Solving Linear Systems + Echelon Forms

Lecture 2

CAS CS 132

Practice Problem

 $3x_1 - 2x_2 + 6x_3 - 4x_4 = 0$

Write down four distinct points in \mathbb{R}^4 which are in the point set defined by the above linear equation.



 $3x_1 - 2x_2 + 6x_3 - 4x_4 = 0$ 3(-2) - 2(-2) + 6 - 4 = 03(2) - 2(3) + 6(4) - 4(6) = (6) $3(4) - 2 - 6 - 4 = 0^{1}$



Objectives

- 1. Solve linear systems by elimination method
- 2. Solve linear systems by row operations
- 3. Introduce echelon forms as as a kind of matrix which "represents" solutions
- 4. Learn how to "read off" a solution from an echelon form matrix.

Keywords

substitution method

elimination method

forward elimination

back-substitution

elementary row operations

scaling, replacement, interchange

Sympy operations

echelon form

row-reduced echelon form (RREF)

general form solution

Recap

Recall: Linear Equations

Definition. A linear equation in the variables x_1, x_2, \ldots, x_n is an equation of the form

where a_1, a_2, \ldots, a_n, b are real numbers (\mathbb{R})

$a_1x_1 + a_2x_2 + \ldots + a_nx_n = b$

Recall: Linear Equations

Definition. A linear equation in the variables x_1, x_2, \ldots, x_n is an equation of the form

coefficients

$a_1x_1 + a_2x_2 + \ldots + a_nx_n = b$

where a_1, a_2, \ldots, a_n, b are real numbers (\mathbb{R})

Recall: Linear Equations

Definition. A linear equation in the variables x_1, x_2, \ldots, x_n is an equation of the form

where a_1, a_2, \ldots, a_n, b are real numbers (\mathbb{R})

unknowns

$a_1x_1 + a_2x_2 + \ldots + a_nx_n = b$

Recall: Linear Equations (Point sets)

Linear equations describe *point sets*:

 $\{(s_1, s_2, \dots, s_n) \in \mathbb{R}^n : a_1 s_1 + a_2 s_2 + \dots + a_n s_n = b\}$



Recall: Linear Equations (Point sets)

Linear equations describe point sets:

$$\{(s_1, s_2, ..., s_n) \in \mathbb{R}^n : a$$

$l_1s_1 + a_2s_2 + \ldots + a_ns_n = b$ The collections of numbers such that the equation holds.





Recall: Linear Equations (Pictorially)



Recall: Linear Systems (General-form)

 $a_{11}x_1 + a_{12}x_2 + \ldots + a_{1n}x_n = b_1$ $a_{21}x_1 + a_{22}x_2 + \ldots + a_{2n}x_n = b_2$ $a_{m1}x_1 + a_{m2}x_2 + \ldots + a_{mn}x_n = b_m$

Recall: Linear Systems (General-form) $a_{11}x_1 + a_{12}x_2 + \ldots + a_{1n}x_n = b_1$ $a_{21}x_1 + a_{22}x_2 + \ldots + a_{2n}x_n = b_2$ $a_{m1}x_1 + a_{m2}x_2 + \ldots + a_{mn}x_n = b_m$

Does a system have a solution? How many solutions are there? What are its solutions?

Recall: Linear Systems (Pictorially)



Recall: Number of Solutions

zero the system is inconsistent

one the system has a unique solution

many the system has infinity solutions

Recall: Number of Solutions

zero the system is inconsistent

one the system has a unique solution

many the system has infinity solutions

These are the only options









augmented matrix







coefficient matrix

Solving Linear Systems (Elimination Method)

Line Intersection Problem

2x=-6-37 x = -3 - 3/2 Y

-12 - 67 - 57 = 10-114 = 72Y - - 2

2x + 3y = -64x - 5y = 102x + 3(-2) = -62 x = 0 X=O $\chi = 0$ Y = - 2





2x + 3y = -64x - 5y = 10

The Approach

2x + 3y = -64x - 5y = 10

- The Approach Solve for x in terms of y in EQ1
- 2x + 3y = -64x - 5y = 10

Solving Systems with Two Variables 2x + 3y = -64x - 5y = 10The Approach Solve for x in terms of y in EQ1

