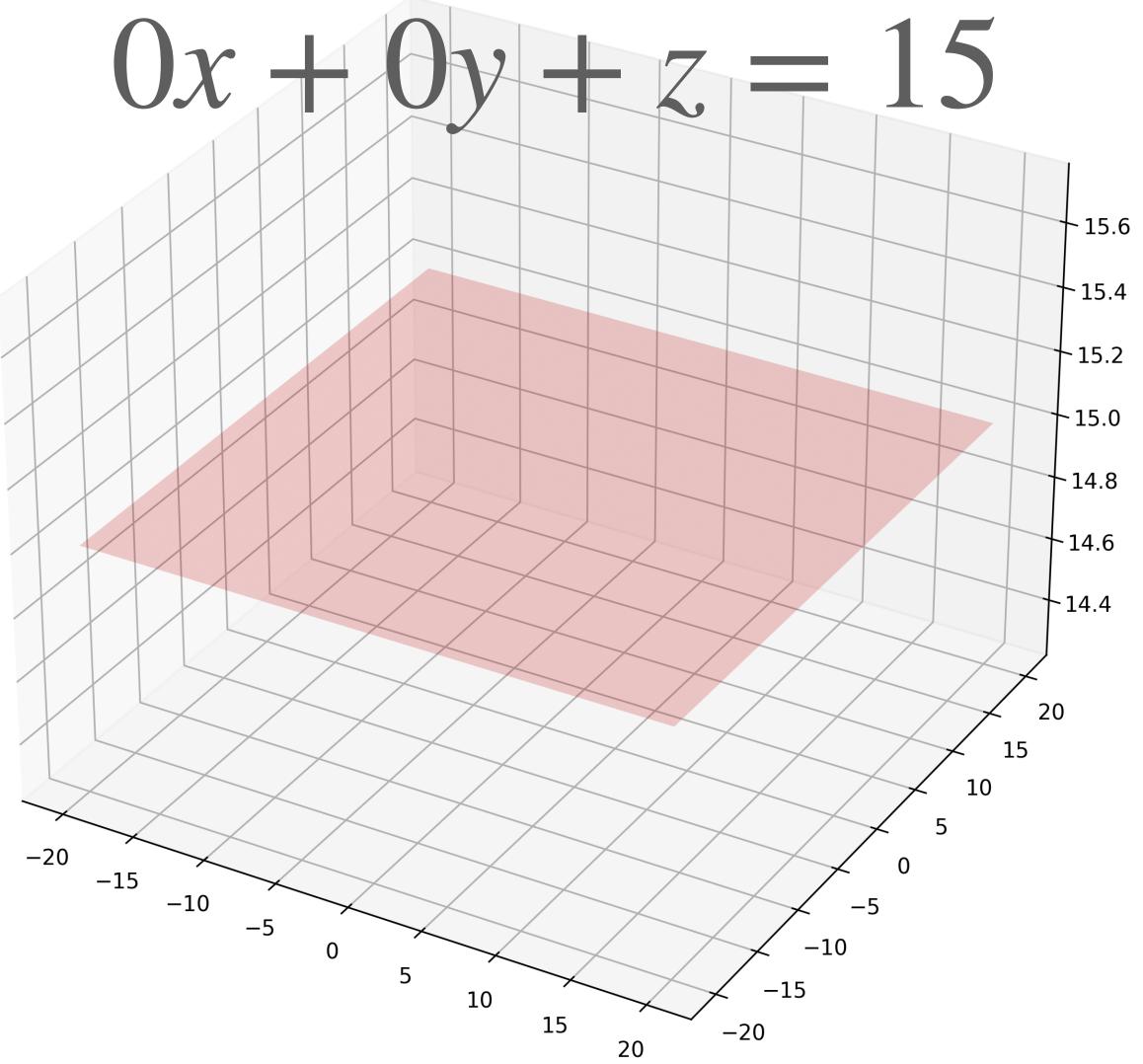
demo

Example 1 0x + 0y + z = 5

This equation describes the solution set so x and y can be whatever we want

- $\{(x, y, z) : z = 5\}$

Example 1



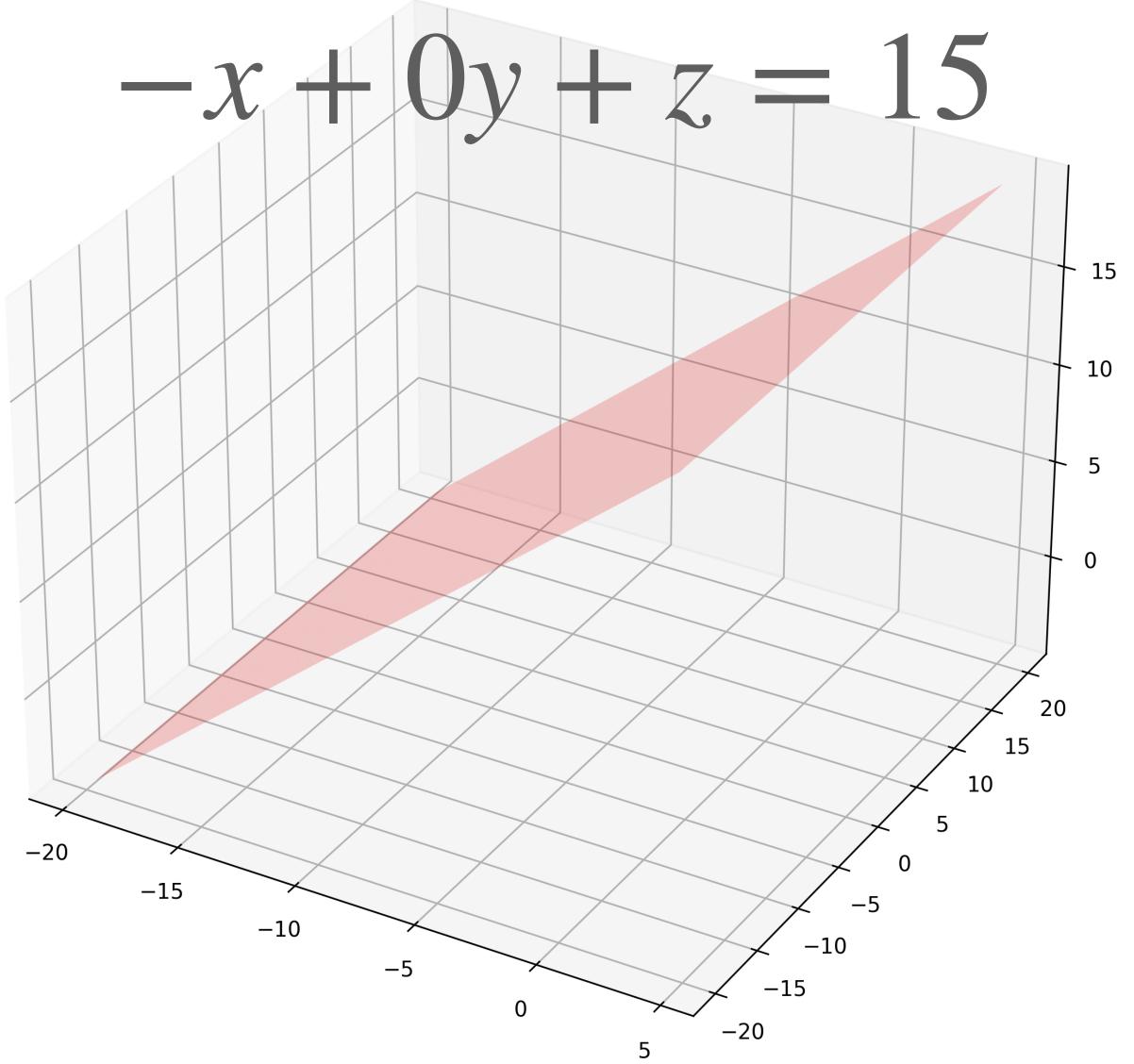
demo

Example 2 -x + 0y + z = 5

This equation describes the point set so y can be whatever we want

- $\{(x, y, z) : z = x + 5\}$

Example 2



demo

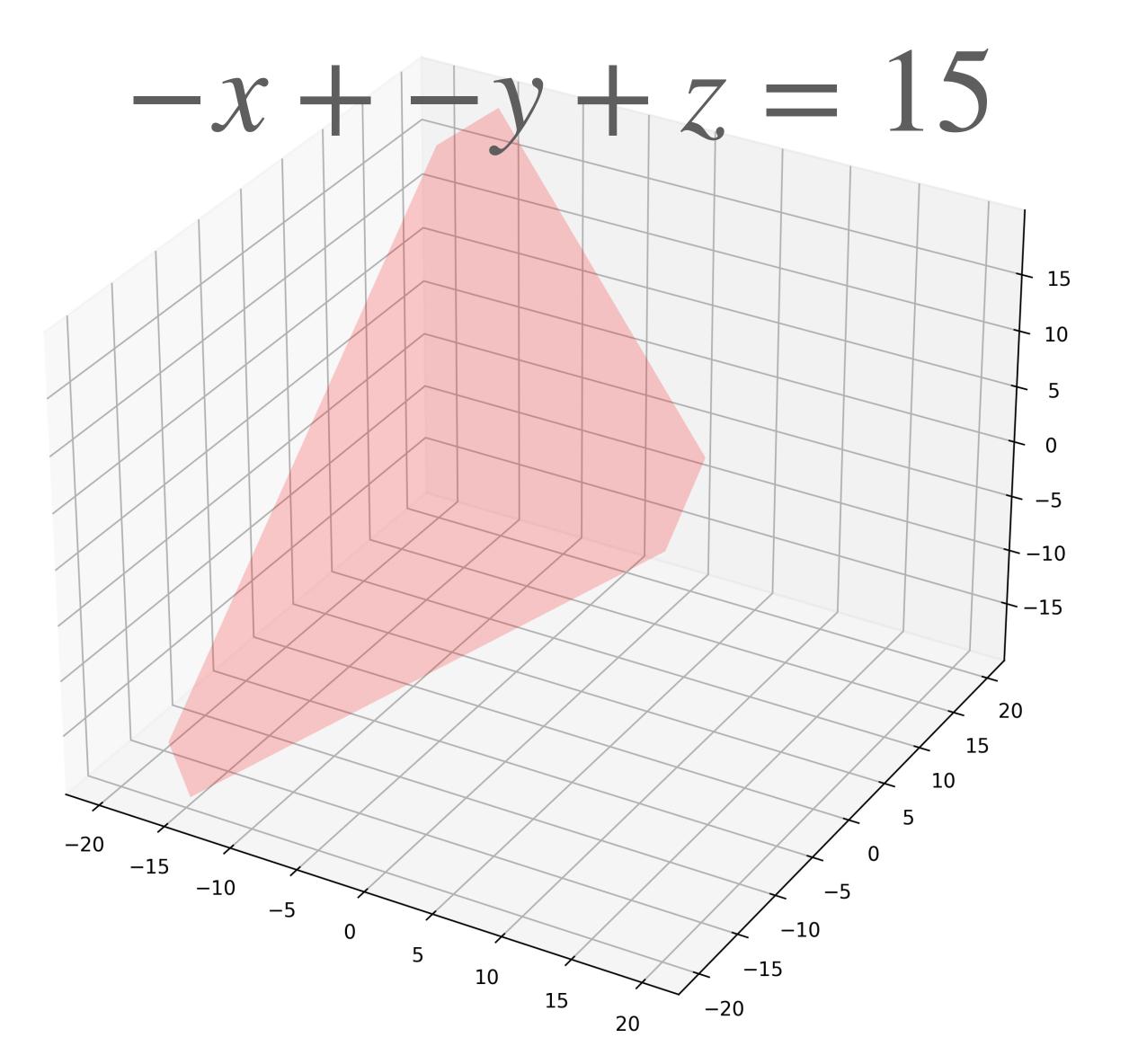
Example 3

This equation describes the solution set so all variables depend on each other

-x + -y + z = 5

- $\{(x, y, z) : z = x + y + 5\}$

Example 3



demo

XYZ-intercepts ax + by + cz = dJust like with lines, we can define x-intercept: $\frac{d}{a}$ y-intercept: $\frac{d}{b}$ z-intercept: $\frac{d}{c}$

These three points define the plane

Question

I just lied.

Give an example of a linear equation that defines a plane with an x-intercept and *y*-intercept but no *z*-intercept



after three dimensions, we can't visualize planes

after three dimensions, we can't visualize planes

a hyperplane

the point set of a linear equation is called

planes

a hyperplane

<u>Theme of the course:</u> Hyperplanes "behave" like 3D planes in many respects

