Linear Models

Geometric Algorithms Lecture 24

Practice Problem

$$B = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 1 \\ 1 & 0 & -1 \end{bmatrix} \qquad \mathbf{b} = \begin{bmatrix} 3 \\ 1 \\ -4 \end{bmatrix}$$

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Find the projection of **b** onto
$$Col(A) = Col(B)$$

$$\frac{hint!}{A_2 - A_1 = A_3}$$

$$B^TB = \begin{bmatrix} 1 & 0 & 1 \\ 2 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 6 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 2 \\ 2 & 5 \end{bmatrix} \begin{bmatrix} 5 & -2 \\ 6 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 1 \\ 1 & 0 & -1 \end{bmatrix}$$

$$\mathbf{b} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$$

Answer
$$A = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 1 \\ 1 & 0 & -1 \end{bmatrix}$$

$$\hat{x} = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 1 \\ 1 & 0 & -1 \end{bmatrix}$$

$$\hat{x} = (B^T B)^T B^T b = -\frac{1}{6} \begin{bmatrix} 5-2 \\ -2 & 2 \end{bmatrix} \begin{bmatrix} -1 \\ 7 \end{bmatrix} = -\frac{1}{6} \begin{bmatrix} -19 \\ 16 \end{bmatrix}$$

$$proj_{GICA)} \vec{b} = \vec{B} \cdot \vec{X} = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 1 & 0 \end{bmatrix} (1) \begin{bmatrix} -19 \\ 16 \end{bmatrix} = \begin{bmatrix} -19+32 \\ 16 \\ -19 \end{bmatrix} (16) = 16 \begin{bmatrix} 13 \\ 16 \\ 19 \end{bmatrix}$$

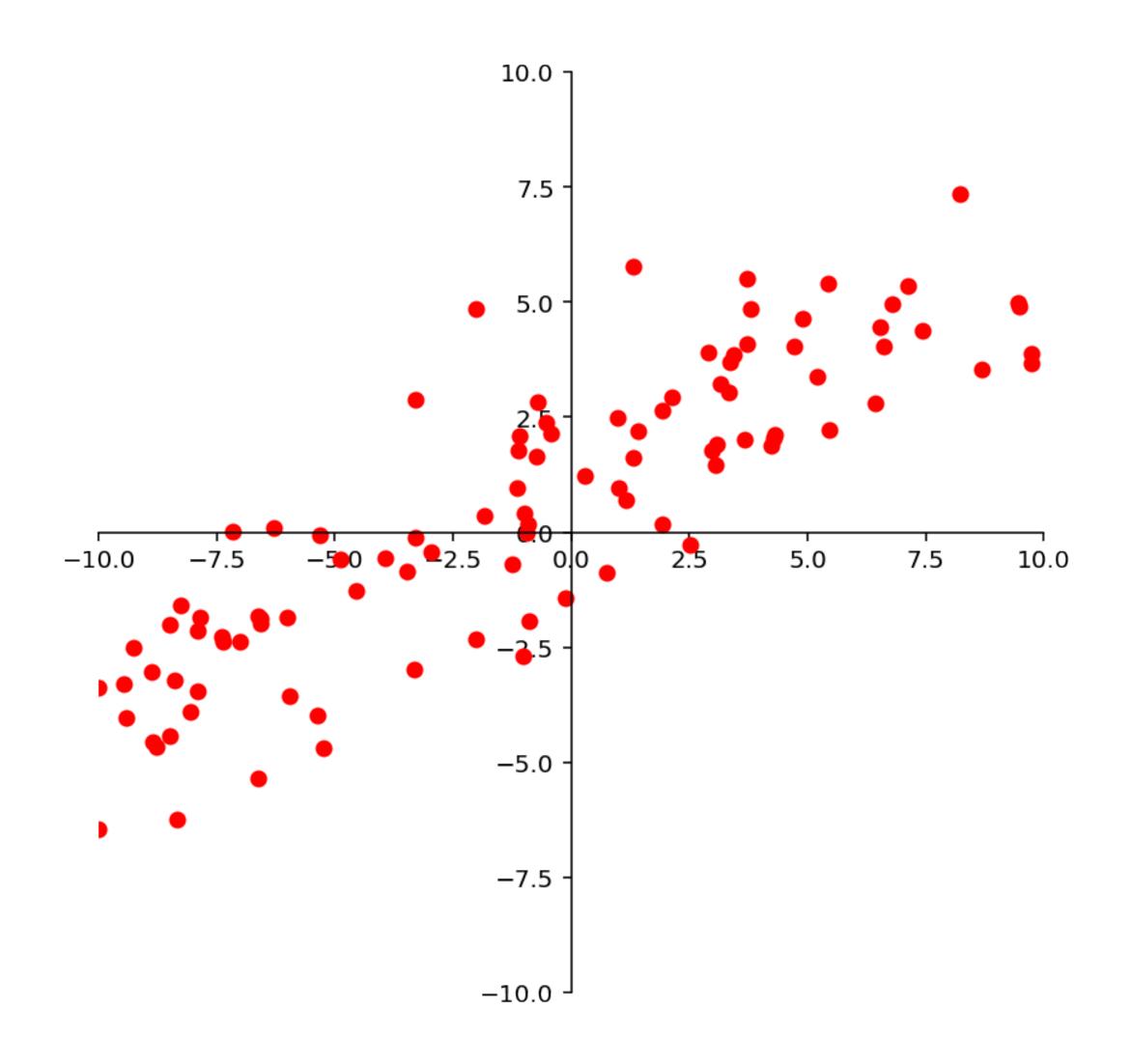
Objectives

- 1. Use the least square method to build linear models of noisy data.
- 2. Show how we can use linear algebraic methods to model with non-linear models.