Substitute result for x in EQ2 and solve for y

Solving Systems with Two Variables 2x + 3y = -64x - 5y = 10The Approach Solve for x in terms of y in EQ1 Substitute result for x in EQ2 and solve for ySubstitute result for y in EQ1 and solve for x



Solving Systems with Two Variables 2x = (-3)y - 64x - 5y = 10The Approach Solve for x in terms of y in EQ1 Substitute result for x in EQ2 and solve for ySubstitute result for y in EQ1 and solve for x



Solving Systems with Two Variables x = (-3/2)y - 34x - 5y = 10The Approach Solve for x in terms of y in EQ1 Substitute result for x in EQ2 and solve for ySubstitute result for y in EQ1 and solve for x



4((-3/2)y - 3) - 5y = 10The Approach Solve for x in terms of y in EQ1 Substitute result for x in EQ2 and solve for y Substitute result for y in EQ1 and solve for x

x = (-3/2)y - 3



Solving Systems with Two Variables x = (-3/2)y - 3-6y - 12 - 5y = 10

The Approach Solve for x in terms of y in EQ1 Substitute result for x in EQ2 and solve for ySubstitute result for y in EQ1 and solve for x



Solving Systems with Two Variables x = (-3/2)y - 3-11y = 22The Approach Solve for x in terms of y in EQ1 Substitute result for x in EQ2 and solve for y Substitute result for y in EQ1 and solve for x



Solving Systems with Two Variables x = (-3/2)y - 3y = -2The Approach Solve for x in terms of y in EQ1 Substitute result for x in EQ2 and solve for y Substitute result for y in EQ1 and solve for x



Solving Systems with Two Variables x = (-3/2)(-2) - 3y = -2The Approach Solve for x in terms of y in EQ1 Substitute result for x in EQ2 and solve for ySubstitute result for y in EQ1 and solve for x



The Approach Solve for x in terms of y in EQ1

x = 3 - 3y = -2

- Substitute result for x in EQ2 and solve for y
- Substitute result for y in EQ1 and solve for x


Solving Systems with Two Variables $\chi = ()$ y = -2The Approach Solve for x in terms of y in EQ1 Substitute result for x in EQ2 and solve for y

Substitute result for y in EQ1 and solve for x



another perspective...

Solving Systems with Two Variables 2x + 3y = -64x - 5y = 10

The Approach Eliminate x from the EQ2 and solve for y Substitute y into EQ1 and solve for x

 $E_1 2x + 3y = -6$ Let's work through it again... $E_{3} 4x - 5y = 10$ $E_2 - 2E_1$ 4x - 5y - (4x + 6y) = 10 + 122 x + 3 1 = - 1 E11 -11y = 22E1-3E2 $Z_X = 0$ E2/-11 2 × + 3







Solving Systems of Linear Equations

1. Some simple examples 2. Elimination and Back-Substitution 3. Row Equivalence

Solving Systems with Three Variables x - 2y + z = 52y - 8z = -46x + 5y + 9z = -4

Solving Systems with Three Variables x - 2y + z = 5 2y - 8z = -46x + 5y + 9z = -4

The Approach

Solving Systems with Three Variables x - 2y + z = 52y - 8z = -46x + 5y + 9z = -4The Approach Eliminate x from the EQ2 and EQ3

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Eliminate y from EQ3

Solving Systems with Three Variables x - 2y + z = 52y - 8z = -46x + 5y + 9z = -4The Approach

- Eliminate x from the EQ2 and EQ3
- Eliminate y from EQ3
- Eliminate $\ensuremath{\mathcal{Z}}$ from EQ2 and EQ1

Solving Systems with Three Variables x - 2y + z = 52y - 8z = -46x + 5y + 9z = -4The Approach

- Eliminate x from the EQ2 and EQ3
- Eliminate y from EQ3
- Eliminate $\ensuremath{\mathcal{Z}}$ from EQ2 and EQ1
- Eliminate y from from EQ1

Solving Systems with Three Variables x - 2y + z = 52y - 8z = -46x + 5y + 9z = -4The Approach Eliminate x from the EQ2 and EQ3 Eliminate y from EQ3 Eliminate z from EQ2 and EQ1 Eliminate y from from EQ1