the point set of a linear equation is called

after three dimensions, we can't visualize

Defining Systems of Linear Equations

- 1. Linear equations
- 2. Systems of linear equations
- 3. Consistency
- 4. Matrix representations

Systems of Linear Equations

Definition. A *system of linear equations* is just a collection of linear equations <u>over the</u> <u>same variables</u>.

Systems of Linear Equations

Definition. A system of linear equations is same variables.

just a collection of linear equations over the

Definition. A solution to a system is a point that satisfies all its equations <u>simultaneously</u>

Example

linear system: x + 2y = 1 -x - y - z = -1 2x + 6y - z = 1

solution: (3, -1, -1)

System of Linear equations (General-form) $a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$ $a_{21}x_1 + a_{22}x_2 + \ldots + a_{2n}x_n = b_2$ $a_{m1}x_1 + a_{m2}x_2 + \ldots + a_{mn}x_n = b_m$

System of Linear equations (General-form) $a_{11}x_1 + a_{12}x_2 + \ldots + a_{1n}x_n = b_1$ $a_{21}x_1 + a_{22}x_2 + \ldots + a_{2n}x_n = b_2$ $a_{m1}x_1 + a_m x_2 + \dots + a_m x_n = b_m$

Does a system have a solution? How many solutions are there? What are its solutions?