Keywords

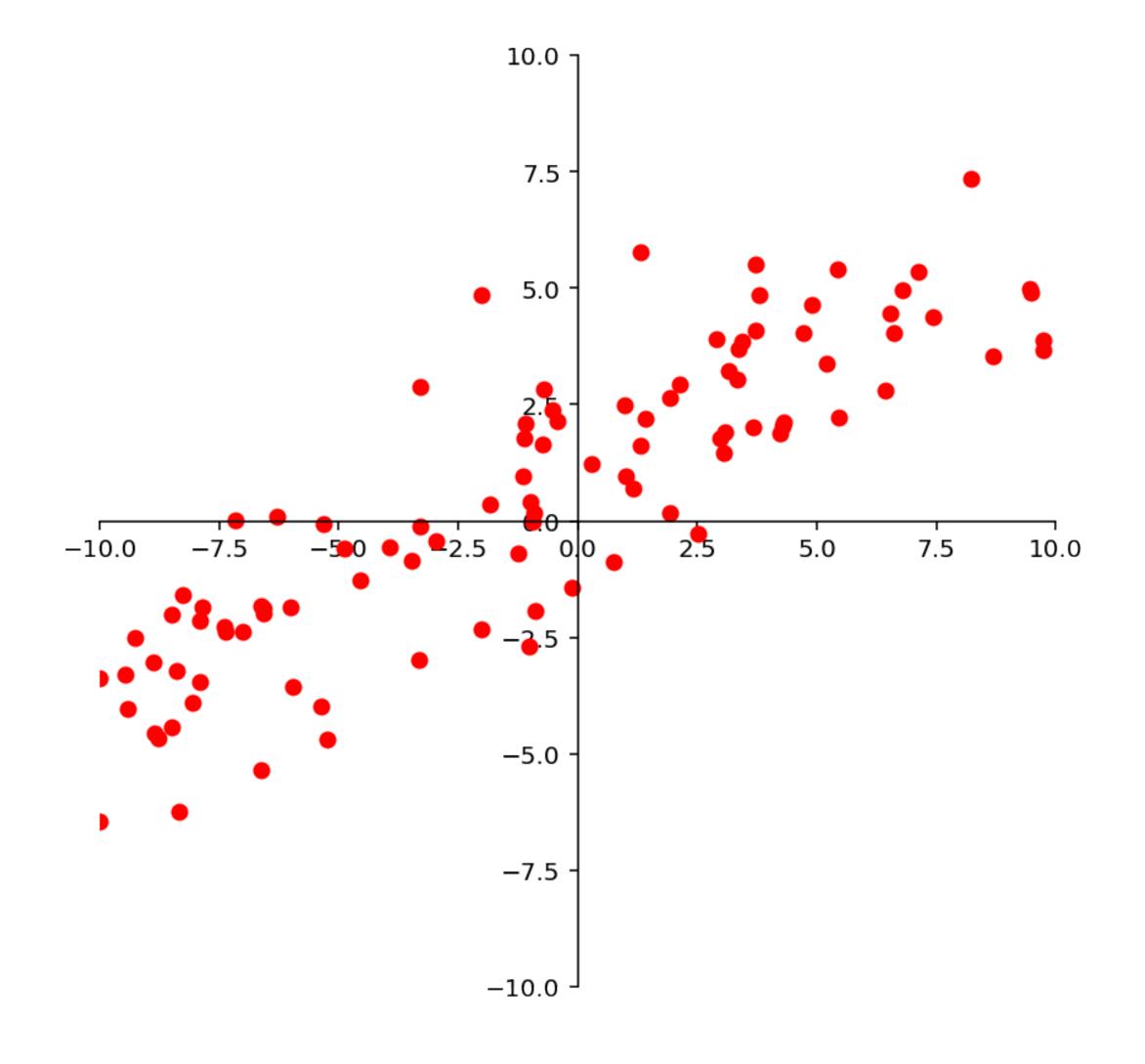
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line of best fit
independent/dependent variables
residuals
prediction
simple least squares regression
multiple regression
polynomial regression
models
model fitting
model parameters
design matrices
```

Warm-up: Line of Best Fit



You're given a set of points in \mathbb{R}^2

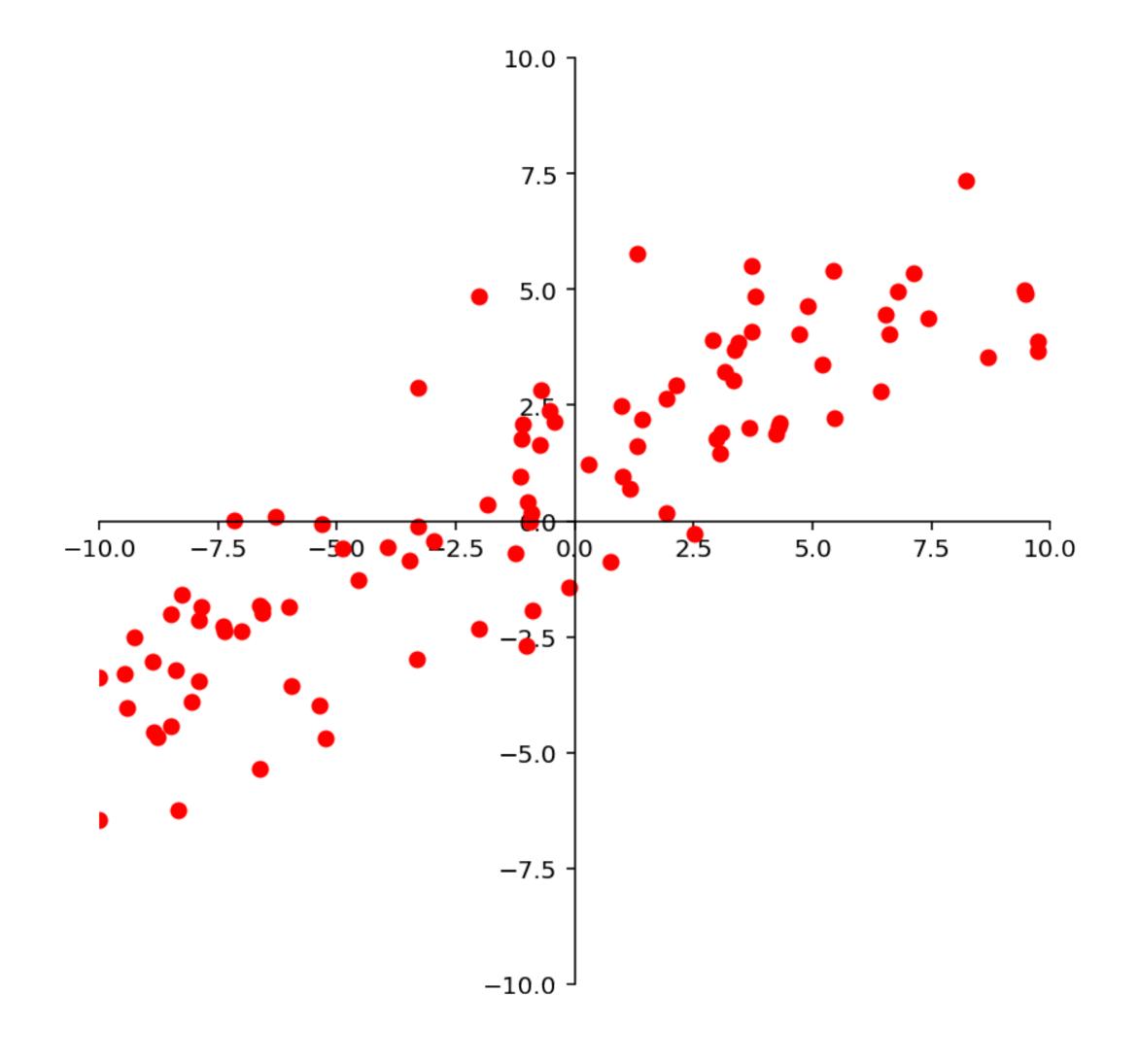
$$\{(x_1, y_1), \ldots, (x_k, y_k)\}$$



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Example. You collect (height, weight) data for a population.

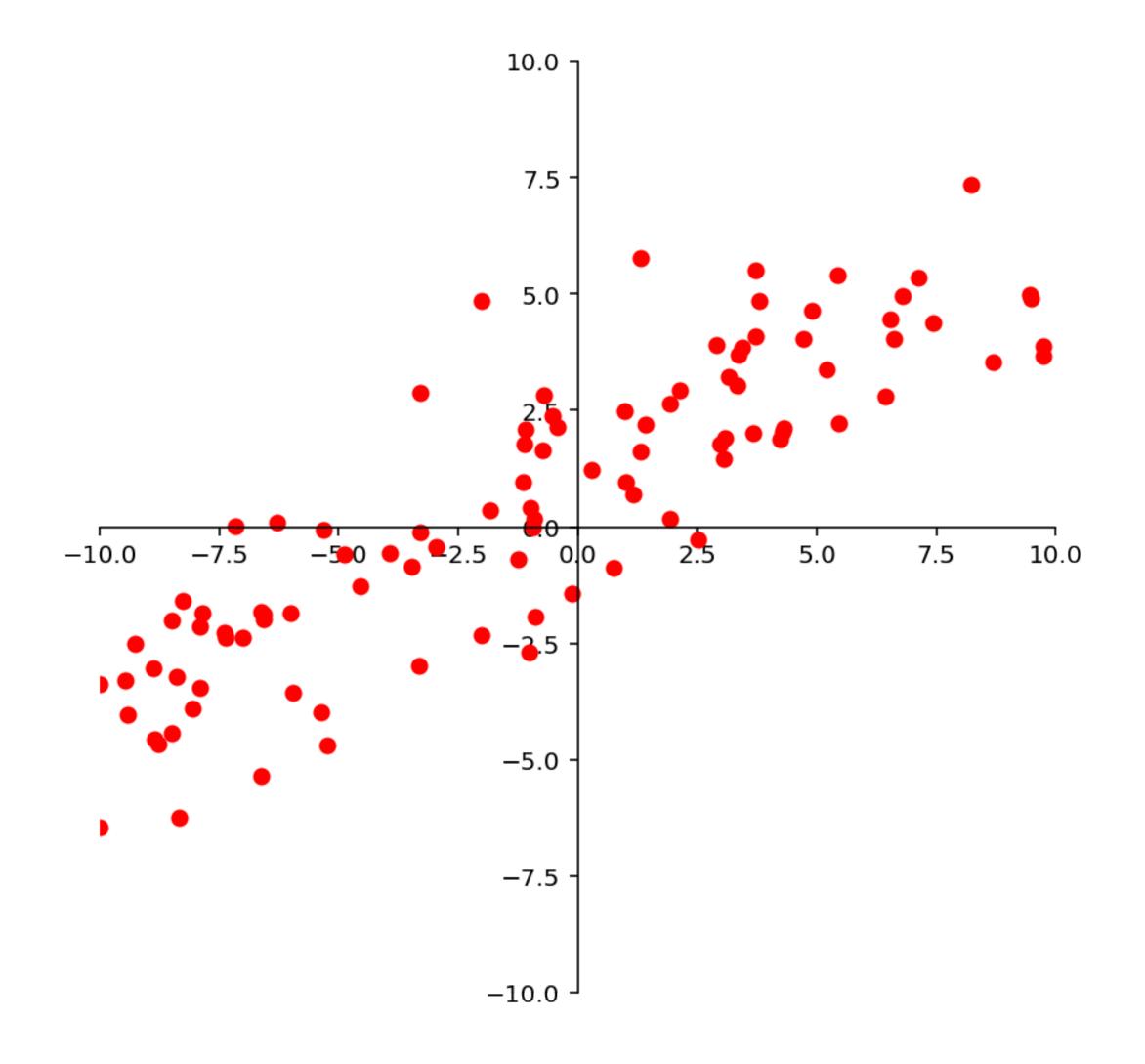


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You notice they *kind* of trend as a line.

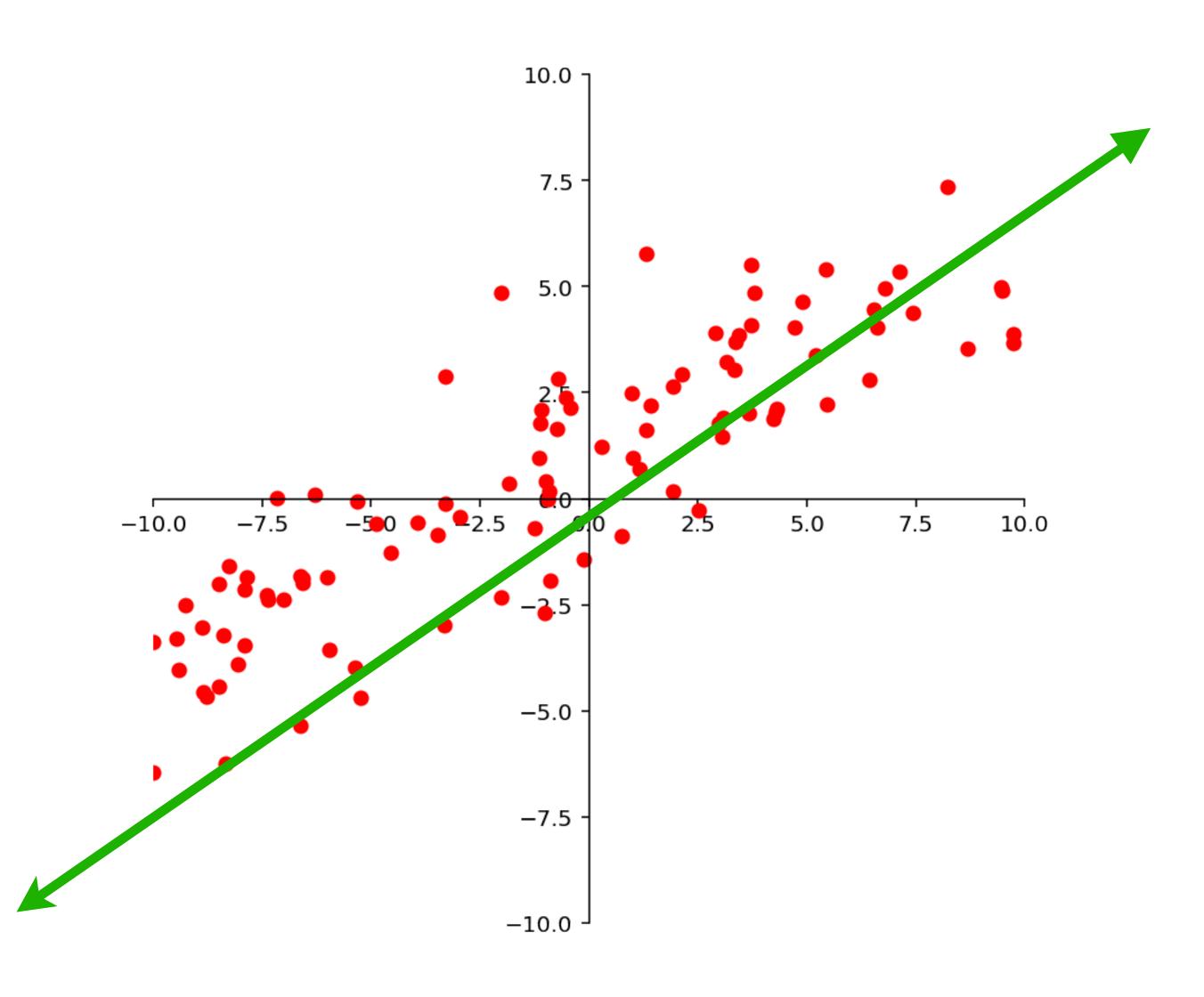


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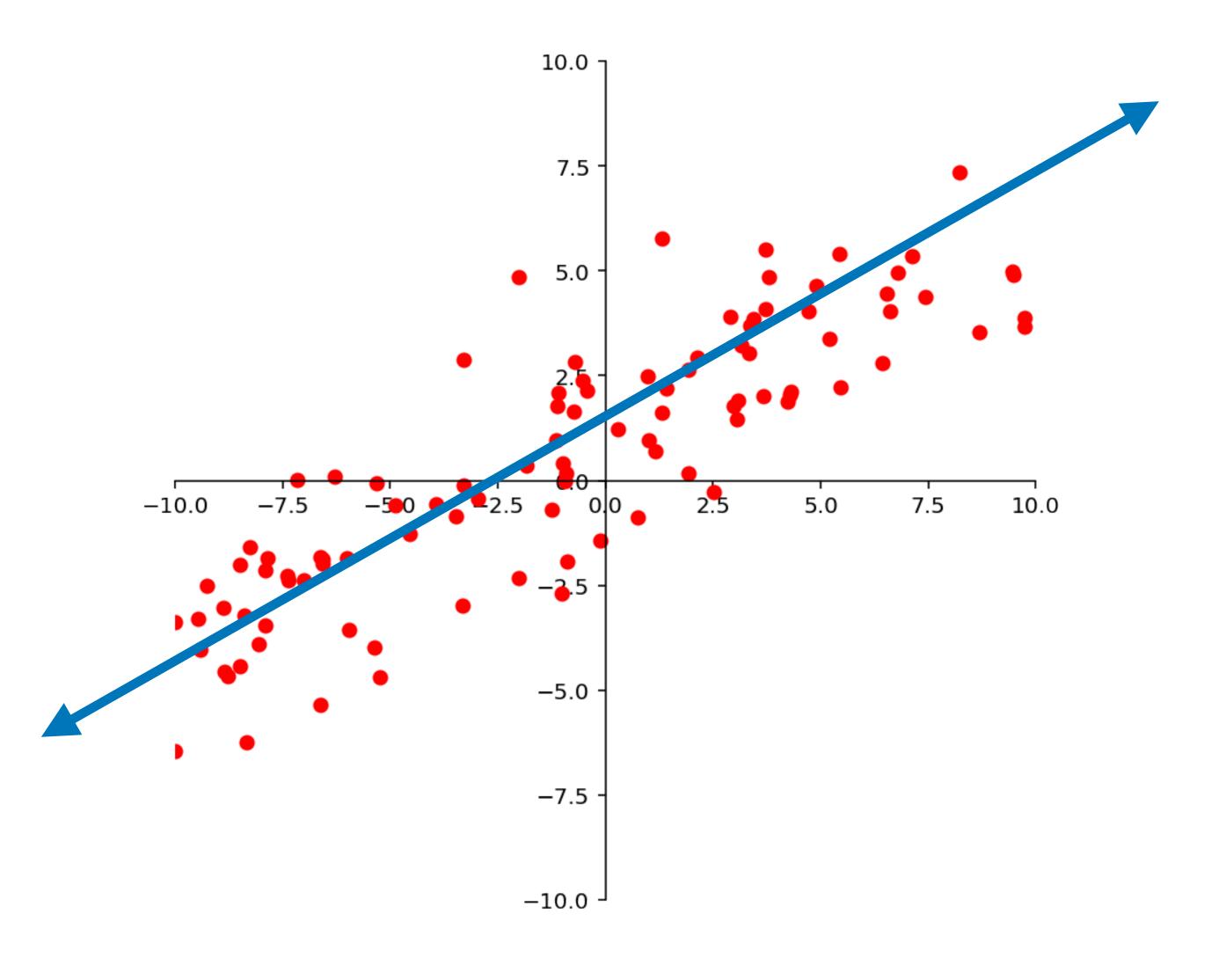


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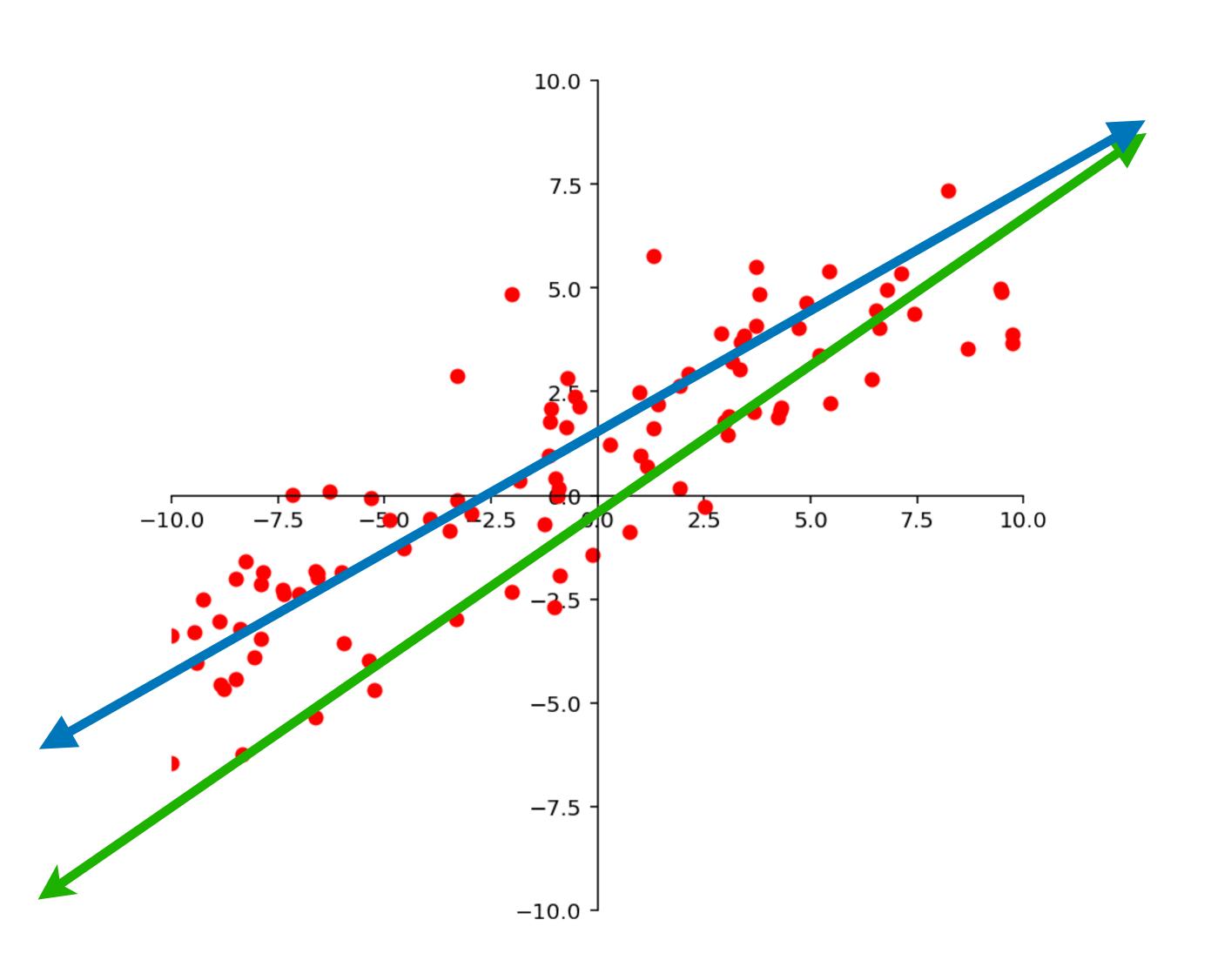