Elimination

Back-Substitution





E, x - 2y + z = 5 $E_{2} = 2y - 8z = -4$ $E_3 6x + 5y + 9z = -4$ -Gx +12y -GZ -30

E3 - 1742 $\chi - 2\gamma + 2 = 5$ y-42=-2 7/2=0 E3/71



E, +2Ez X - 2 - 1 + 2 = 5 7-42-2 7- $E, -E_{2}$ $E_2 + UE_3$ 20 x - 2y = 5 -2 2--

Solving Systems with Three Variables x - 2y + z = 52y - 8z = -4

6(5+2y-z) The Approach

- Eliminate x from the EQ2 and EQ3
- Eliminate y from EQ3
- Eliminate $\ensuremath{\mathcal{Z}}$ from EQ2 and EQ1
- Eliminate y from EQ1

6(5 + 2y - z) + 5y + 9z = -4

x - 2y + z = 52y - 8z = -430 + 12y - 6z + 5y + 9z = -4

Solving Systems with Three Variables The Approach

Eliminate x from the EQ2 and EQ3

Eliminate y from EQ3

Eliminate z from EQ2 and EQ1

Eliminate y from EQ1

Solving Systems with Three Variables x - 2y + z = 52y - 8z = -417y + 3z = -34The Approach Eliminate x from the EQ2 and EQ3 Eliminate y from EQ3 Eliminate z from EQ2 and EQ1 Eliminate y from EQ1

Solving Systems with Three Variables x - 2y + z = 52y - 8z = -417(8z - 4)/2 + 3z = -34

The Approach

- Eliminate x from the EQ2 and EQ3
- Eliminate y from EQ3
- Eliminate z from EQ2 and EQ1
- Eliminate y from EQ1

Solving Systems with Three Variables x - 2y + z = 52y - 8z = -417(4z - 2) - 3z = -34The Approach Eliminate x from the EQ2 and EQ3 Eliminate y from EQ3 Eliminate z from EQ2 and EQ1 Eliminate y from EQ1

Solving Systems with Three Variables x - 2y + z = 52y - 8z = -468z - 34 - 3z = 26The Approach Eliminate x from the EQ2 and EQ3 Eliminate y from EQ3 Eliminate z from EQ2 and EQ1 Eliminate y from EQ1

Solving Systems with Three Variables x - 2y + z = 52y - 8z = -4

The Approach

- Eliminate x from the EQ2 and EQ3
- Eliminate y from EQ3
- Eliminate z from EQ2 and EQ1
- Eliminate y from EQ1

71z = 0

Solving Systems with Three Variables x - 2y + 0 = 52y - 8(0) = -4z = 0

The Approach

- Eliminate x from the EQ2 and EQ3
- Eliminate y from EQ3
- Eliminate z from EQ2 and EQ1
- Eliminate y from EQ1

Solving Systems with Three Variables x - 2y = 52y = -4

The Approach

- Eliminate x from the EQ2 and EQ3
- Eliminate y from EQ3
- Eliminate z from EQ2 and EQ1
- Eliminate y from EQ1

z = 0

Solving Systems with Three Variables x - 2(-2) = 5 y = -2z = 0

The Approach

- Eliminate x from the EQ2 and EQ3
- Eliminate y from EQ3
- Eliminate z from EQ2 and EQ1
- Eliminate y from EQ1

Solving Systems with Three Variables x = 1 y = -2z = 0

The Approach

- Eliminate x from the EQ2 and EQ3
- Eliminate y from EQ3
- Eliminate z from EQ2 and EQ1
- Eliminate y from EQ1

Solving Systems with Three Variables x = 1y = -2z = 0

The Approach

Eliminate x from the EQ2 and EQ3

Eliminate y from EQ3

Eliminate z from EQ2 and EQ1

Eliminate y from EQ1

Elimination

Back-Substitution



Verifying the Solution 1 - 2(-2) + 0 = 5 1 $2(-2) - 9(0) = -4 \sqrt{2}$ $6(1) + 5(-2) + 0 = -4^{1}$







Verifying the Solution

x - 2y + z = 52y - 8z = -46x + 5y + 9z = -4

x = 1y = -2z = 0

Verifying the Solution (1) - 2(-2) + (0) = 52(-2) - 8(0) = -46(1) + 5(-2) + 9(0) = -4

x = 1y = -2z = 0

Verifying the Solution

1 + 4 + 0 = 5-4 + 0 = -46 - 10 + 0 = -4

x = 1y = -2z = 0

Verifying the Solution

5 = 5-4 = -4-4 = -4The solution simultaneously satisfies the equations x = 1y = -2z = 0