Defining Systems of Linear Equations

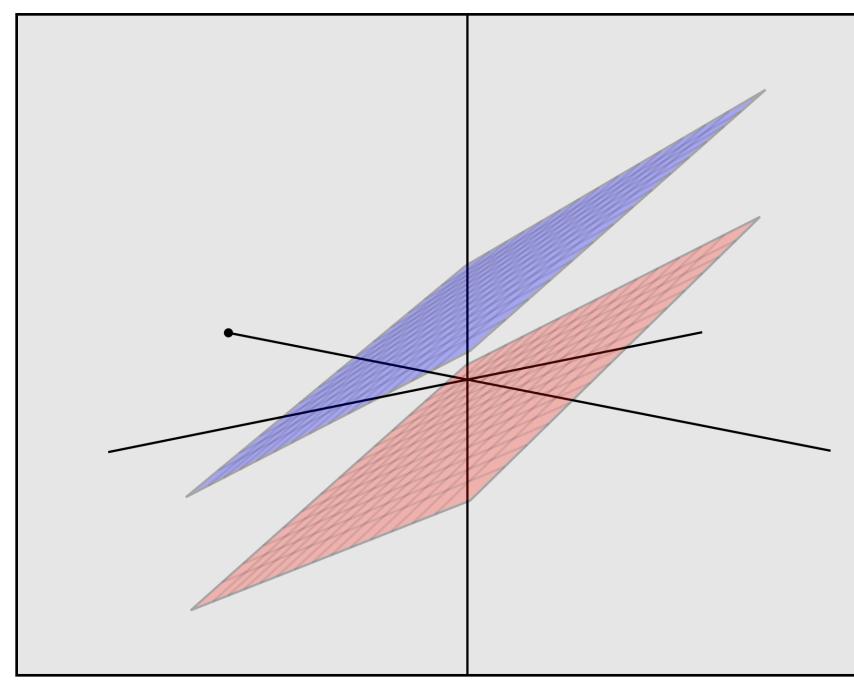
- 1. Linear equations
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Consistency

Definition. A system of linear equations is *consistent* if it has a solution

It is *inconsistent* if it has <u>no</u> solutions

Example





Number of Solutions

zero the system is inconsistent



one the system has a unique solution

many the system has infinity solutions

Number of Solutions

zero the system is inconsistent

one the system has a unique solution

many the system has infinity solutions

These are the only options



Defining Systems of Linear Equations

- 1. Linear equations
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Matrix Representations

always writing down the unknowns is <u>exhausting</u>

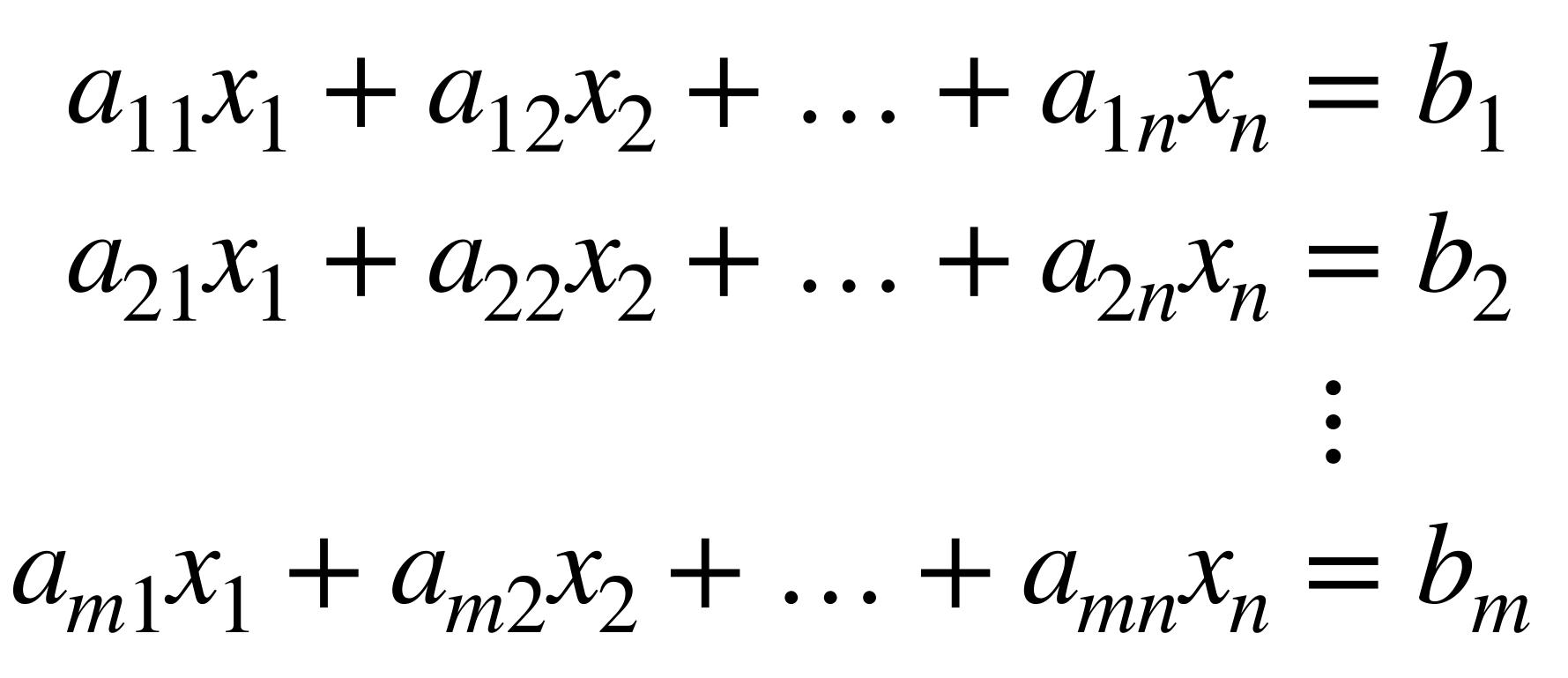
we will write down linear systems as matrices, which are just 2D grids of numbers with fixed width and height