Example. You collect (height, weight) data for a population.

You notice they *kind* of trend as a line.



Question. Which line "best" describes the trend of the dataset?

Which one *best models* the dataset?



1. What is a model?

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We'll come back to this...

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2. What does "best" mean?

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We'll come back to this...

2. What does "best" mean?

This is a make-or-break question.

Least Squares Simple Linear Regression

Problem. Given a set of points $\{(x_1,y_1),...,(x_n,y_n)\}$, find the line

$$f(x) = \beta_0 + \beta_1 x$$

which <u>minimizes</u>

$$\sum_{i=1}^{n} (y_i - f(x_i))^2$$

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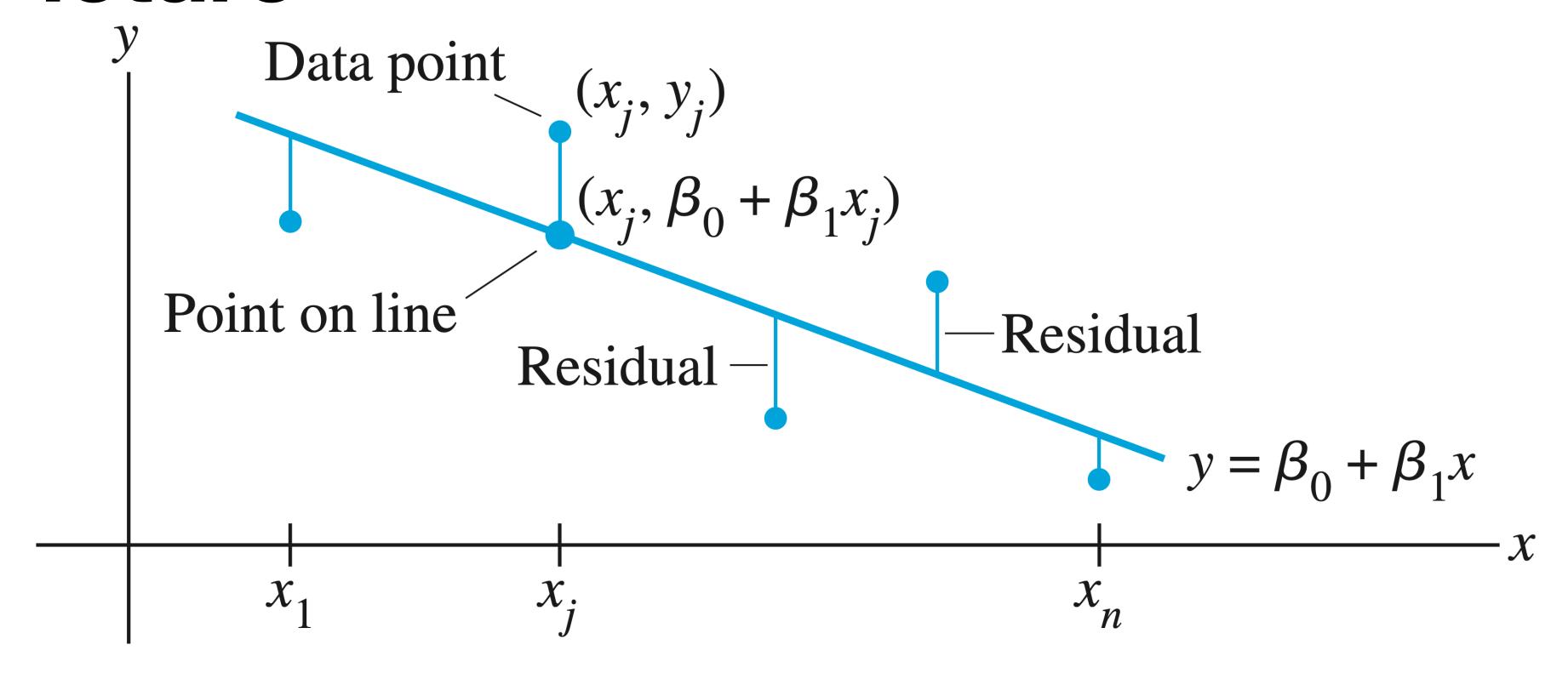
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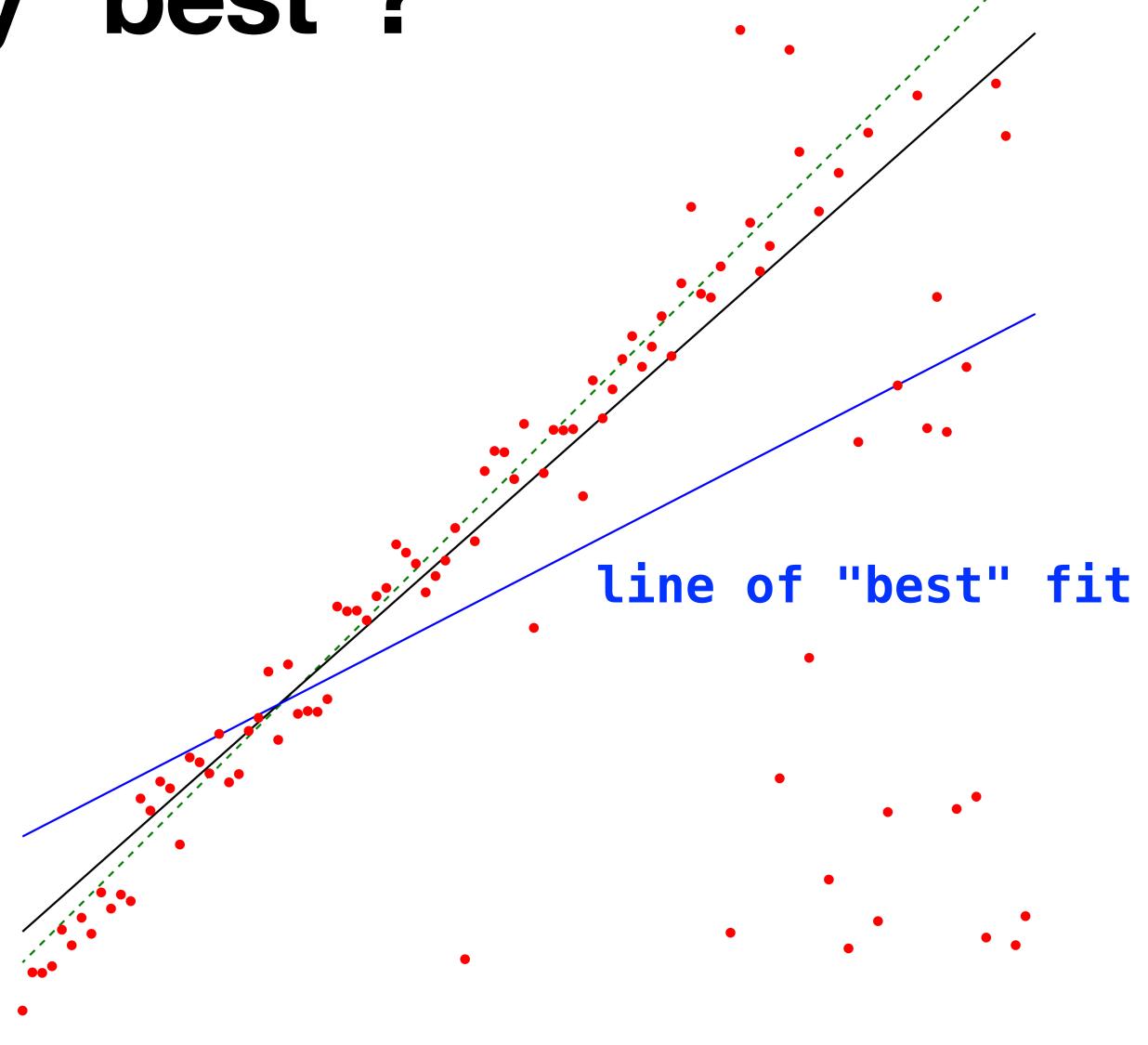