Solving Systems as Matrices

How does this look with matrices? elimination and back-substitution same solutions

Observation. Each intermediate step of gives us a new linear system with the

Solving Systems as Matrices

How does this look with matrices? **Observation.** Each intermediate step of elimination and back-substitution gives us a new linear system with the same solutions

Can we represent these intermediate steps as operations on matrices?

Row Equivalence

2x + 3y = -6Let's look back at this... 4x - 5y = 10 $\begin{bmatrix} 2 & 3 & -6 \\ \end{bmatrix} R_2 \in R_2 - ZR_1$ $\begin{array}{c} 4 - 5 & 10 \\ -4 & -6 & +12 \\ 7 & 3 & -6 \\ 7 & 7 & 7 \\ \end{array}$ 2x+3y =-6 $-11_{7} = 22$ L M - 11 22 3-67R1FR1-3R2 $X = \bigcirc$ $\begin{bmatrix} 2 & -2 \\ 2 & -2 \end{bmatrix} \xrightarrow{P_1 \leftarrow P_1/2} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -2 \end{bmatrix}$



Elementary Row Operations

scaling multiply
replacement add a mu
another
interchange switch t

multiply a row by a number

add a multiple of one row to

switch two rows
Elementary Row Operations

- scaling multiply a row by a number add a multiple of one row to replacement another
- interchange

switch two rows

These operations don't change the solutions

Scaling Example

2x + 3y = -64x - 5y = 10

 $\begin{bmatrix} 2 & 3 & -6 \\ 4 & -5 & 10 \end{bmatrix}$

4x + 6y = -124x - 5y = 10

 $R_{16} \sim 2 \, R_{1} \, 2(2) \, 2(3) \, 2(-6)$ $\begin{bmatrix} 4 & 6 & -12 \\ 4 & -5 & 10 \end{bmatrix}$

Replacement Example

2x + 3y = -64x - 5y = 10

2x + 3y = -66x - 2y = 4

 $P_2 \leftarrow P_1 + P_2$ (2+4)(3+-5)(-6+10)



Interchange Example

2x + 3y = -64x - 5y = 10

 $\begin{vmatrix} 2 & 3 & -6 \\ 4 & -5 & 10 \end{vmatrix}$

4x - 5y = 102x + 3y = -6

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 $\begin{bmatrix} 2 & 3 & -6 \\ 4 & -5 & 10 \end{bmatrix} \xrightarrow{R_2 \leftarrow R_2 - 2R_1} \begin{bmatrix} 2 & 3 & -6 \\ 0 & -11 & 22 \end{bmatrix}$ $R_2 \leftarrow R_2/(-11) \begin{bmatrix} 2 & 3 & -6 \\ 0 & -11 & 22 \end{bmatrix}$ $\begin{bmatrix} 2 & 3 & -6 \\ 0 & 1 & -2 \end{bmatrix}$



 $\begin{bmatrix} 2 & 3 & -6 \\ 4 & -5 & 10 \end{bmatrix} \xrightarrow{R_2 \leftarrow R_2 - 2R_1} \begin{bmatrix} 2 & 3 & -6 \\ 0 & -11 & 22 \end{bmatrix}$ $R_2 \leftarrow R_2/(-11) \begin{bmatrix} 2 & 3 & -6 \\ 0 & -11 & 22 \end{bmatrix} \begin{bmatrix} 2 & 3 & -6 \\ 0 & -11 & 22 \end{bmatrix}$ $R_{1} \leftarrow R_{1} - 3R_{2}$ $\begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & -2 \end{bmatrix}$



 $\begin{bmatrix} 2 & 3 & -6 \\ 4 & -5 & 10 \end{bmatrix} \xrightarrow{R_2 \leftarrow R_2 - 2R_1} \begin{bmatrix} 2 & 3 & -6 \\ 0 & -11 & 22 \end{bmatrix}$ $R_2 \leftarrow R_2/(-11) \begin{bmatrix} 2 & 3 & -6 \\ 0 & -11 & 22 \end{bmatrix} \begin{bmatrix} 2 & 3 & -6 \\ 0 & -11 & 22 \end{bmatrix}$ $\begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & -2 \end{bmatrix}$ $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -2 \end{bmatrix} \times = 0$