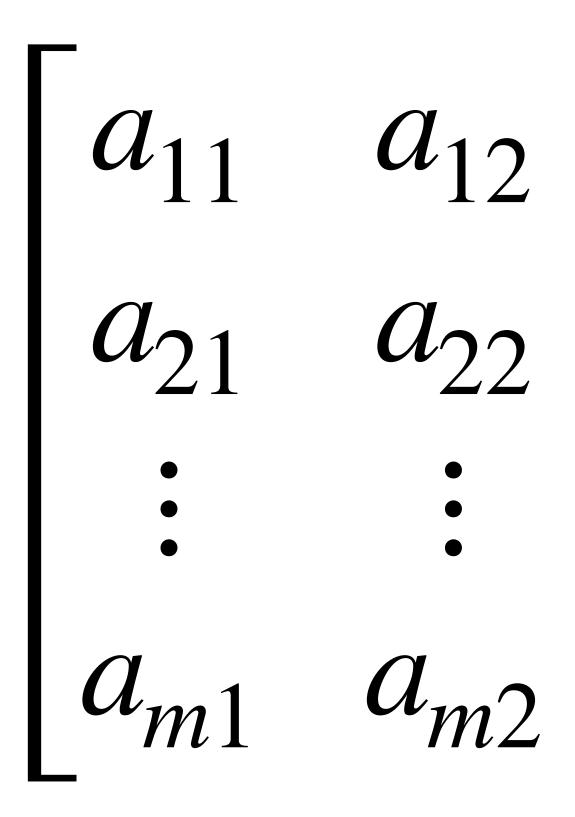
Matrix Representations

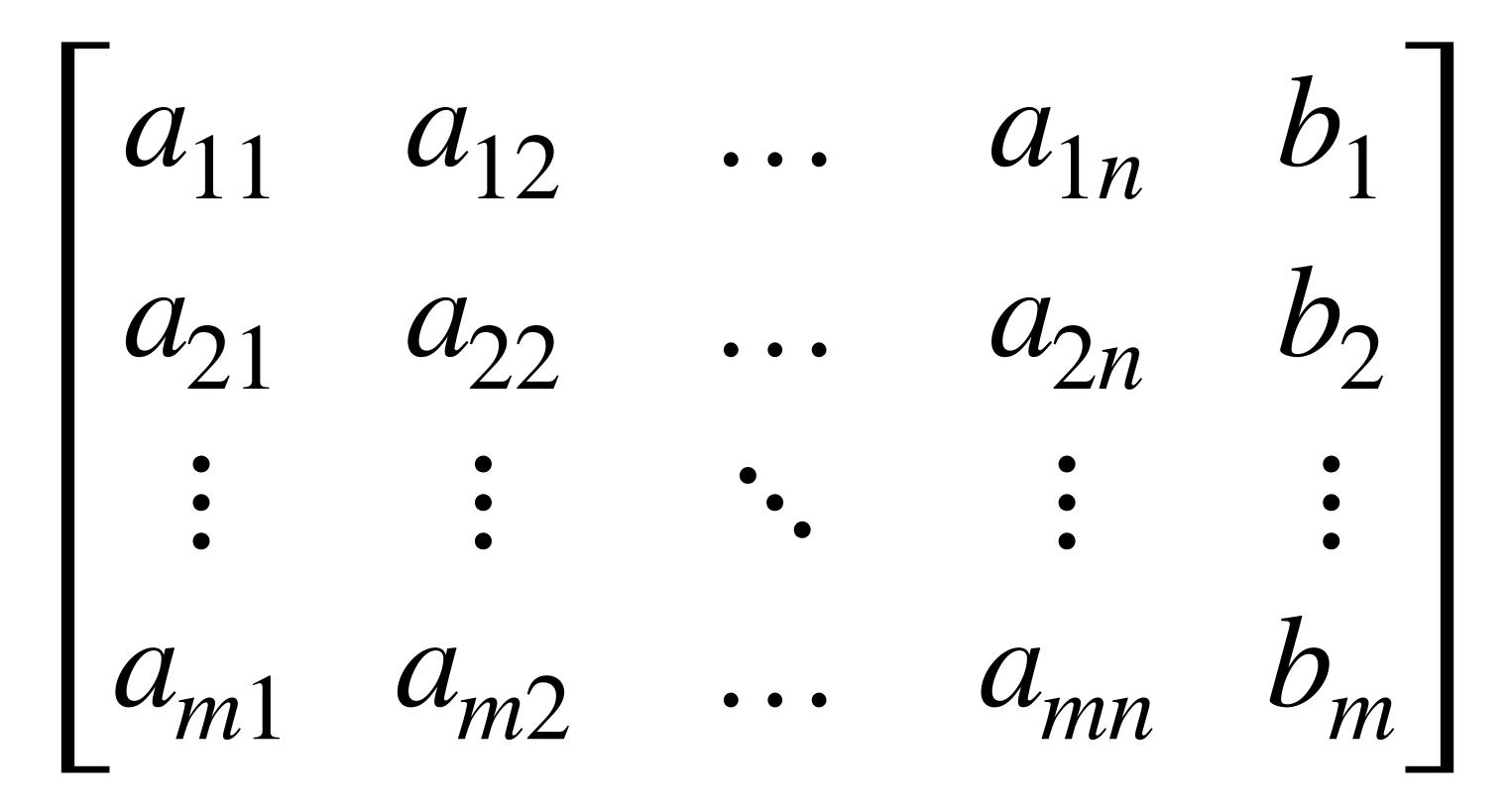
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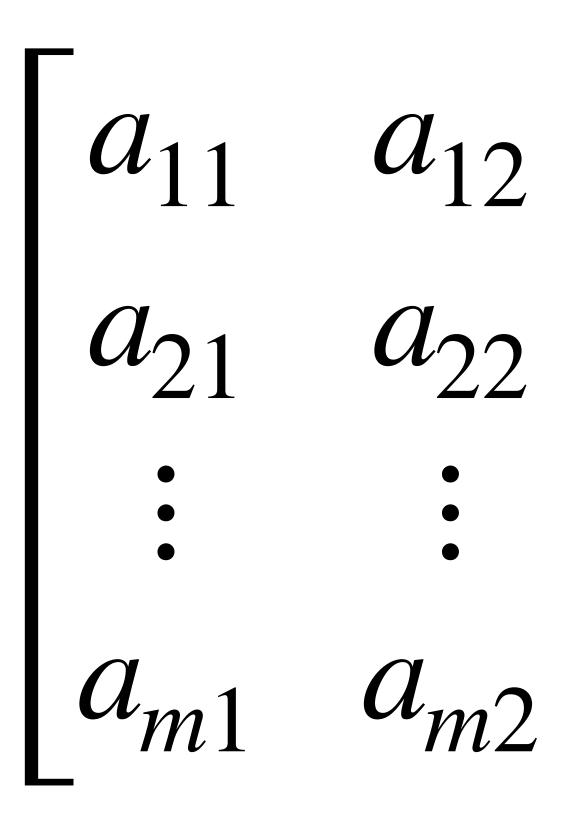
we will write down linear systems as matrices, which are just 2D grids of numbers with <u>fixed</u> width and height