$$\sum_{i=1}^{n} (y_i - f(x_i))^2$$

The "best" line minimizes the sum of squares of differences.

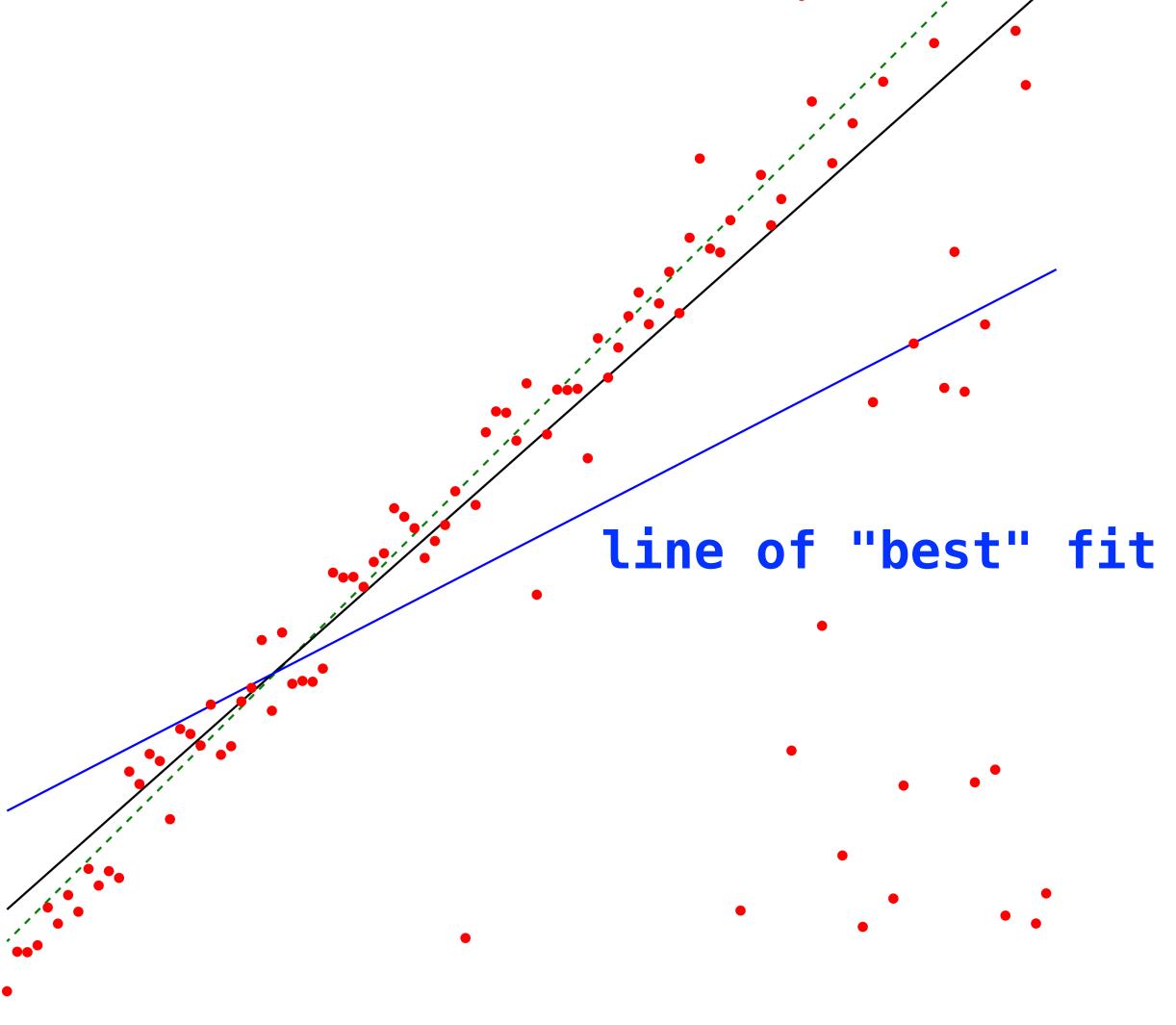
The Picture



We want to find the line which makes the sum of these differences as small as possible.

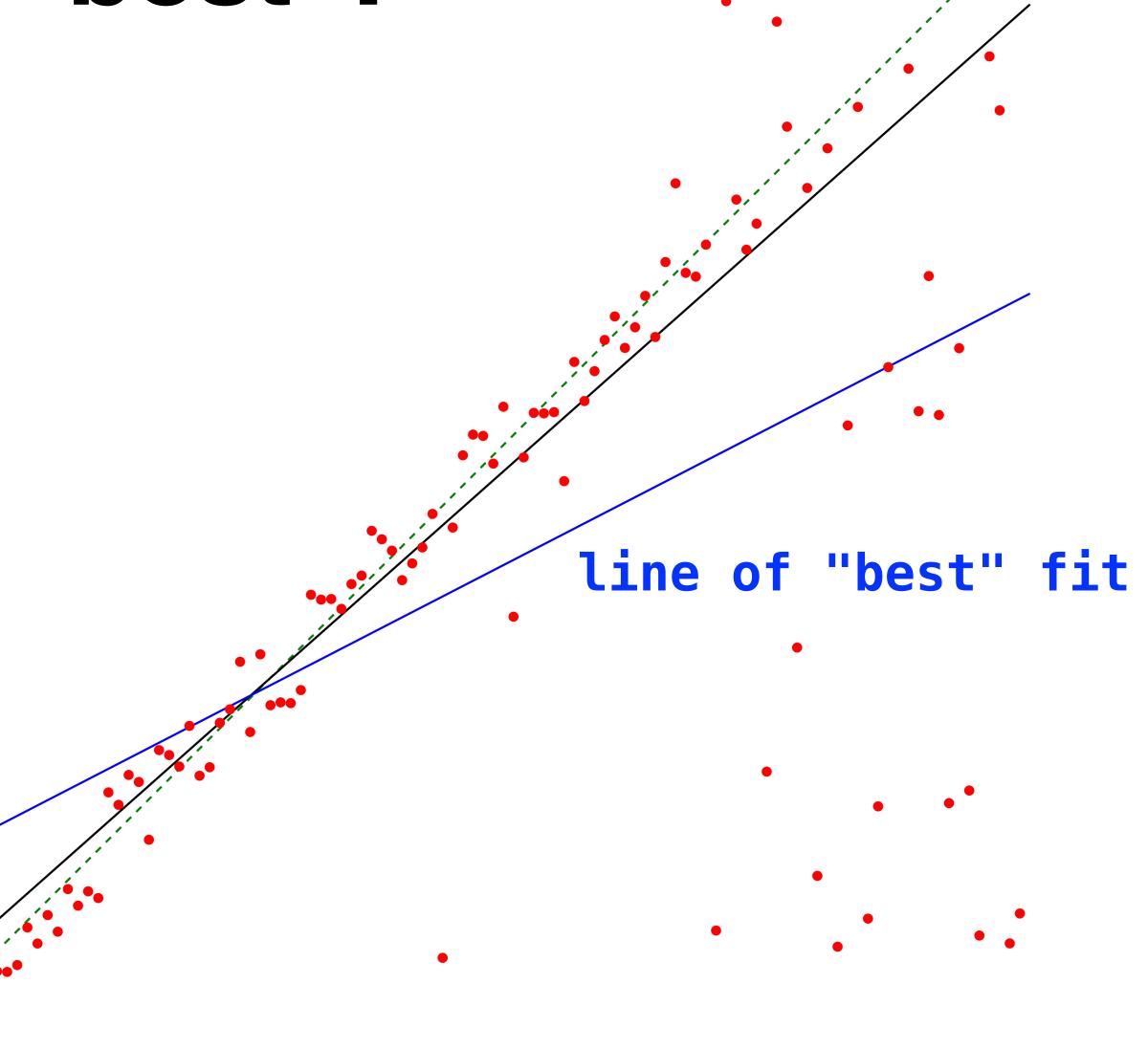


Who's to say...



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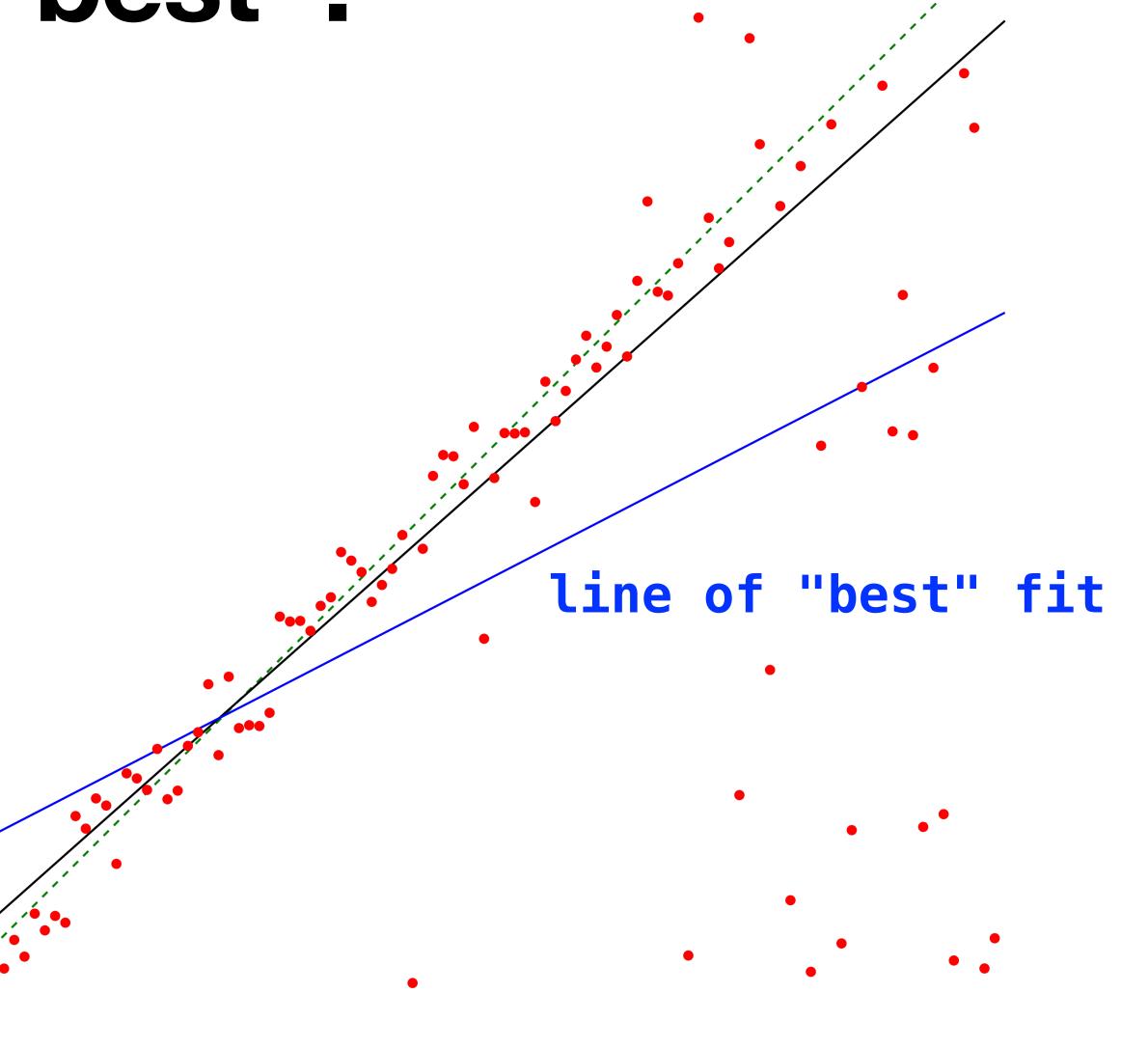
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Who's to say...

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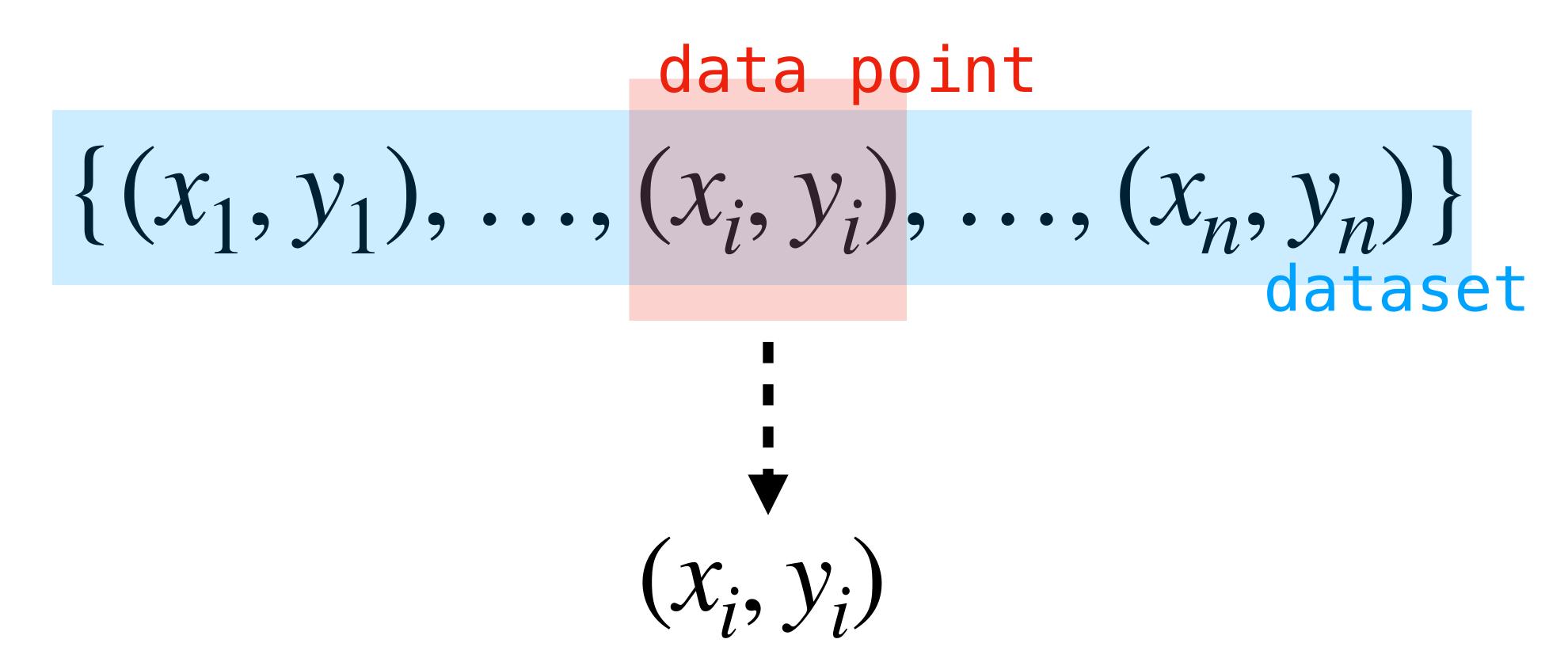
The point. We fix our notion of "best" first, and then we do calculations and derivations from there.

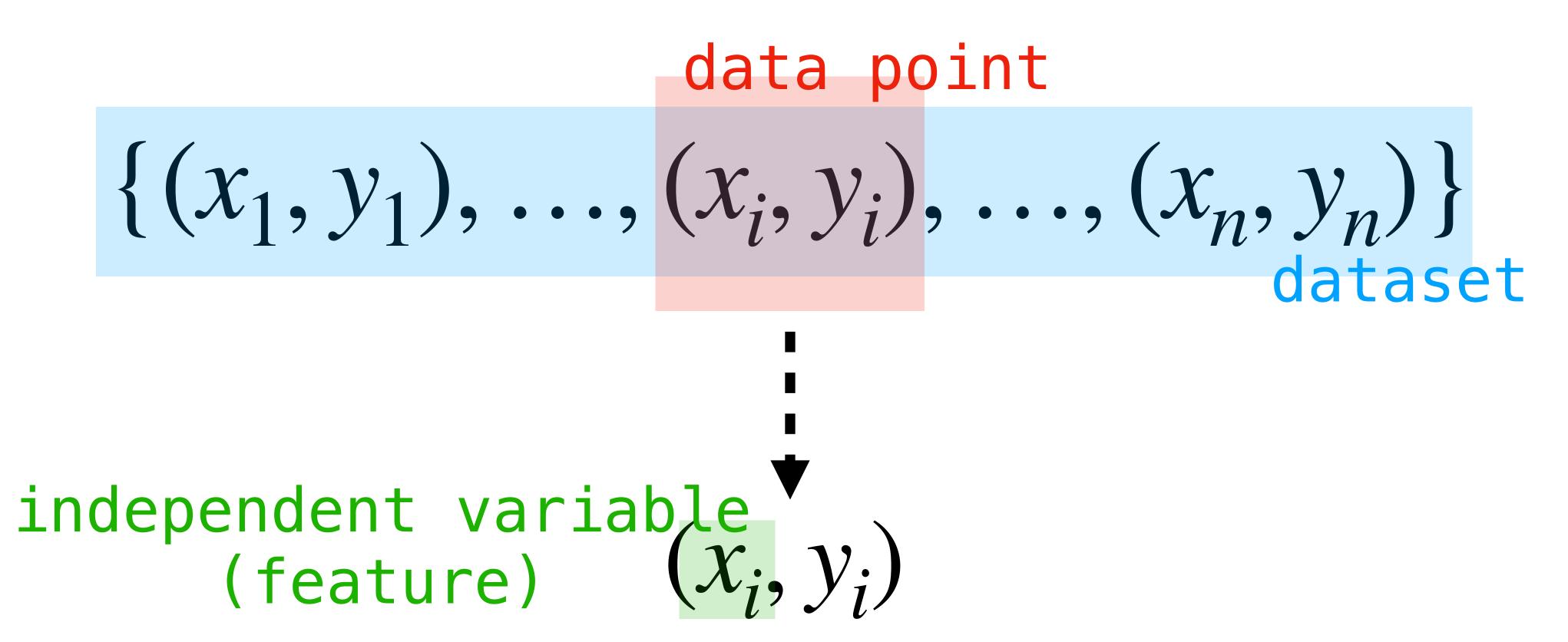


$$\{(x_1,y_1),\ldots,(x_i,y_i),\ldots,(x_n,y_n)\}$$

$$\{(x_1, y_1), \dots, (x_i, y_i), \dots, (x_n, y_n)\}\$$
dataset

$$\{(x_1,y_1),\ldots,(x_i,y_i),\ldots,(x_n,y_n)\}$$
data point
$$\{(x_1,y_1),\ldots,(x_i,y_i),\ldots,(x_n,y_n)\}$$
dataset