 $\begin{bmatrix} 2 & 3 & -6 \\ 4 & -5 & 10 \end{bmatrix}$

 $R_2 \leftarrow R_2 - 2R_1$ $R_2 \leftarrow R_2/(-11)$ $R_1 \leftarrow R_1 - 3R_2$ $R_1 \leftarrow R_1/2$

$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 2 \end{bmatrix}$

 $R_{2} \leftarrow R_{1} \leftarrow R_{1$

 $\begin{bmatrix} 2 & 3 & -6 \\ 4 & -5 & 10 \end{bmatrix}$

$$- \frac{R_2 - 2R_1}{R_2 - R_2 - R_1 - 3R_2}$$
$$- \frac{R_1 - 3R_2}{R_1 - R_1 - 2R_2}$$

elimination substitution

$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 2 \end{bmatrix}$

Row Equivalence

one can be transformed into the other by a sequence of row operations

$$\begin{bmatrix} 2 & 3 & -6 \\ 4 & -5 & 10 \end{bmatrix}$$

Definition. Two matrices are row equivalent if

Row Equivalence

one can be transformed into the other by a sequence of row operations

$\begin{vmatrix} 2 & 3 & -6 \\ 4 & -5 & 10 \end{vmatrix}$

Definition. Two matrices are row equivalent if

We can compute solutions by sequence of row operations

Question

Write a sequence of row operations that on the right.

$\begin{bmatrix} 1 & 2 & 4 \\ 1 & 6 & 2 \\ 1 & 4 & 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 6 & 2 \\ 0 & -4 & 2 \\ 0 & -2 & 3 \end{bmatrix}$

converts the matrix on the left to the matrix







first, a demo (SymPy)

of linear equations

Observation. Solutions look like simple systems

of linear equations

solutions of some systems

Observation. Solutions look like simple systems said another way: it's easy to "read off" the

Observation. Solutions of linear equations

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solutions of some systems

<u>Solving a system of linear equations</u> is the same as <u>row reducing its augmented matrix</u> to a matrix which "represents a solution".

Observation. Solutions look like simple systems

Observation. Solutions of linear equations

said another way: it's easy to "read off" the
solutions of some systems

<u>Solving a system of linear equations</u> is the same as <u>row reducing its augmented matrix</u> to a matrix which "represents a solution".

What matrices "represent solutions"?

Observation. Solutions look like simple systems

Motivating Questions

What matrices "represent solutions"? (which have solutions that are easy to "read off"?)

How does the number of solutions affect the shape of these matrix?

How do we use row operations to get to those matrices?

Motivating Questions Let's consider these first

- What matrices "represent solutions"? (which have solutions that are easy to "read off"?)
- How does the number of solutions affect the shape of these matrix?

How do we use row operations to get to those matrices?



$\begin{bmatrix} 2 & -3 & 5 & 11 \\ 2 & -1 & 13 & 39 \\ 1 & -1 & 5 & 14 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 3 \end{bmatrix}$



x = 1y = 2z = 3

$\begin{bmatrix} 2 & -3 & 5 & 11 \\ 2 & -1 & 13 & 39 \\ 1 & -1 & 5 & 14 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 3 \end{bmatrix}$



z = 3

x = 1 y = 2Like all the examples we've seen for so far

The Identity Matrix

$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

The Identity Matrix

$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 \end{bmatrix}$ 1s along the diagonal 0s elsewhere 0 0 1 \\ 0 & 1 \end{bmatrix}



coefficient matrix



a system of linear equations whose coefficient matrix is the identity matrix represents a unique solution

$\begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 3 \end{bmatrix}$







 $\begin{bmatrix}
 1 & 1 & 1 & 1 \\
 1 & 1 & 1 & 2 \\
 1 & 2 & 3 & 4
 \end{bmatrix}$