a matrix is just a representation

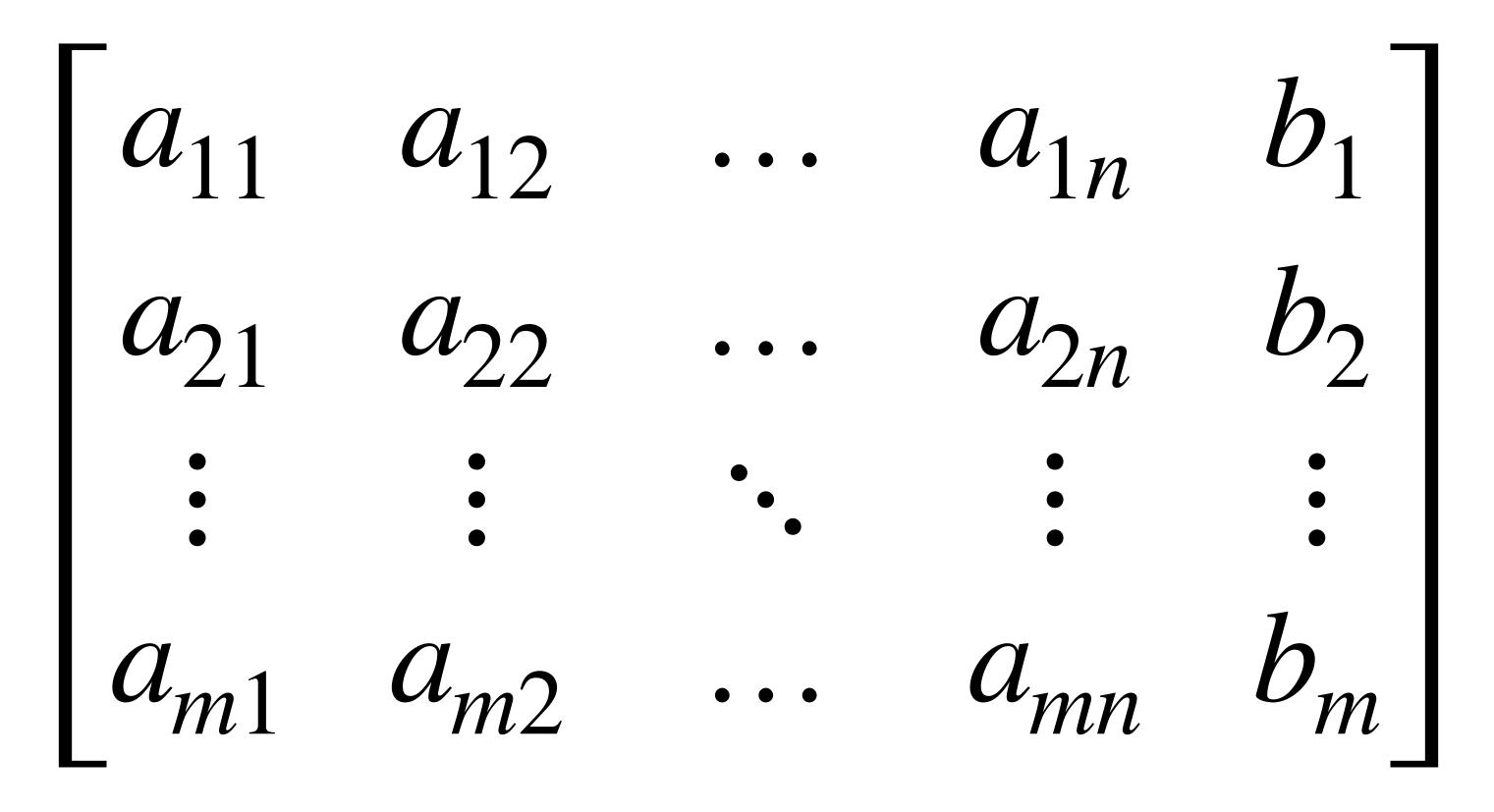


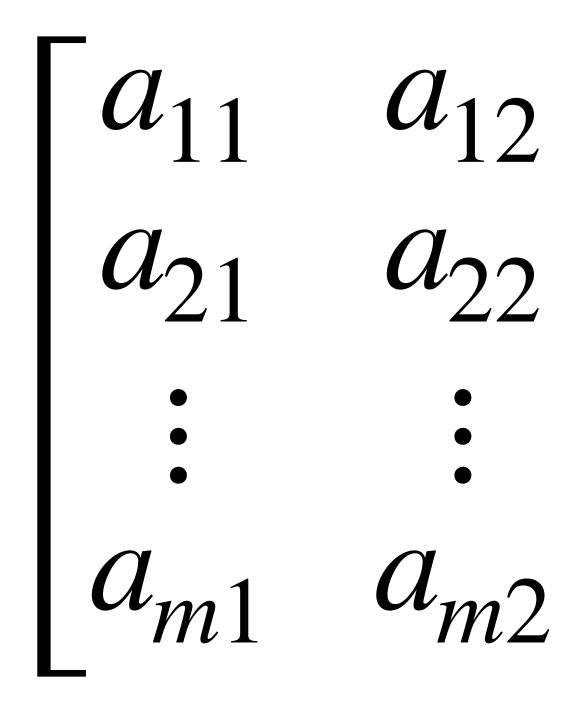


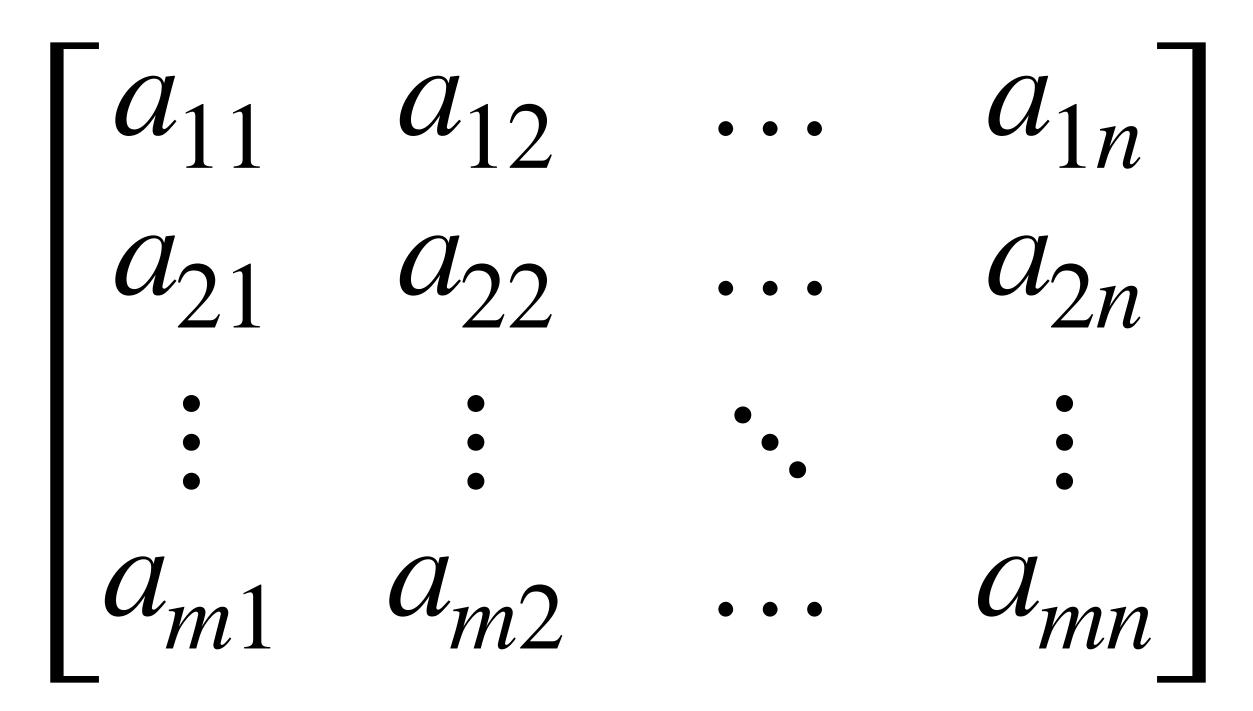




augmented matrix







coefficient matrix

 $6\alpha - 2\beta - \gamma = 0$ $12\alpha - 6\beta = 0$ $6\alpha - \beta - 2\gamma = 0$

(C) (H) **(O)**

$\begin{bmatrix} 6 & -2 & -1 & 0 \\ 12 & -6 & 0 & 0 \\ 6 & -1 & -2 & 0 \end{bmatrix}$

More Examples

Objectives

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- 3. Solve systems of linear equations

- 1. Some simple examples
- 2. Elimination and Back-Substitution
- 3. Row Equivalence

1. Some simple examples

- 2. Elimination and Back-Substitution
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1. Some simple examples

- 2. Elimination and Back-Substitution
- 3. Row Equivalence

We'll only consider systems with unique solutions for now.