```
data point
     \{(x_1,y_1),\ldots,(x_i,y_i),\ldots,(x_n,y_n)\}
                                                dataset
independent variable (feature) (x_i, y_i) dependent variable (1961)
                                       (label)
```

Terminology: Models

$$f(x) = \beta_0 + \beta_1 x$$

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Terminology: Models

model parameters/ regression coefficients

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Terminology: Least-Squares Error

$$\sum_{i=1}^{n} (y_i - f(x_i))^2$$

Terminology: Least-Squares Error

$$\sum_{i=1}^{n} (y_i - f(x_i))^2$$

$$i=1$$

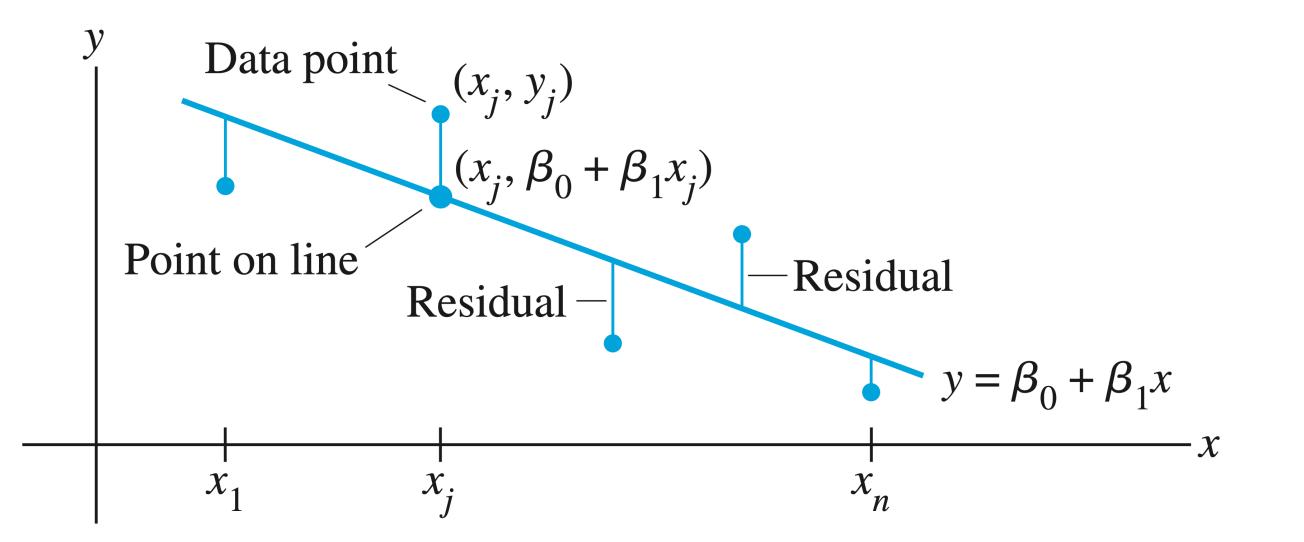
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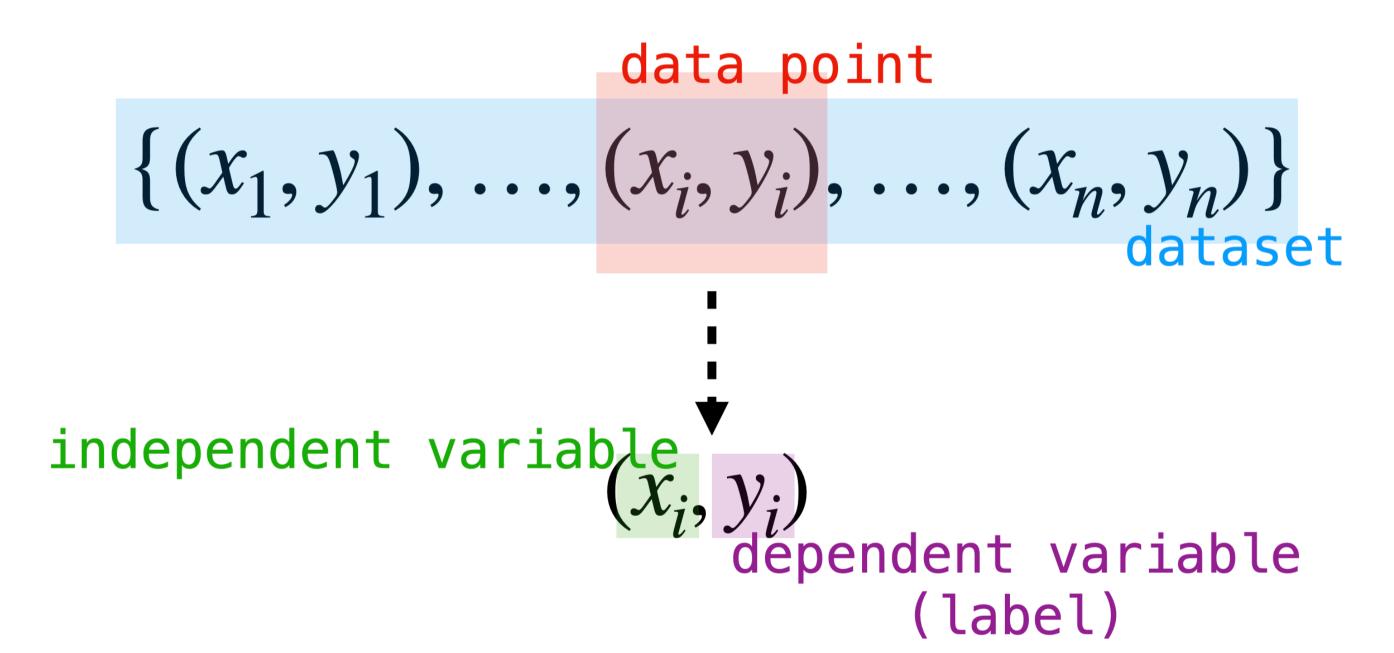
$$\sum_{i=1}^{n} \frac{\text{observation}}{y_i - f(x_i)^2}$$

Terminology: Least-Squares Error

$$\sum_{i=1}^{n} \frac{\text{observation}}{(y_i - f(x_i))^2}$$

Terminology





model parameters/
regression coefficients
$$f(x) = \beta_0 + \beta_1 x$$
model

$$\sum_{i=1}^{n} \frac{\text{observation}}{(y_i - f(x_i))^2}$$

$$\sum_{i=1}^{n} \frac{y_i - f(x_i)^2}{\text{prediction}}$$

$$\beta_{1} = \frac{n \sum_{i=1}^{n} x_{i} y_{i} - \left(\sum_{i=1}^{n} x_{i}\right) \left(\sum_{i=1}^{n} y_{i}\right)}{n \sum_{i=1}^{n} x_{i}^{2} - \left(\sum_{i=1}^{n} x_{i}\right)^{2}} \qquad \beta_{0} = \frac{\sum_{i=1}^{n} y_{i} - \beta_{1} \sum_{i=1}^{n} x_{i}}{n}$$

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Solution (First attempt). Use these equations...

Don't memorize these.

$$\beta_{1} = \frac{\sum_{i=1}^{n} x_{i} \sum_{i=1}^{n} x_{i}}{\sum_{i=1}^{n} x_{i}} \left(\sum_{i=1}^{n} x_{i} \right) \left(\sum_{i=1}$$

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Solution (First attempt). Use these equations...

$$\sum_{i=1}^{n} (y_i - f(x_i))^2$$

$$||A\mathbf{x} - \mathbf{b}||^2 = \sum_{i=1}^n ((A\mathbf{x})_i - \mathbf{b}_i)^2$$

$$\sum_{i=1}^{n} (y_i - f(x_i))^2$$

minimize for least-squares line

$$||A\mathbf{x} - \mathbf{b}||^2 = \sum_{i=1}^n ((A\mathbf{x})_i - \mathbf{b}_i)^2$$

minimize for least-squares method

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These expressions look very similar.

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minimize for least-squares line minimize for least-squares method

These expressions look very similar.

Can we <u>design</u> a matrix where finding a least squares solution gives us a least squares line?

$$\beta_0 + \beta_1 x_1 = y_1$$

$$\beta_0 + \beta_1 x_2 = y_2$$

$$\vdots$$

$$\beta_0 + \beta_1 x_n = y_n$$

In the "ideal" world, we could find parameters β_0 and β_1 such that all of these equations hold.

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This is a linear system in the variables eta_0 and eta_1

$$\begin{bmatrix} 1 & x_1 \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_n \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

In the "ideal" world, this matrix equation has a solution.

$$\begin{bmatrix} 1 & x_1 \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_n \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

In the "ideal" world, this matrix equation has a solution.

In reality this system is unlikely to have a solution, but maybe we can find an approximate solution.

$$\begin{bmatrix} 1 & x_1 \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_n \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

A Least Squares Problem

$$\begin{bmatrix} 1 & X \\ 1 & x_1 \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_n \end{bmatrix} \begin{bmatrix} \vec{\beta} \\ \beta_0 \\ \beta_1 \end{bmatrix} = \begin{bmatrix} \mathbf{y} \\ y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