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$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 2 \\ 1 & 2 & 3 & 4 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 3 & 4 \\ 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$

two parallel planes

$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 2 \\ 1 & 2 & 3 & 4 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 3 & 4 \\ 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$

two parallel lanes

$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 2 \\ 1 & 2 & 3 & 4 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 3 & 4 \\ 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$ row representing 0 = 1

a system with no solutions can be reduced to a matrix with the row 00...01

$\begin{bmatrix} 1 & 2 & 3 & 4 \\ 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$ row representing 0 = 1

Infinite Solution Case



Example

$\begin{bmatrix} 2 & 4 & 2 & 14 \\ 1 & 7 & 1 & 12 \end{bmatrix}$




$\begin{bmatrix} 2 & 4 & 2 & 14 \\ 1 & 7 & 1 & 12 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 & 2 \\ 0 & 1 & 0 & 1 \end{bmatrix}$

$\begin{bmatrix} 2 & 4 & 2 & 14 \\ 1 & 7 & 1 & 12 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 & 2 \\ 0 & 1 & 0 & 1 \end{bmatrix}$ $x_1 + x_3 = 2$



 $x_2 = 1$

a system with infinity solutions can be

 $\begin{bmatrix} 2 & 4 & 2 & 14 \\ 1 & 7 & 1 & 12 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 & 2 \\ 0 & 1 & 0 & 1 \end{bmatrix}$ $x_1 + x_3 = 2$ $x_2 = 1$ reduced to a system which leaves a variable <u>unrestricted</u>





$x_1 + x_3 = 2$ $x_{2} = 1$

it doesn't matter what x_3 is if we want to satisfy this system of equations

 $x_1 = 2$ $x_2 = 1$ $x_3 = 0$





$x_1 + x_3 = 2$ $x_{2} = 1$

it doesn't matter what x_3 is if we want to satisfy this system of equations

 $x_1 = 1.5$ $x_2 = 1$ $x_3 = 0.5$





$x_1 + x_3 = 2$ $x_{2} = 1$

it doesn't matter what x_3 is if we want to satisfy this system of equations

 $x_1 = 20$ $x_2 = 1$ $x_3 = -18$







$x_1 + x_3 = 2$ $x_{2} = 1$

it doesn't matter what x_3 is if we want to satisfy this system of equations

 $x_1 = 2 - x_3$ x_3 is free







$x_1 + x_3 = 2$ $x_{2} = 1$

it doesn't matter what x_3 is if we want to satisfy this system of equations

 $x_1 = 2 - x_3$ x_3 is free

general form



In Sum

reduces to a system with the none equation 0 = 1reduces to a system whose coefficient one matrix is the identity matrix

infinity

reduces to a system which leaves a variable unrestricted

In Sum

none equation 0 = 1

one

infinity variable unrestricted

reduces to a system with the

- reduces to a system whose coefficient matrix is the identity matrix
- reduces to a system which leaves a
- Ideally, we want one form that handles all three cases

Motivating Questions

solutions that are easy to read off?)

How does the number of solutions affect the shape of these matrix?

How do we use row operations to get to those matrices?

What matrices represent solutions? (which have

Motivating Questions

solutions that are easy to read off?)

How does the number of solutions affect the shape of these matrix?

How do we use row operations to get to those matrices?

What matrices represent solutions? (which have

this is Gaussian elimination (next lecture)

Echelon Form

The Picture (and a bit of history)

TROOPS

V O O O SHIPS

https://commons.wikimedia.org/wiki/File:Echelon_1_(PSF).png



Echelon Form (Pictorially)



Leading Entries

Definition. the leading entry of a row is the first nonzero value



Echelon Form

Echelon Form Definition. A matrix is in echelon form if

Echelon Form

- Definition. A matrix is in echelon form if
- 1. The leading entry of each row appears to the right of the leading entry above it

Echelon Form

- Definition. A matrix is in echelon form if
- 1. The leading entry of each row appears to the right of the leading entry above it
- 2. Every all-zeros row appears below any nonzero rows

Echelon Form (Pictorially)



Echelon Form (Pictorially)



next leading entry to the right



Question

Is the identity matrix in echelon form?

Answer: Yes

$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

the leading entries of each row appears to the right of the leading entry above it

it has no all-zero rows

Question

Is this matrix in echelon form?