2x + 3y = -64x - 5y = 10

The Approach

2x + 3y = -64x - 5y = 10

- The Approach Solve for x in terms of y in EQ1
- 2x + 3y = -64x - 5y = 10

Solving Systems with Two Variables 2x + 3y = -64x - 5y = 10The Approach Solve for x in terms of y in EQ1

Substitute result for x in EQ2 and solve for y

Solving Systems with Two Variables 2x + 3y = -64x - 5y = 10The Approach Solve for x in terms of y in EQ1 Substitute result for x in EQ2 and solve for ySubstitute result for y in EQ1 and solve for x



Let's work through it...



2x + 3y = -64x - 5y = 10





Solving Systems with Two Variables 2x = (-3)y - 64x - 5y = 10The Approach Solve for x in terms of y in EQ1 Substitute result for x in EQ2 and solve for ySubstitute result for y in EQ1 and solve for x



Solving Systems with Two Variables x = (-3/2)y - 34x - 5y = 10The Approach Solve for x in terms of y in EQ1 Substitute result for x in EQ2 and solve for ySubstitute result for y in EQ1 and solve for x



4((-3/2)y - 3) - 5y = 10The Approach Solve for x in terms of y in EQ1 Substitute result for x in EQ2 and solve for y Substitute result for y in EQ1 and solve for x

x = (-3/2)y - 3



Solving Systems with Two Variables x = (-3/2)y - 3-6y - 12 - 5y = 10

The Approach Solve for x in terms of y in EQ1 Substitute result for x in EQ2 and solve for ySubstitute result for y in EQ1 and solve for x



Solving Systems with Two Variables x = (-3/2)y - 3-11y = 22The Approach Solve for x in terms of y in EQ1 Substitute result for x in EQ2 and solve for y Substitute result for y in EQ1 and solve for x



Solving Systems with Two Variables x = (-3/2)y - 3y = -2The Approach Solve for x in terms of y in EQ1 Substitute result for x in EQ2 and solve for y Substitute result for y in EQ1 and solve for x



Solving Systems with Two Variables x = (-3/2)(-2) - 3y = -2The Approach Solve for x in terms of y in EQ1 Substitute result for x in EQ2 and solve for ySubstitute result for y in EQ1 and solve for x



The Approach Solve for x in terms of y in EQ1

x = 3 - 3y = -2

- Substitute result for x in EQ2 and solve for y
- Substitute result for y in EQ1 and solve for x



Solving Systems with Two Variables $\chi = ()$ y = -2The Approach Solve for x in terms of y in EQ1 Substitute result for x in EQ2 and solve for y

Substitute result for y in EQ1 and solve for x



another perspective...

Solving Systems with Two Variables 2x + 3y = -64x - 5y = 10The Approach

The Approach Eliminate x from the EQ2 and solve for y Eliminate y from EQ1 and solve for x

Let's work through it again...

2x + 3y = -64x - 5y = 10





1. Some simple examples 2. Elimination and Back-Substitution 3. Row Equivalence

Solving Systems with Three Variables x - 2y + z = 52y - 8z = -46x + 5y + 9z = -4

Solving Systems with Three Variables x - 2y + z = 5 2y - 8z = -46x + 5y + 9z = -4

The Approach

Solving Systems with Three Variables x - 2y + z = 52y - 8z = -46x + 5y + 9z = -4The Approach Eliminate x from the EQ2 and EQ3

Solving Systems with Three Variables x - 2y + z = 52y - 8z = -46x + 5y + 9z = -4The Approach Eliminate x from the EQ2 and EQ3

Eliminate y from EQ3

Solving Systems with Three Variables x - 2y + z = 52y - 8z = -46x + 5y + 9z = -4The Approach

- Eliminate x from the EQ2 and EQ3
- Eliminate y from EQ3
- Eliminate $\ensuremath{\mathcal{Z}}$ from EQ2 and EQ1

Solving Systems with Three Variables x - 2y + z = 52y - 8z = -46x + 5y + 9z = -4The Approach Eliminate x from the EQ2 and EQ3

Eliminate y from EQ3

Eliminate z from EQ2 and EQ1

Eliminate y from EQ1

Solving Systems with Three Variables x - 2y + z = 52y - 8z = -46x + 5y + 9z = -4The Approach Eliminate x from the EQ2 and EQ3 Eliminate y from EQ3 Eliminate z from EQ2 and EQ1 Eliminate y from EQ1

Elimination

Back-Substitution



Let's work through it

x - 2y + z = 52y - 8z = -46x + 5y + 9z = -4



Solving Systems with Three Variables x - 2y + z = 52y - 8z = -4

6(5+2y-z) The Approach

- Eliminate x from the EQ2 and EQ3
- Eliminate y from EQ3
- Eliminate $\ensuremath{\mathcal{Z}}$ from EQ2 and EQ1
- Eliminate y from EQ1

6(5 + 2y - z) + 5y + 9z = -4

Solving Systems with Three Variables x - 2y + z = 52y - 8z = -430 + 12y - 6z + 5y + 9z = -4

The Approach

Eliminate x from the EQ2 and EQ3

Eliminate y from EQ3

Eliminate z from EQ2 and EQ1

Eliminate y from EQ1

Solving Systems with Three Variables x - 2y + z = 52y - 8z = -417y + 3z = -34The Approach Eliminate x from the EQ2 and EQ3 Eliminate y from EQ3 Eliminate z from EQ2 and EQ1 Eliminate y from EQ1

Solving Systems with Three Variables x - 2y + z = 52y - 8z = -417(8z - 4)/2 + 3z = -34

The Approach

- Eliminate x from the EQ2 and EQ3
- Eliminate y from EQ3
- Eliminate z from EQ2 and EQ1
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Solving Systems with Three Variables x - 2y + z = 52y - 8z = -417(4z - 2) - 3z = -34The Approach Eliminate x from the EQ2 and EQ3 Eliminate y from EQ3 Eliminate z from EQ2 and EQ1 Eliminate y from EQ1