$$\|X\vec{\beta} - \mathbf{y}\|^2 = \sum_{i=1}^n ((\beta_0 + \beta_1 x_i) - y_i)^2$$

A Least Squares Problem
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The sum of squares of residuals is the squared distances between $X\beta$ and y.

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The sum of squares of residuals is the squared distances between $X\beta$ and y.

Least <u>squares</u> <u>solutions</u> to this system give us parameters for least squares lines.

Theorem. The set of least-squares solutions of $A\mathbf{x} = \mathbf{b}$ is the same as the set of solutions to

$$A^T A \mathbf{x} = A^T \mathbf{b}$$

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In particular, this set of solutions is nonempty

Theorem. The set of least-squares solutions of $A\mathbf{x} = \mathbf{b}$ is the same as the set of solutions to

$$A^T A \mathbf{x} = A^T \mathbf{b}$$

In particular, this set of solutions is nonempty

(We just showed that if $\hat{\mathbf{x}}$ is a least squares solution then $A^T A \hat{\mathbf{x}} = A^T \mathbf{b}$)

Recall: Unique Least Squares Solutions

$$\hat{\mathbf{x}} = (A^T A)^{-1} A^T \mathbf{b}$$

If A has linearly independent columns, then its unique least squares solution is defined as above.

$$\begin{bmatrix} 1 & x_1 \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_n \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

Just for Fun
$$\frac{\begin{bmatrix} \beta_{\sigma} \\ \beta_{i} \end{bmatrix} = (A^{T}A)^{T}A^{T}D}{\beta_{1}} = \sum_{i} x_{i}y_{i} - \left(\sum_{i} x_{i}\right)\left(\sum_{i} y_{i}\right)}{\beta_{2}}$$

Let's derive it:

et's derive it:
$$n \sum_{i} x_{i}^{2} - \left(\sum_{i} x_{i}\right)^{2}$$

$$A^{T}A = \begin{bmatrix} 1 & \cdots & 1 \\ x_{1} & x_{2} & \cdots & x_{n} \end{bmatrix} \begin{bmatrix} 1 & x_{1} \\ 1 & x_{2} \\ \vdots & \vdots \\ 1 & x_{n} \end{bmatrix} = \begin{bmatrix} x_{1} & x_{2} & \cdots & x_{n} \\ x_{1} + x_{2} + \cdots + x_{n} & x_{1}^{2} + x_{2}^{2} + \cdots + x_{n}^{2} \end{bmatrix}$$

$$(A^{T}A)^{-1} = \frac{1}{n(\overline{z_i} \times_i^2) - (\overline{z_i} \times_i)^2} \begin{bmatrix} \overline{z_i} \times_i^2 & -\overline{z_i} \times_i \\ -\overline{z_i} \times_i & n \end{bmatrix}$$

$$A^{\Gamma}b = \begin{bmatrix} 1 & \dots & 1 \\ x_1 & \dots & x_n \end{bmatrix} \begin{bmatrix} y_1 \\ y_n \end{bmatrix} = \begin{bmatrix} \sum_{i=1}^{n} y_i \\ \sum_{i=1}^{n} x_i y_i \end{bmatrix}$$

How To: Least Squares Line

$$\begin{bmatrix} 1 & x_1 \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_n \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

How To: Least Squares Line

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Problem. Find the least squares line for the dataset $\{(x_1, y_1), ..., (x_n, y_n)\}$.

Solution. Find the least squares solution to the above equation.

Question

$$\begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & -1 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \\ 1 \\ 3 \end{bmatrix}$$

Find the line of best fit for the dataset

$$\{(0,3),(1,1),(-1,1),(2,3)\}$$

by using the the least-squares method.

If you have time, graph your result and use it to "predict" the corresponding value for the input 4.

$$x^{T}x^{2} = \begin{bmatrix} 4 & 2 \\ 2 & 6 \end{bmatrix}$$

$$x^{T}b = \begin{bmatrix} 8 \\ 6 \end{bmatrix}$$

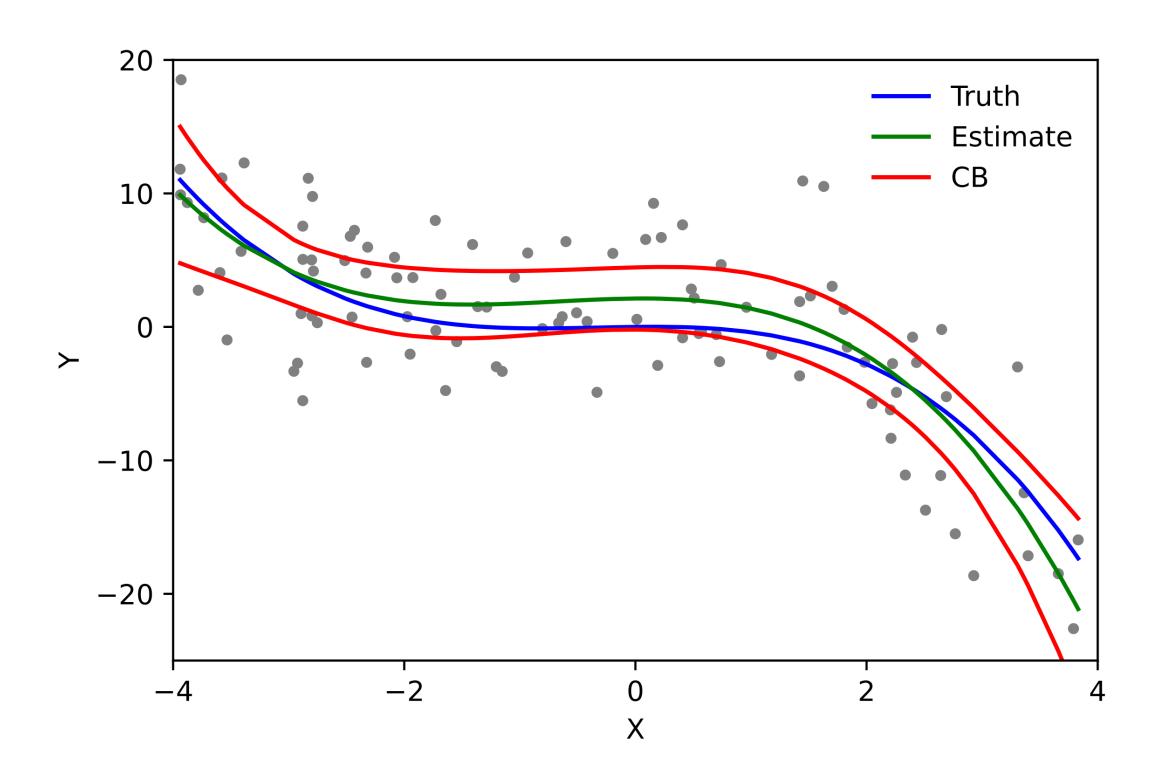
$$x^{T}x^{2}b = \begin{bmatrix} 2 & 1 & 4 \\ 2 & 8 \\ 2 & 6 & 6 \end{bmatrix} \sim \begin{bmatrix} 2 & 1 & 4 \\ 1 & 3 & 3 \end{bmatrix} \sim \begin{bmatrix} 1 & 3 & 3 \\ 0 & -5 & -2 \end{bmatrix}$$