$\begin{bmatrix} 2 & 3 & -8 \\ 0 & 1 & 2 \\ 0 & 2 & 0 \end{bmatrix}$

Answer: No

$\begin{bmatrix} 2 & 3 & -8 \\ 0 & 1 & 2 \\ 0 & 2 & 0 \end{bmatrix}$ The leading entry of the least row is not to the right of the leading entry of the second row

What's special about Echelon forms?

Theorem. Let A be the augmented matrix of an echelon form then B has the row

<u>inconsistent</u> linear system. If $A \sim B$ and B is in

$\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$

Example

The Problem with Echelon Forms

If our system *is* consistent, we can't get a solution quite yet.

The Problem with Echelon Forms

If our system *is* consistent, we can't get a solution quite yet.

We need to simplify our matrix a bit more until it "represents" a solution



Reduced Echelon Form

Row-Reduced Echelon Form (RREF)

- Definition. A matrix is in (row-)reduced echelon form if
- 1. The leading entry of each row appears to the right of the leading entry above it
- 2. Every all-zeros row appears below any non-zero rows
- 3. The leading entries of non-zero rows are 1
- 4. the leading entries are the only non-zero entries of their columns

Reduced Echelon Form (Pictorially)

 $\begin{bmatrix} 0 & 1 & * & 0 & 0 & 0 & * & * & 0 & * \\ 0 & 0 & 0 & 1 & 0 & 0 & * & * & 0 & * \\ 0 & 0 & 0 & 0 & 1 & 0 & * & * & 0 & * \\ 0 & 0 & 0 & 0 & 0 & 1 & * & * & 0 & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$

Reduced Echelon Form (Pictorially)



leading entries are 1



Reduced Echelon Form (A Simple Example)





Reduced Echelon Form (A Simple Example)




What's special about RREF?

Every leading variable can be written in terms of every non-leading variable.

0	1	*	0	0	0	*	*	0	*
0	0	0	1	0	0	*	*	0	*
0	0	0	0	1	0	*	*	0	*
0	0	0	0	0	1	*	*	0	*
0	0	0	0	0	0	0	0	1	*
0	0	0	0	0	0	0	0	0	0

 $\begin{bmatrix} 1 & 0 & 1 & 2 \\ 0 & 1 & 0 & 1 \end{bmatrix}$

The Fundamental Points

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system of linear equations from its RREF

Point 1. we can "read off" the solutions of a

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Point 2. *every* matrix is row equivalent to a <u>unique</u> matrix in reduced echelon form



1. Write your system as an augmented matrix



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2. Find the RREF of that matrix



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3. Read off the solution from the RREF



1. Write your system as an augmented matrix

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3. Read off the solution from the RREF Our next topic



General-Form Solutions

Definition. a *pivot position* (*i*,*j*) in a matrix is the

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1 0 1 2 0 1 0 1 0 1 0 1

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x_3 is free

Solutions of Reduced Echelon Forms

the row of a <u>pivot position in row i</u> describes the <u>value of x_i in a solution</u> to the system, in terms of the free variables

$\begin{bmatrix} 1 & 0 & 1 & 2 \\ 0 & 1 & 0 & 1 \end{bmatrix}$

General Form Solution 1 0 1 2 0 1 0 1

for each pivot position (i,j), isolate x_i in the equation in row j

if x, does not have a pivot position, write

 $x_1 = 2 - x_3$ $x_2 = 1$ x_3 is free

x_i is free

Example

$\begin{bmatrix} 1 & 2 & 0 & -2 & 4 \\ 0 & 0 & 1 & 3 & 5 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$





the goal of <u>back-substitution</u> is to reduce an echelon form matrix to a **reduced** echelon form



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the goal of <u>Gaussian elimination</u> is to reduce an **augmented** matrix to a **reduced** echelon form



reduced echelon forms describe solutions to linear equations

the goal of <u>back-substitution</u> is to reduce an echelon form matrix to a reduced echelon form

the goal of Gaussian elimination is to reduce an augmented matrix to a reduced echelon form



Question

write down a solution in general form for this reduced echelon form matrix

$\begin{bmatrix} 1 & 0 & 0 & 3 & 1 \\ 0 & 0 & 1 & 2 & 4 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$



$\begin{bmatrix} 1 & 0 & 0 & 3 & 1 \\ 0 & 0 & 1 & 2 & 4 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$



demo (a.rref())