Solving Systems with Three Variables x - 2y + z = 52y - 8z = -468z - 34 - 3z = 26The Approach Eliminate x from the EQ2 and EQ3 Eliminate y from EQ3 Eliminate z from EQ2 and EQ1 Eliminate y from EQ1

Solving Systems with Three Variables x - 2y + z = 52y - 8z = -4

The Approach

- Eliminate x from the EQ2 and EQ3
- Eliminate y from EQ3
- Eliminate z from EQ2 and EQ1
- Eliminate y from EQ1

71z = 0

Solving Systems with Three Variables x - 2y + 0 = 52y - 8(0) = -4z = 0

The Approach

- Eliminate x from the EQ2 and EQ3
- Eliminate y from EQ3
- Eliminate z from EQ2 and EQ1
- Eliminate y from EQ1

Solving Systems with Three Variables x - 2y = 52y = -4

The Approach

- Eliminate x from the EQ2 and EQ3
- Eliminate y from EQ3
- Eliminate z from EQ2 and EQ1
- Eliminate y from EQ1

z = 0

Solving Systems with Three Variables x - 2(-2) = 5 y = -2z = 0

The Approach

- Eliminate x from the EQ2 and EQ3
- Eliminate y from EQ3
- Eliminate z from EQ2 and EQ1
- Eliminate y from EQ1

Solving Systems with Three Variables x = 1 y = -2z = 0

The Approach

- Eliminate x from the EQ2 and EQ3
- Eliminate y from EQ3
- Eliminate z from EQ2 and EQ1
- Eliminate y from EQ1

Solving Systems with Three Variables x = 1y = -2z = 0

The Approach

Eliminate x from the EQ2 and EQ3

Eliminate y from EQ3

Eliminate z from EQ2 and EQ1

Eliminate y from EQ1

Elimination

Back-Substitution



Verifying the Solution

x - 2y + z = 52y - 8z = -46x + 5y + 9z = -4





Verifying the Solution

x - 2y + z = 52y - 8z = -46x + 5y + 9z = -4

Verifying the Solution (1) - 2(-2) + (0) = 52(-2) - 8(0) = -46(1) + 5(-2) + 9(0) = -4

Verifying the Solution

1 + 4 + 0 = 5-4 + 0 = -46 - 10 + 0 = -4

Verifying the Solution

5 = 5-4 = -4-4 = -4The solution simultaneously satisfies the equations x = 1y = -2z = 0



Solving Systems of Linear Equations

Some simple examples
 Elimination and Back-Substitution

3. Row Equivalence

Solving Systems as Matrices

How does this look with matrices? elimination and back-substitution same solutions

Observation. Each intermediate step of gives us a new linear system with the

Solving Systems as Matrices

How does this look with matrices? **Observation.** Each intermediate step of elimination and back-substitution gives us a new linear system with the same solutions

Can we represent these intermediate steps as operations on matrices?

Let's look back at this...

2x + 3y = -64x - 5y = 10





Elementary Row Operations

scaling multiply
replacement add a mu
another
interchange switch t

multiply a row by a number

add a multiple of one row to

switch two rows

Elementary Row Operations

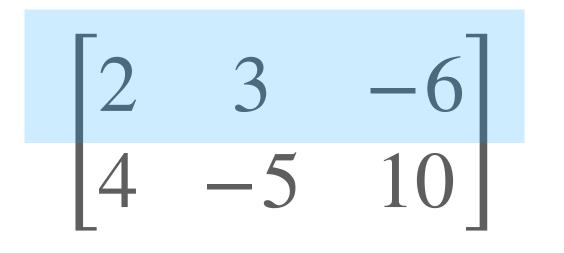
- scaling multiply a row by a number add a multiple of one row to replacement another
- interchange

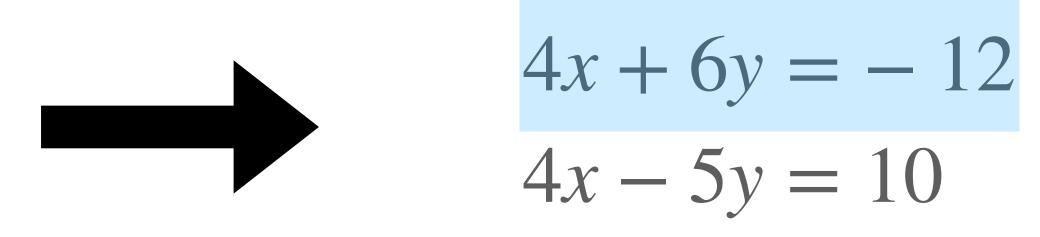
switch two rows

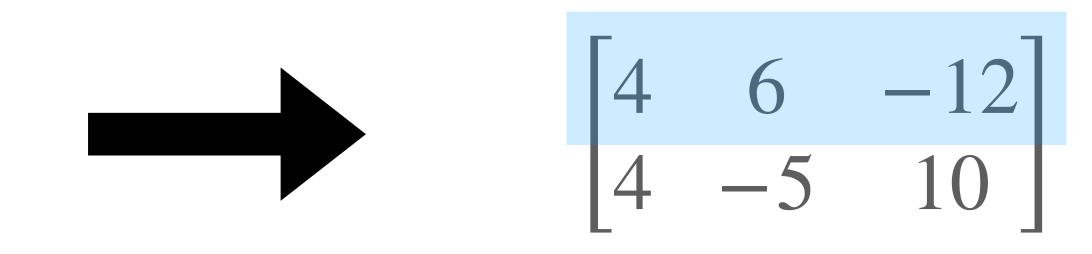
These operations don't change the solutions