$$\Rightarrow -5\beta_{1} = -2 \Rightarrow \beta_{1} = \frac{2}{5}$$

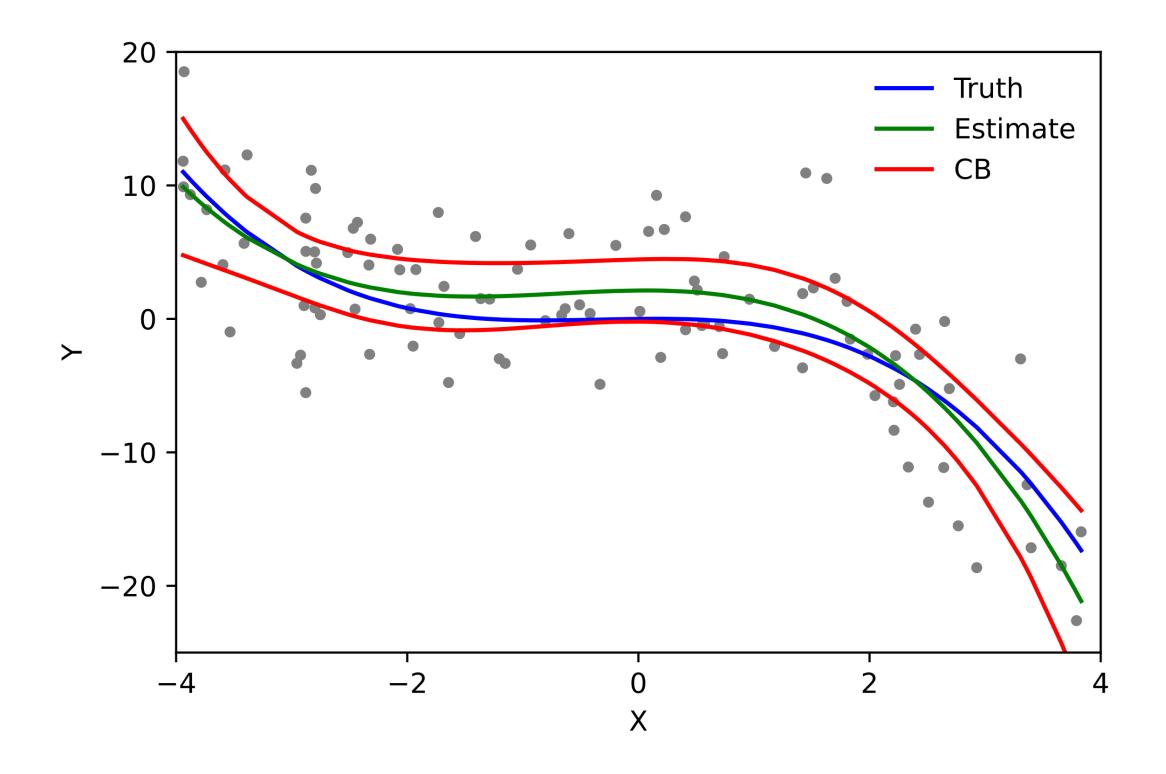
$$\beta_{0} = 3 - 3\beta_{1} = 3 - \frac{6}{5} = \frac{9}{5}$$

$$f(x) = (\frac{2}{5})x + \frac{9}{5}$$

$$f(4) = \frac{8}{5} + \frac{9}{5} = \frac{17}{5}$$

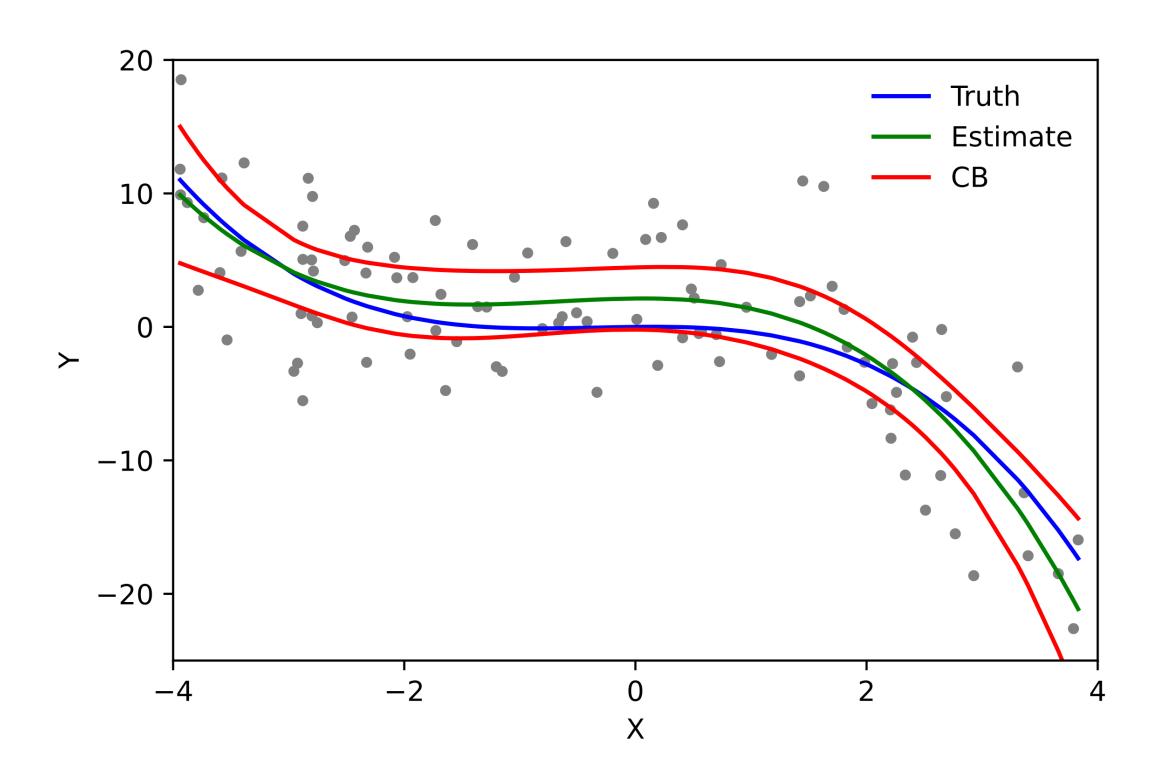


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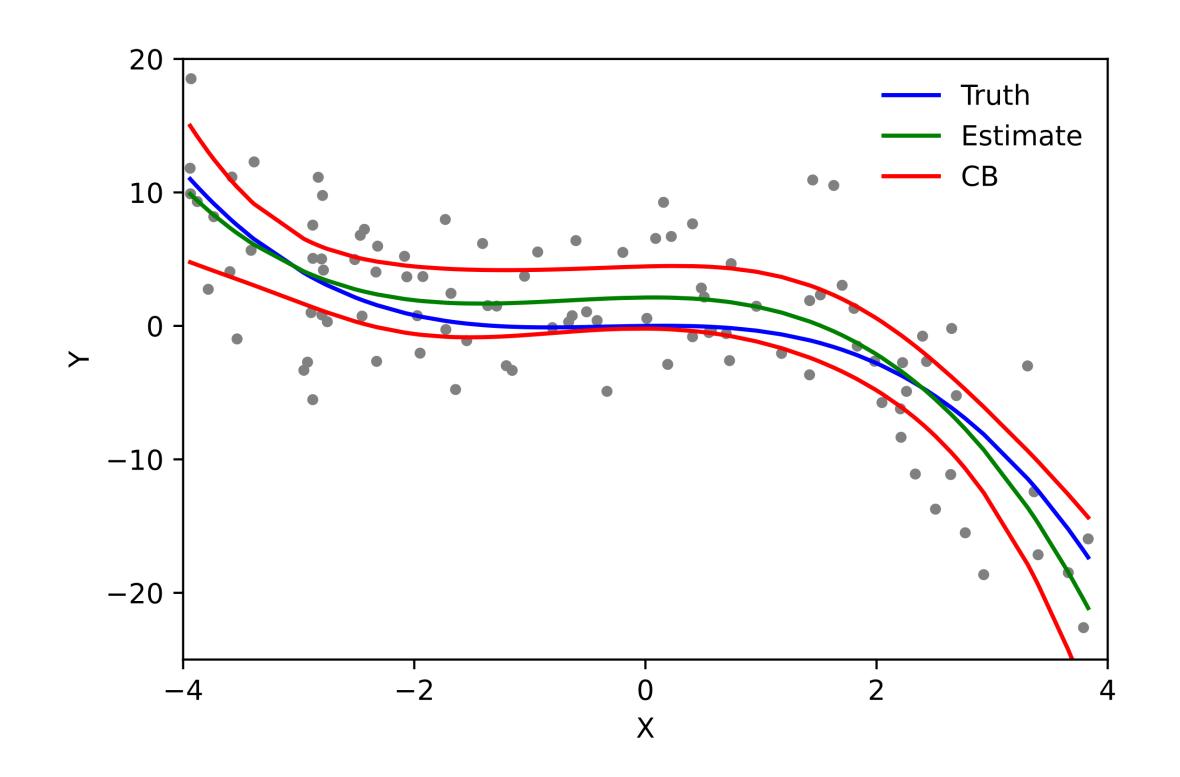
What we are estimating is a mathematical function

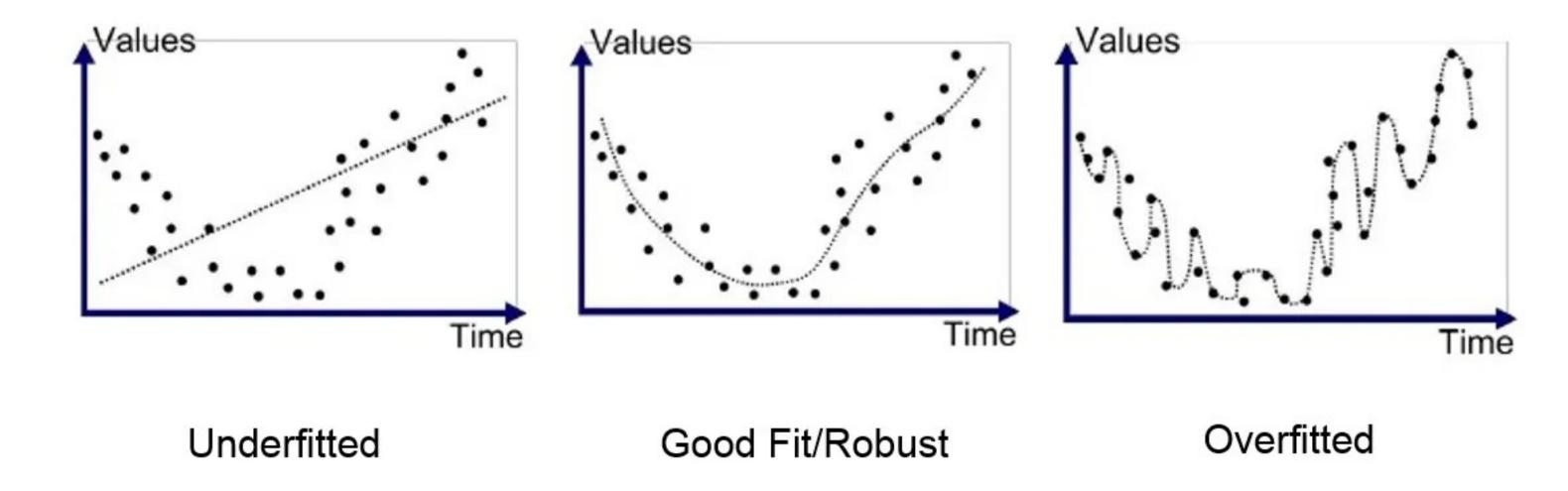


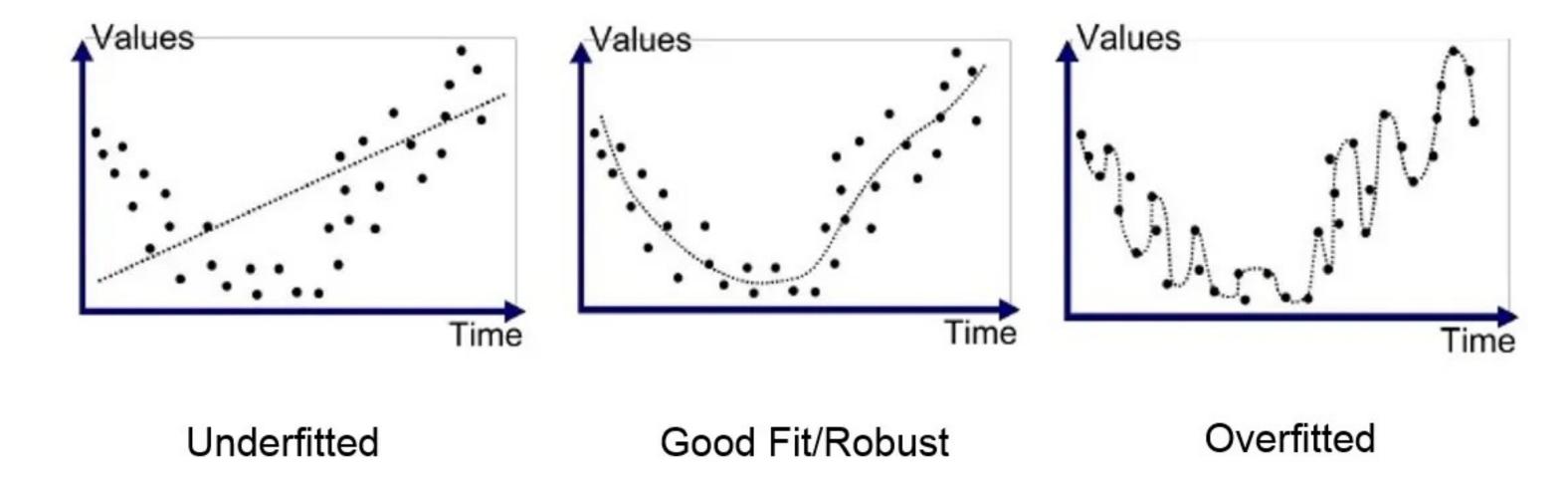
Regression is the process of estimating the relationships independent and dependent variables in a dataset.

What we are estimating is a mathematical function

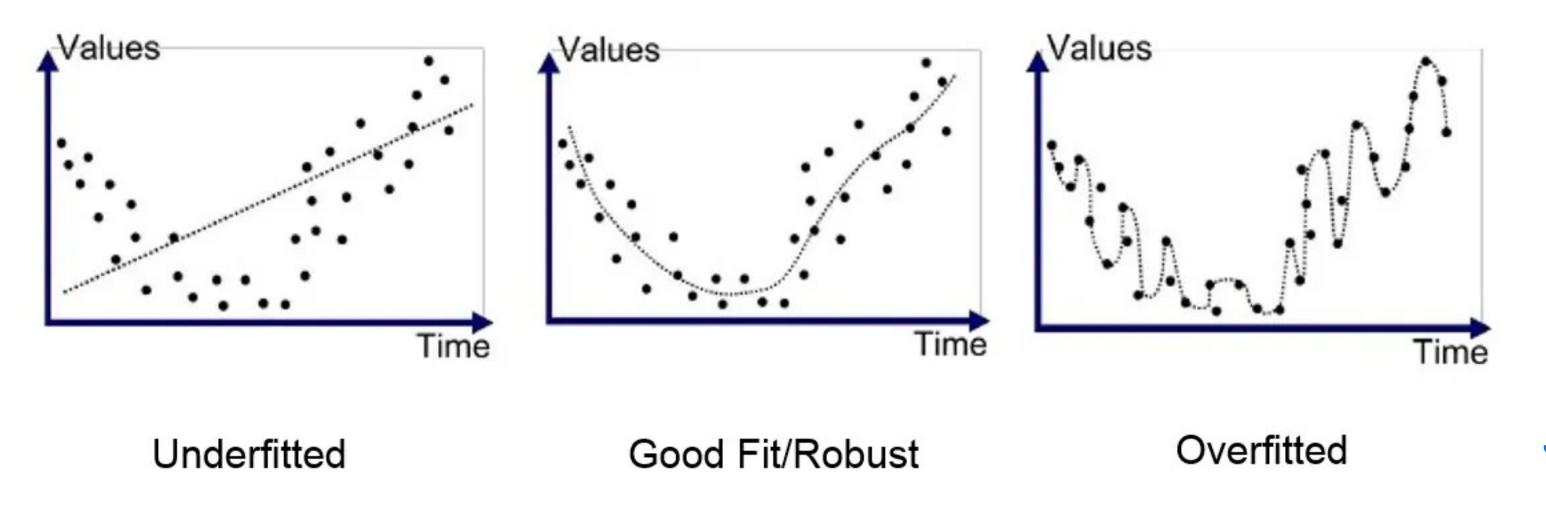
We think of the environment has providing us a function from our independent variables to our dependent variables.





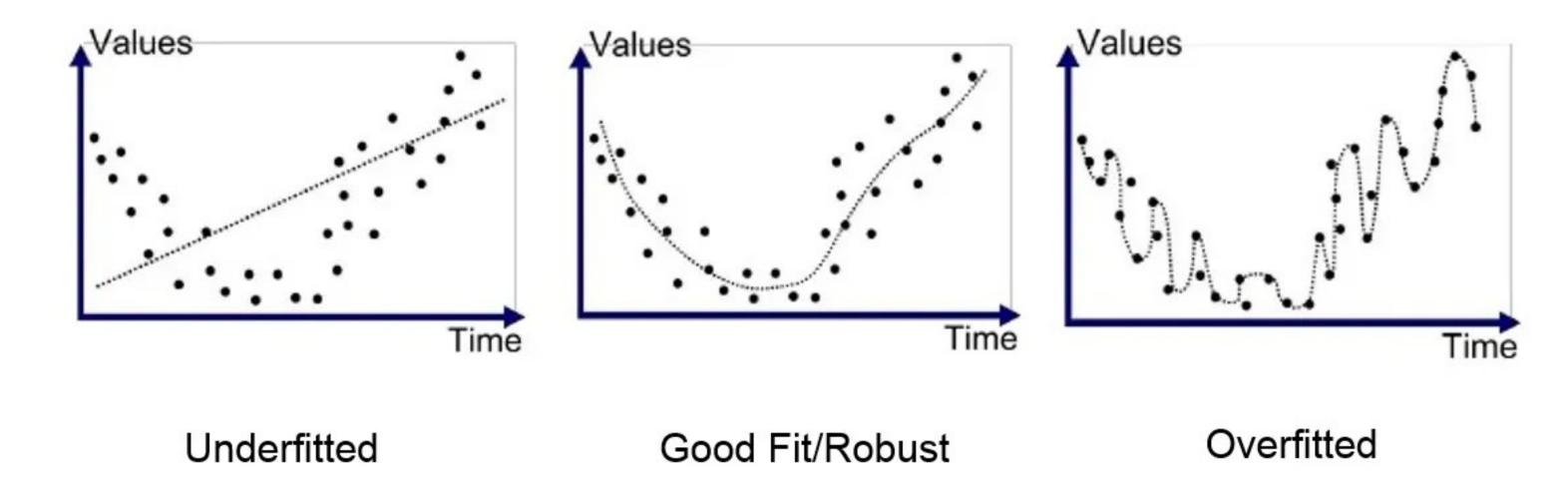


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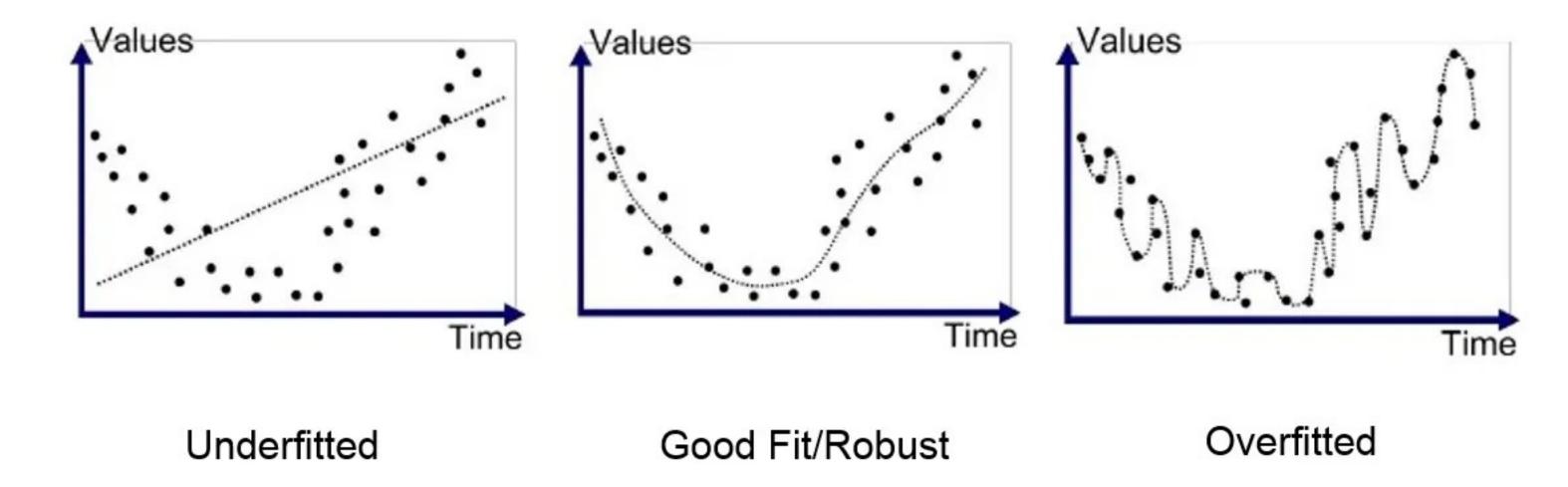
We're interested in finding mathematical functions that correctly model the data we've seen.



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We're interested in finding mathematical functions that "correctly" model the data we've seen.

But this would a bit boring if we just wanted to model data we've seen.



Therefore, a model is a mathematical function.

We're interested in finding mathematical functions that "correctly" model the data we've seen.

But this would a bit boring if we just wanted to model data we've seen.

(Advanced) We pick models from weaker classes of functions so that they are more robust when we **predict** values using the model.

Problem. Given the data $\{(x_1,y_1),...,(x_k,y_k)\}$ use the line of best fit to predict the value of y' for the input x'.

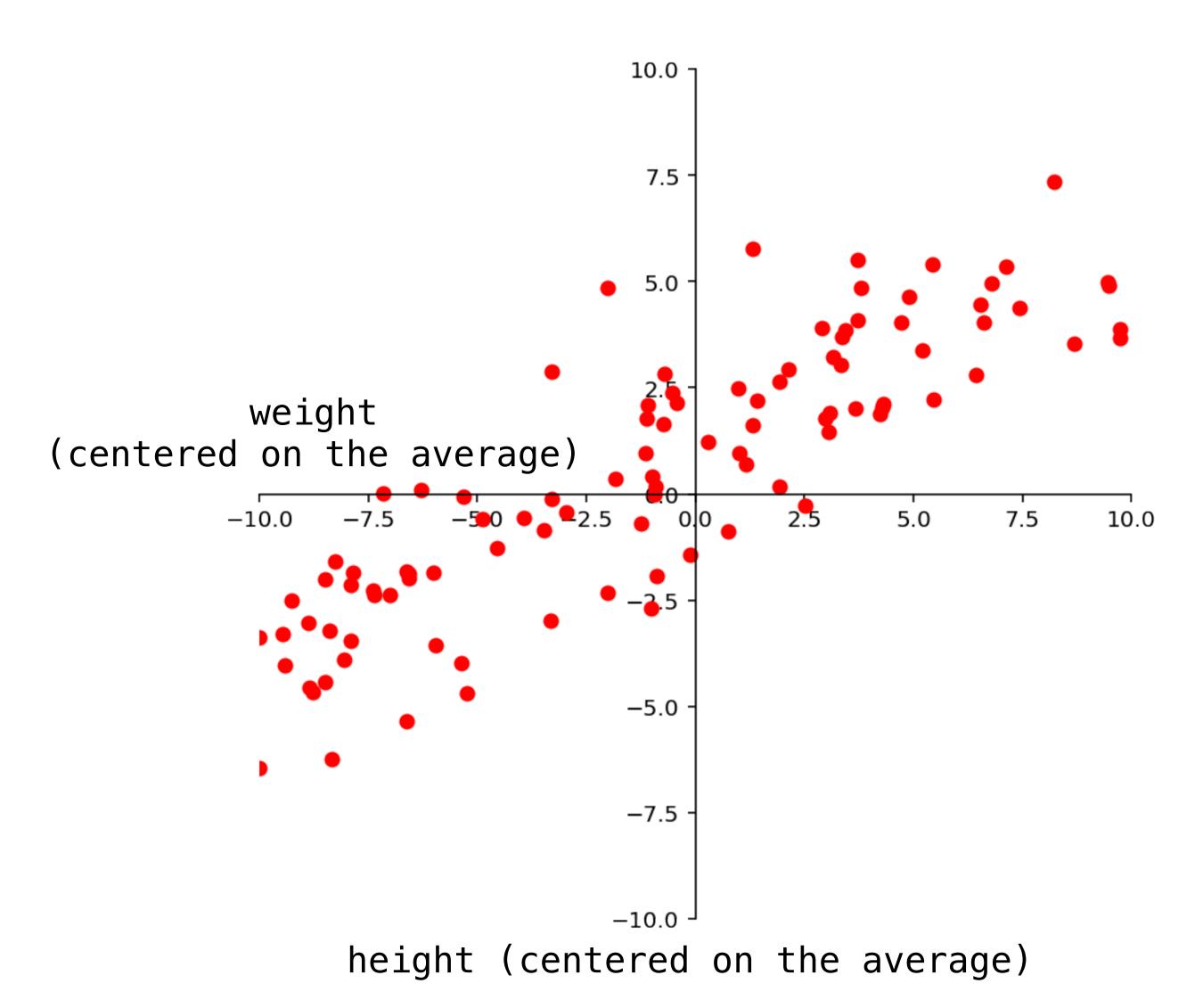
Problem. Given the data $\{(x_1,y_1),...,(x_k,y_k)\}$ use the line of best fit to predict the value of y' for the input x'.

Solution. Find the best fit line $f(x) = \beta_0 + \beta_1 x$. The predicted value of x' is f(x').

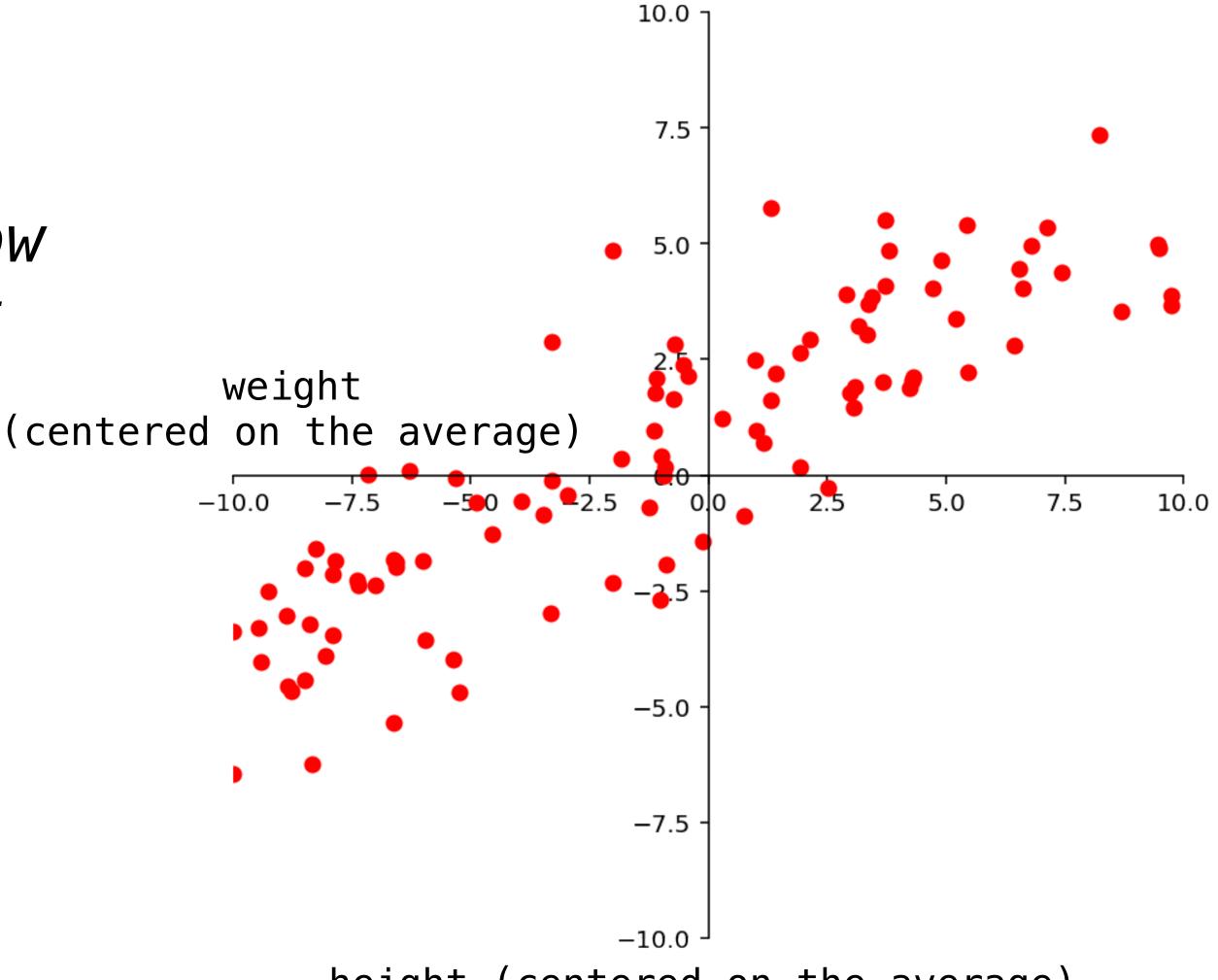
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This generalizes to any model fitting problem

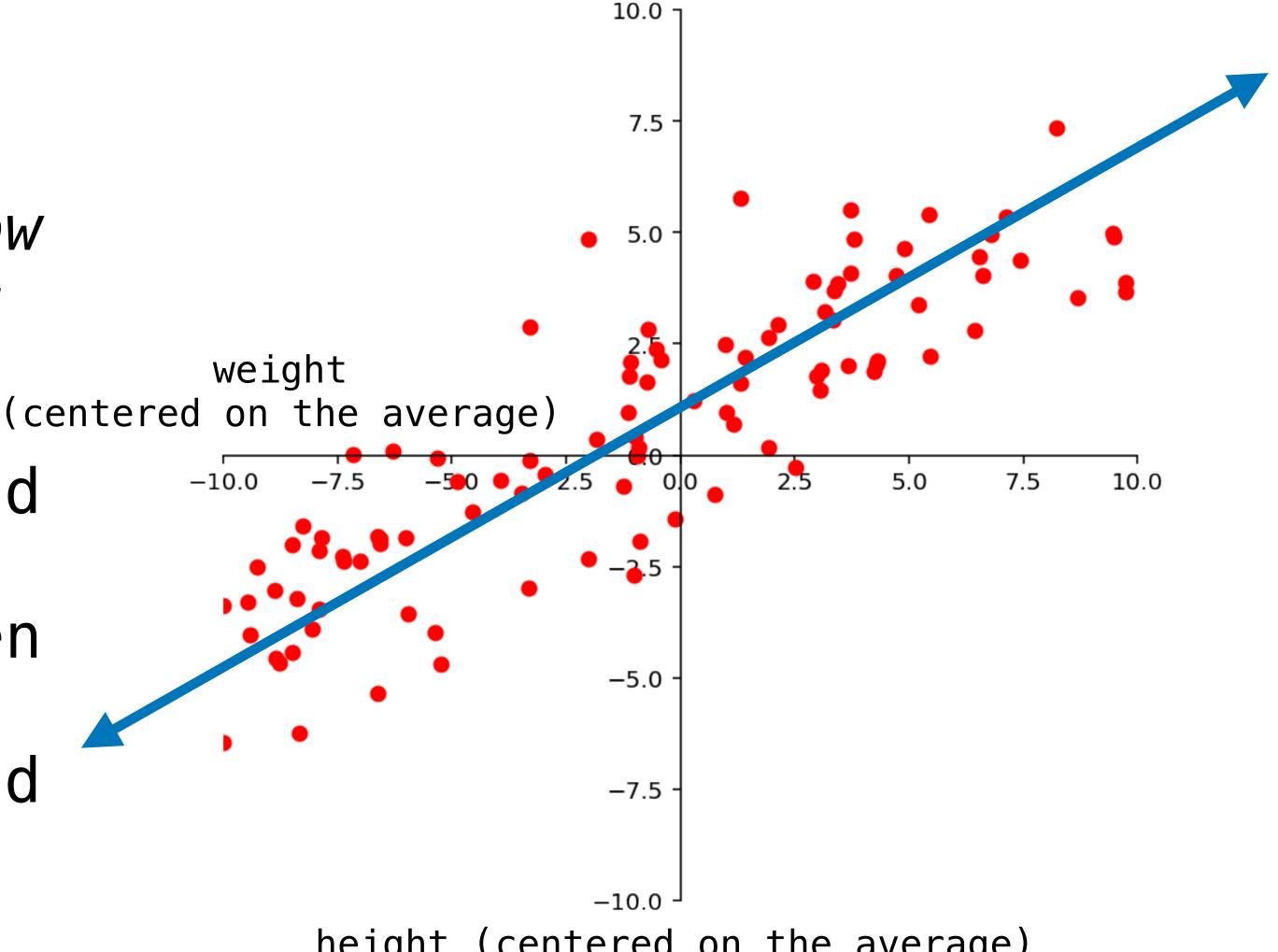


Suppose we know that person X weighs 150lb. How would we guess the height of person X?



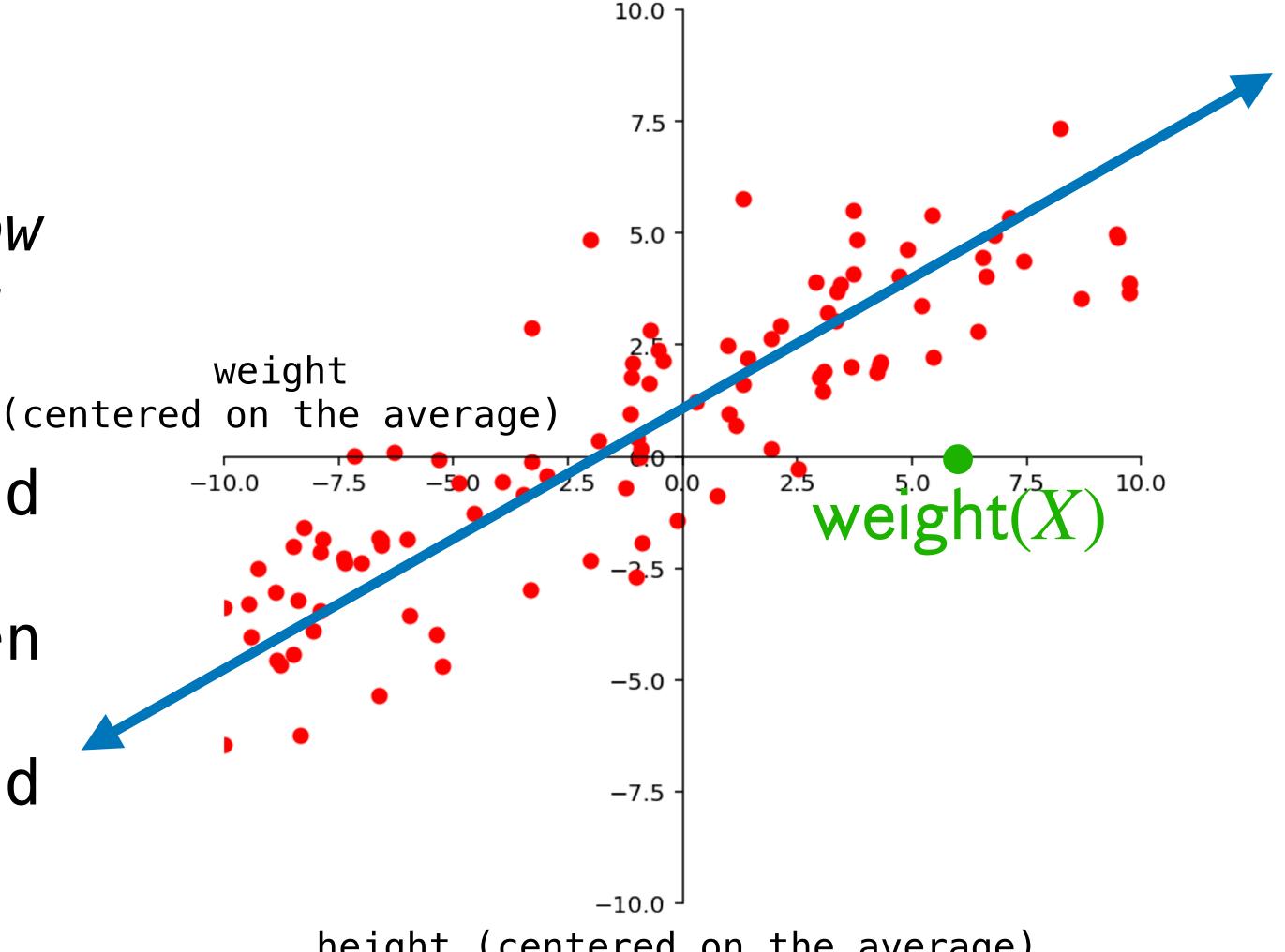
Suppose we know that person X weighs 150lb. How would we guess the height of person X?

If we know the heights and weights of a population (from which X comes), then we can find the line of best fit for that data and then use that function.



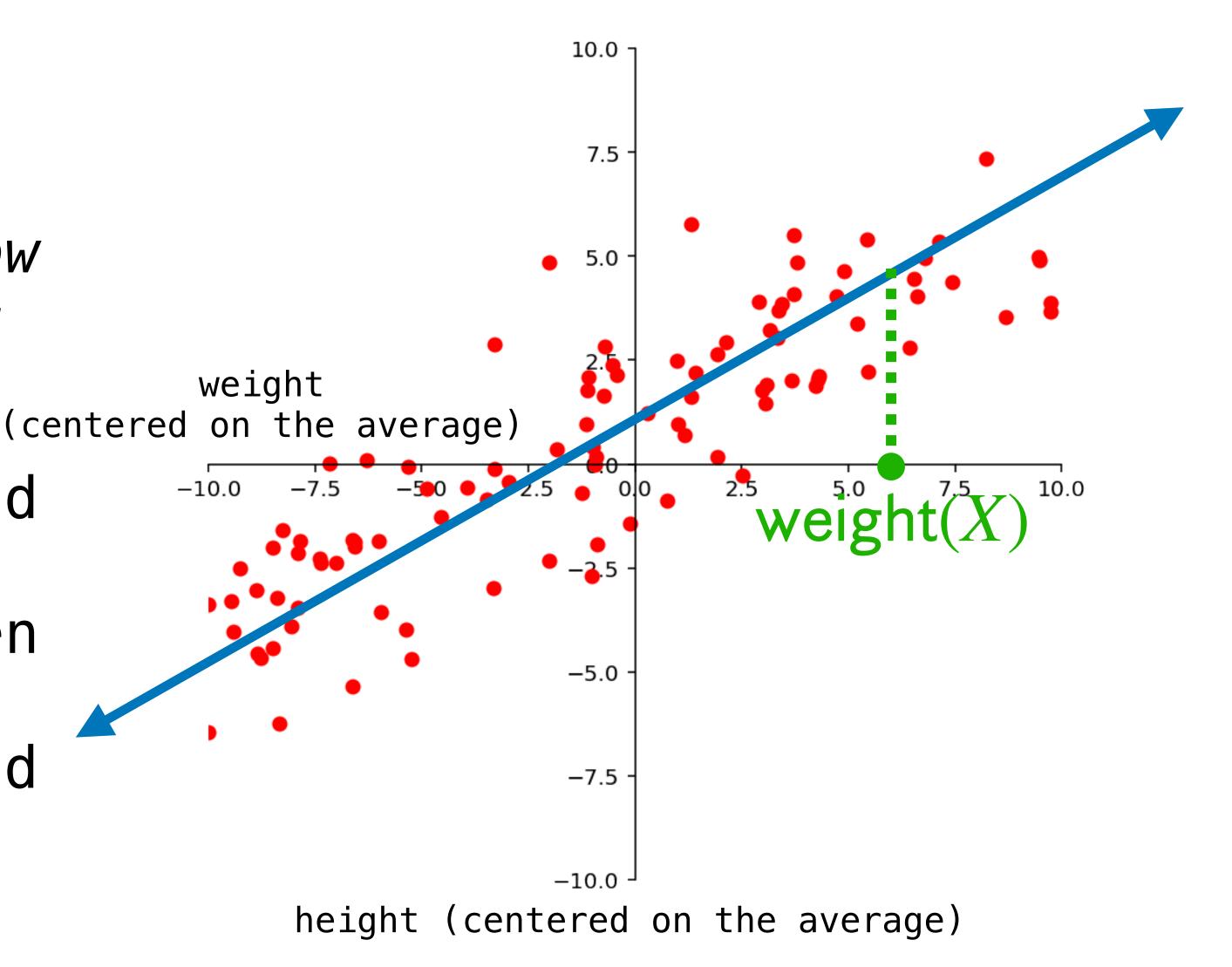
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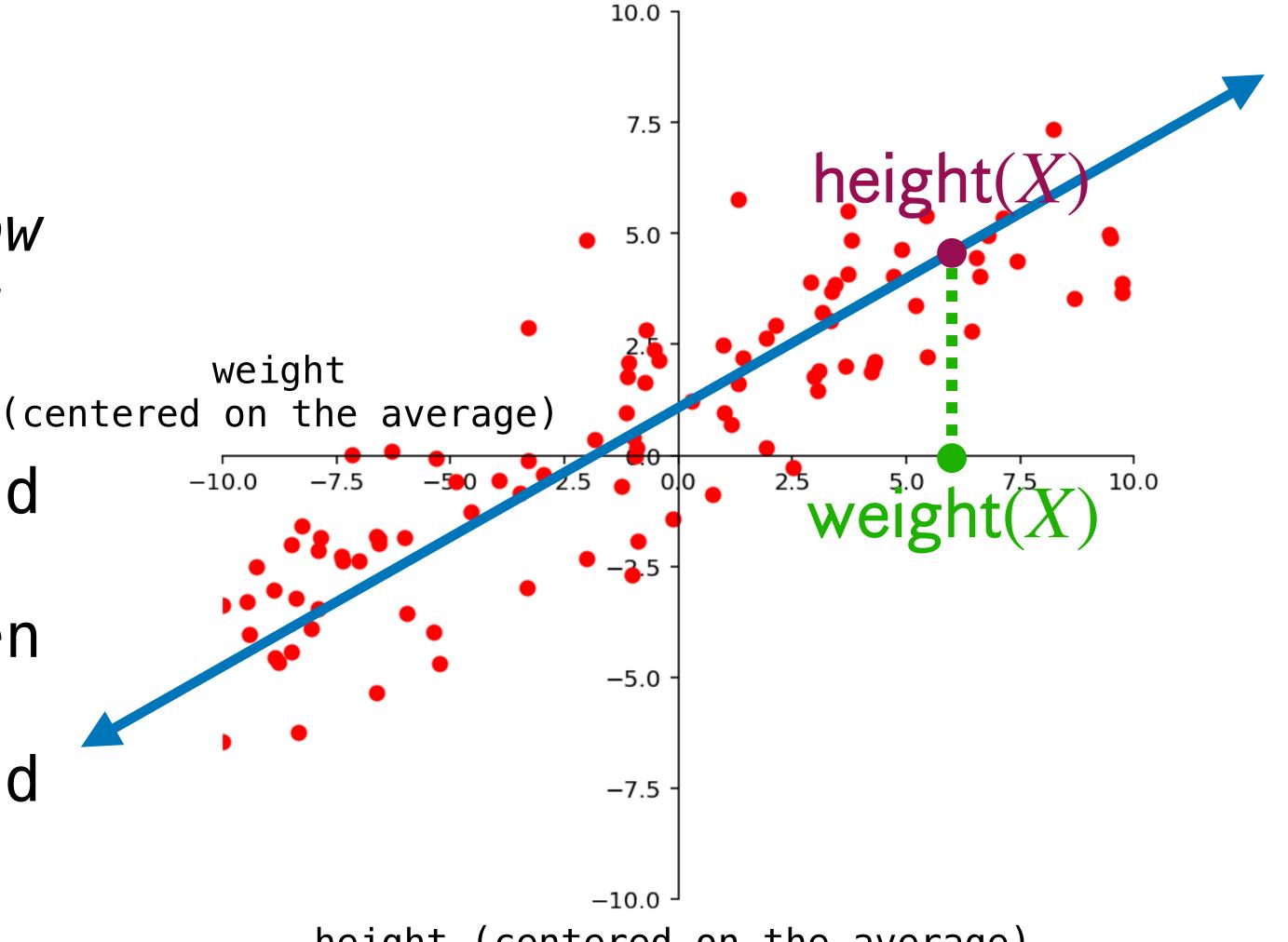
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If we know the heights and weights of a population (from which X comes), then we can **find the line of best fit for that data** and then use that function.



Question

Find the line of best fit for the dataset

$$\{(0,3),(1,1),(-1,1),(2,3)\}$$

If you have time, graph your result and use it to "predict" the corresponding value for the input 4.

$$\{(0,3),(1,1),(-1,1),(2,3)\}$$

Linear Models and Least Squares Regression

1. What if we have *more than one* independent value?

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multiple regression, (hyper)plane of best fit

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e.g., polynomial regression

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multiple regression, (hyper)plane of best fit

2. What if our data is not exactly linear.

e.g., polynomial regression

Figure 23.1