Scaling Example

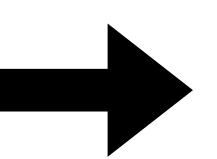
2x + 3y = -64x - 5y = 10









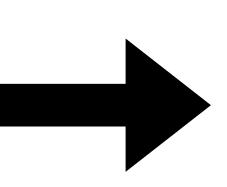


Replacement Example

$$2x + 3y = -6$$
$$4x - 5y = 10$$

$$\begin{bmatrix} 2 & 3 & -6 \\ 4 & -5 & 10 \end{bmatrix}$$

2x + 3y = -66x - 2y = 4



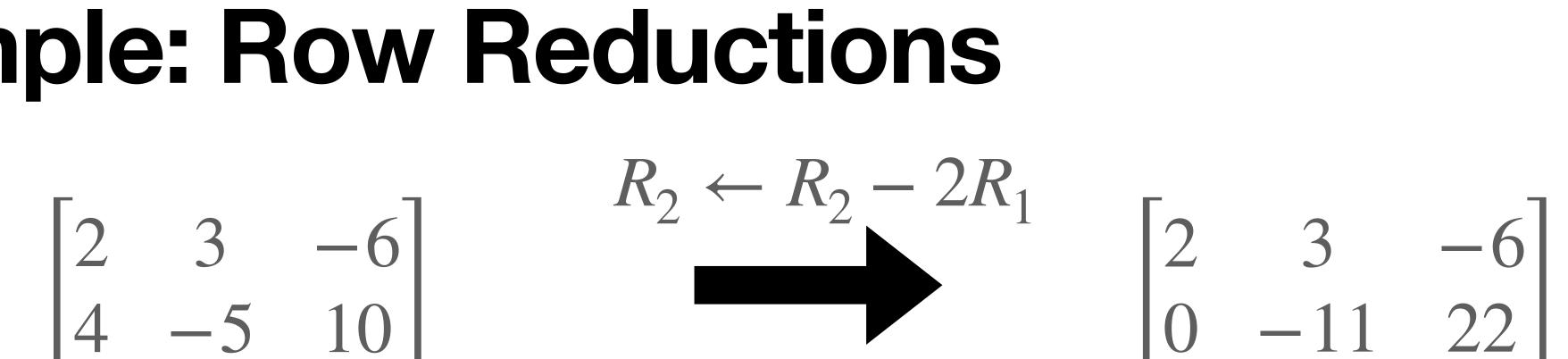
Interchange Example

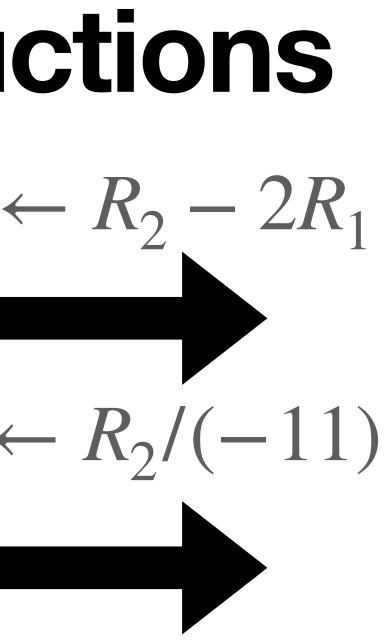
2x + 3y = -64x - 5y = 10

 $\begin{vmatrix} 2 & 3 & -6 \\ 4 & -5 & 10 \end{vmatrix}$

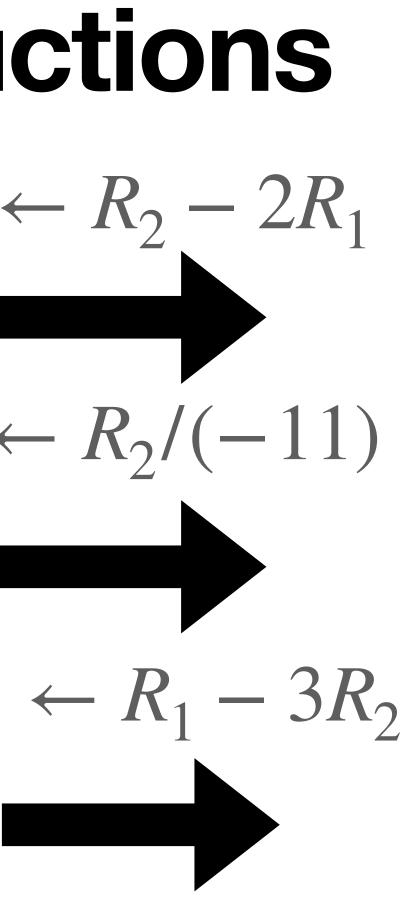
4x - 5y = 102x + 3y = -6

$\begin{vmatrix} 4 & -5 & 10 \\ 2 & 3 & -6 \end{vmatrix}$





 $\begin{bmatrix} 2 & 3 & -6 \\ 4 & -5 & 10 \end{bmatrix} \xrightarrow{R_2 \leftarrow R_2 - 2R_1} \begin{bmatrix} 2 & 3 & -6 \\ 0 & -11 & 22 \end{bmatrix}$ $R_2 \leftarrow R_2/(-11) \begin{bmatrix} 2 & 3 & -6 \\ 0 & -11 & 22 \end{bmatrix}$ $\begin{bmatrix} 2 & 3 & -6 \\ 0 & 1 & -2 \end{bmatrix}$



 $\begin{bmatrix} 2 & 3 & -6 \\ 4 & -5 & 10 \end{bmatrix} \xrightarrow{R_2 \leftarrow R_2 - 2R_1} \begin{bmatrix} 2 & 3 & -6 \\ 0 & -11 & 22 \end{bmatrix}$ $R_2 \leftarrow R_2/(-11) \begin{bmatrix} 2 & 3 & -6 \\ 0 & -11 & 22 \end{bmatrix} \begin{bmatrix} 2 & 3 & -6 \\ 0 & -11 & 22 \end{bmatrix}$ $R_{1} \leftarrow R_{1} - 3R_{2}$ $\begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & -2 \end{bmatrix}$

 $\begin{bmatrix} 2 & 3 & -6 \\ 4 & -5 & 10 \end{bmatrix} \xrightarrow{R_2 \leftarrow R_2 - 2R_1} \begin{bmatrix} 2 & 3 & -6 \\ 0 & -11 & 22 \end{bmatrix}$ $R_2 \leftarrow R_2/(-11) \begin{bmatrix} 2 & 3 & -6 \\ 0 & -11 & 22 \end{bmatrix} \begin{bmatrix} 2 & 3 & -6 \\ 0 & -11 & 22 \end{bmatrix}$ $R_1 \leftarrow R_1 - 3R_2$ $R_1 \leftarrow R_1/2$

 $\begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & -2 \end{bmatrix}$ $\begin{vmatrix} 1 & 0 & 0 \\ 0 & 1 & -2 \end{vmatrix}$

 $\begin{bmatrix} 2 & 3 & -6 \\ 4 & -5 & 10 \end{bmatrix}$

 $R_2 \leftarrow R_2 - 2R_1$ $R_2 \leftarrow R_2/(-11)$ $R_1 \leftarrow R_1 - 3R_2$ $R_1 \leftarrow R_1/2$

0 1 2

 $R_{2} \leftarrow R_{1} \leftarrow R_{1$

 $\begin{bmatrix} 2 & 3 & -6 \\ 4 & -5 & 10 \end{bmatrix}$

$$- \frac{R_2 - 2R_1}{R_2 - R_2 - R_1 - 3R_2}$$
$$- \frac{R_1 - 3R_2}{R_1 - R_1 - 2R_2}$$

elimination substitution

$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 2 \end{bmatrix}$

Row Equivalence

one can be transformed into the other by a sequence of row operations

$$\begin{bmatrix} 2 & 3 & -6 \\ 4 & -5 & 10 \end{bmatrix}$$

Definition. Two matrices are row equivalent if

Row Equivalence

one can be transformed into the other by a sequence of row operations

$\begin{vmatrix} 2 & 3 & -6 \\ 4 & -5 & 10 \end{vmatrix}$

Definition. Two matrices are row equivalent if

We can compute solutions by sequence of row operations

 $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -2 \end{bmatrix}$

(Open-Ended) Question

How do we know when we're done? What is the "target" matrix?

We'll get to that next time...

demo (SciPy)

Summary

Linear equations define <u>hyperplanes</u> not have <u>solutions</u> Linear systems can be represented as matrices, which makes them more convenient to solve

Systems of linear equations may or may