Terrain Data for Multiple Regression

Dataset: $\{(x_1, y_1, z_1), ..., (x_k, y_k, z_k)\}$ where (x_i, y_i) is an longitude and latitude and z_i is an altitude.

Problem: Find the <u>plane</u> which "best" fits the data.

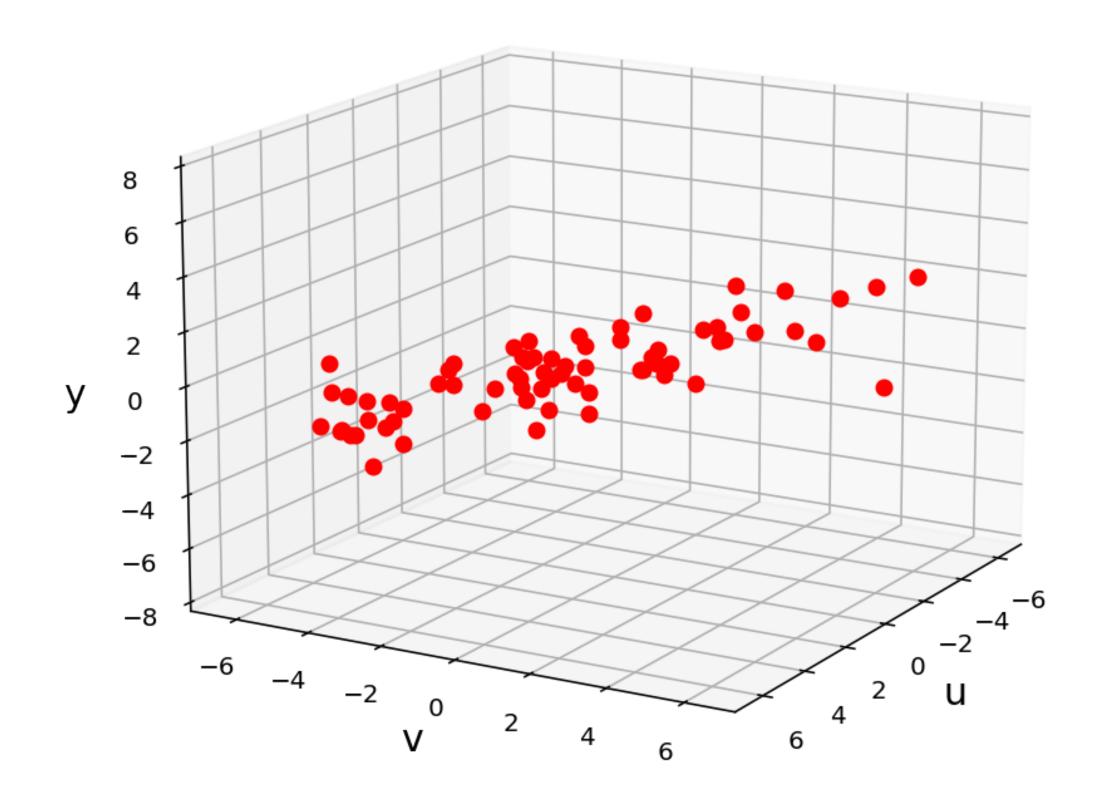


Figure 23.2

Multiple Regression Fit to Data

Dataset: $\{(x_1, y_1, z_1), ..., (x_k, y_k, z_k)\}$ where (x_i, y_i) is an longitude and latitude and z_i is an altitude.

Problem: Find $\beta_0, \beta_1, \beta_2$ such that

$$f(x, y) = \beta_0 + \beta_1 x + \beta_2 y$$

which minimizes

$$\sum_{i=1}^{k} (f(x_i, y_i) - z_i)^2$$

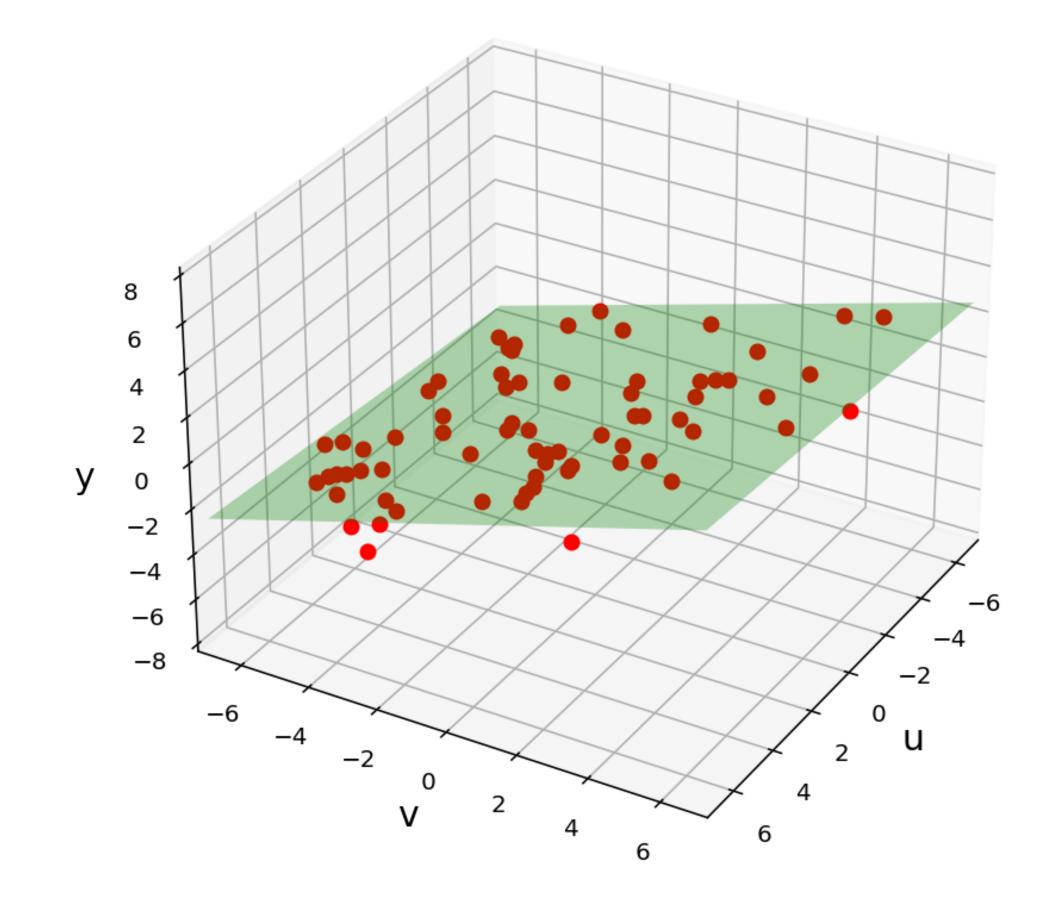


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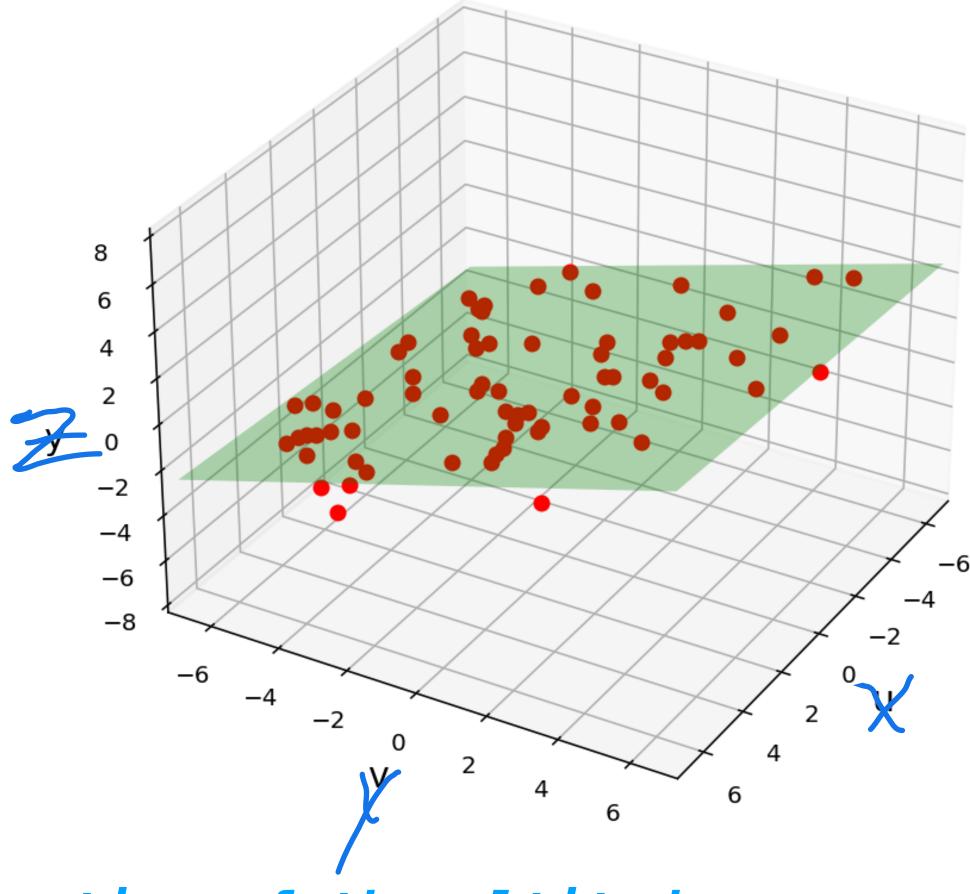
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f(x,y) is a good approximation of the altitude.

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$$f(x,y) = \beta_0 + \beta_1 x + \beta_2 y$$
 recall: planes are given by linear equations

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f(x,y) is a good approximation of the altitude.

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Dataset:
$$\{(x_1,y_1,z_1),...,(x_k,y_k,z_k)\}$$
 $\beta_0+\beta_1x_1+\beta_2y_1=z_1$ where (x_i,y_i) is an longitude and latitude and z_i is an altitude. $\beta_0+\beta_1x_2+\beta_2y_2=z_2$ Problem: Find β_0,β_1,β_2 such that

$$\beta_0 + \beta_1 x_k + \beta_2 y_k = z_k$$

Step 1: Set up an (almost assuredly inconsistent) system of linear equations in terms of the variables $\beta_0, \beta_1, \beta_2$

This is still linear in the β 's

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$$f(x, y) = \beta_0 + \beta_1 x + \beta_2 y$$

$$\begin{bmatrix} 1 & x_1 & y_1 \\ 1 & x_2 & y_2 \\ \vdots & \vdots & \vdots \\ 1 & x_k & y_k \end{bmatrix}$$

$$\begin{bmatrix} \vec{\beta} \\ \beta_0 \\ \beta_1 \\ \beta_2 \end{bmatrix} = \begin{bmatrix} \vec{z} \\ z_1 \\ z_2 \\ \vdots \\ z_k \end{bmatrix}$$

Step 2: Rewrite the system as a matrix equation.

Dataset: $\{(x_1, y_1, z_1), ..., (x_k, y_k, z_k)\}$ where (x_i, y_i) is an longitude and latitude and z_i is an altitude.

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$$\hat{\vec{\beta}} = (X^T X)^{-1} X^T \mathbf{z}$$

Step 3: Find the least squares solution of this system and use as the parameters of your model.

An Aside: Unique Least Squares

$$\begin{bmatrix} 1 & x_1 & y_1 \\ 1 & x_2 & y_2 \\ \vdots & \vdots & \vdots \\ 1 & x_k & y_k \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \end{bmatrix} = \begin{bmatrix} z_1 \\ z_2 \\ \vdots \\ z_k \end{bmatrix}$$

Question (Conceptual). Why can almost always assume that the columns of this matrix are linearly independent?

If the columns were linearly dependent, then one of our independent variables can be computed in terms of the others.

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First off, this is very unlikely.

Answer

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Second, this variable could be then be thought of as a dependent variable.

Answer

If the columns were linearly dependent, then one of our independent variables can be computed in terms of the others.

First off, this is very unlikely.

Second, this variable could be then be thought of as a dependent variable.

It wouldn't contribute anything when using the least squares method.

"Vectors" of Generalization

1. What if we have *more than one* independent value?

multiple regression, (hyper)plane of best fit

2. What if our data is not exactly linear.

e.g., polynomial regression

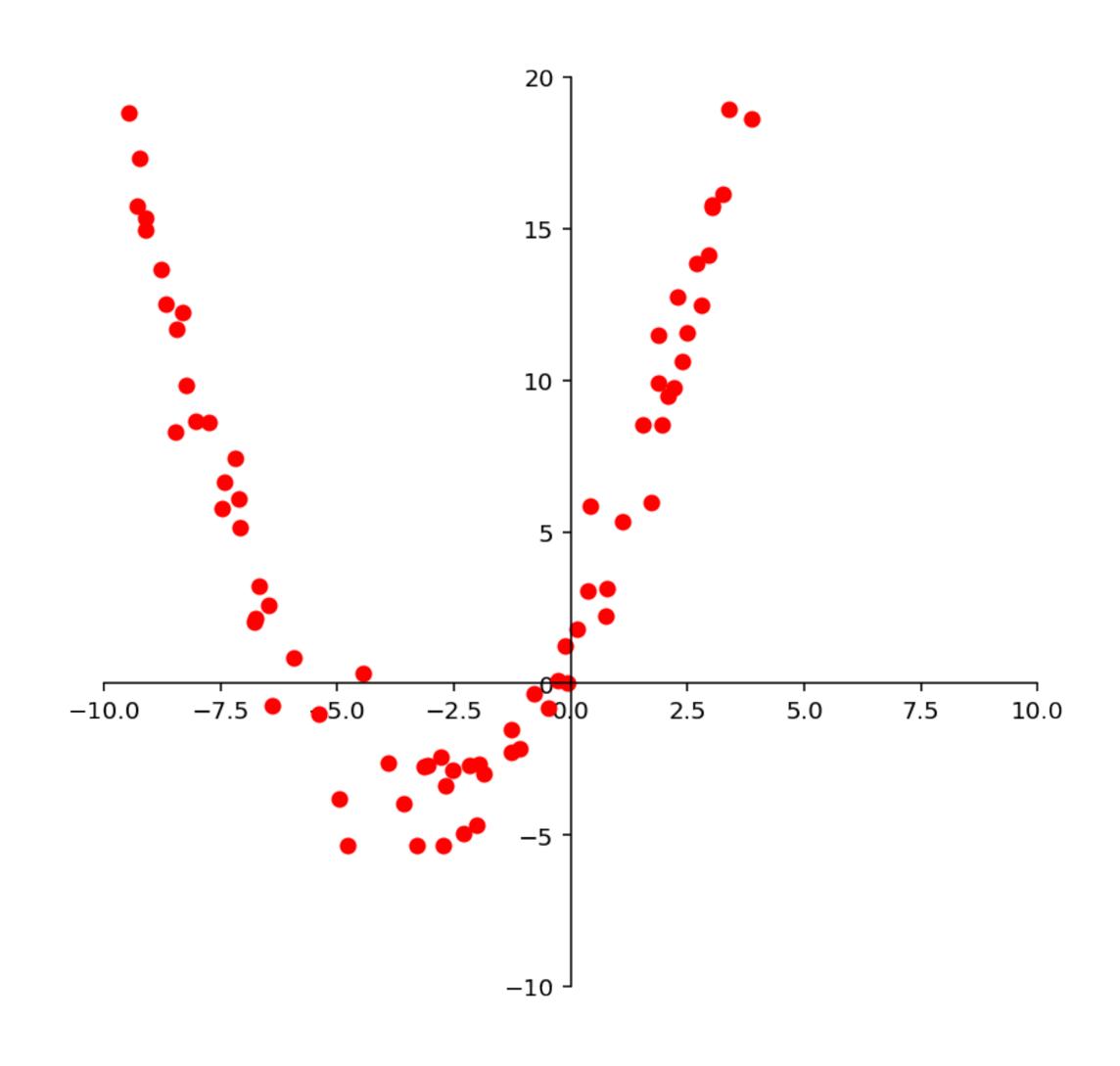
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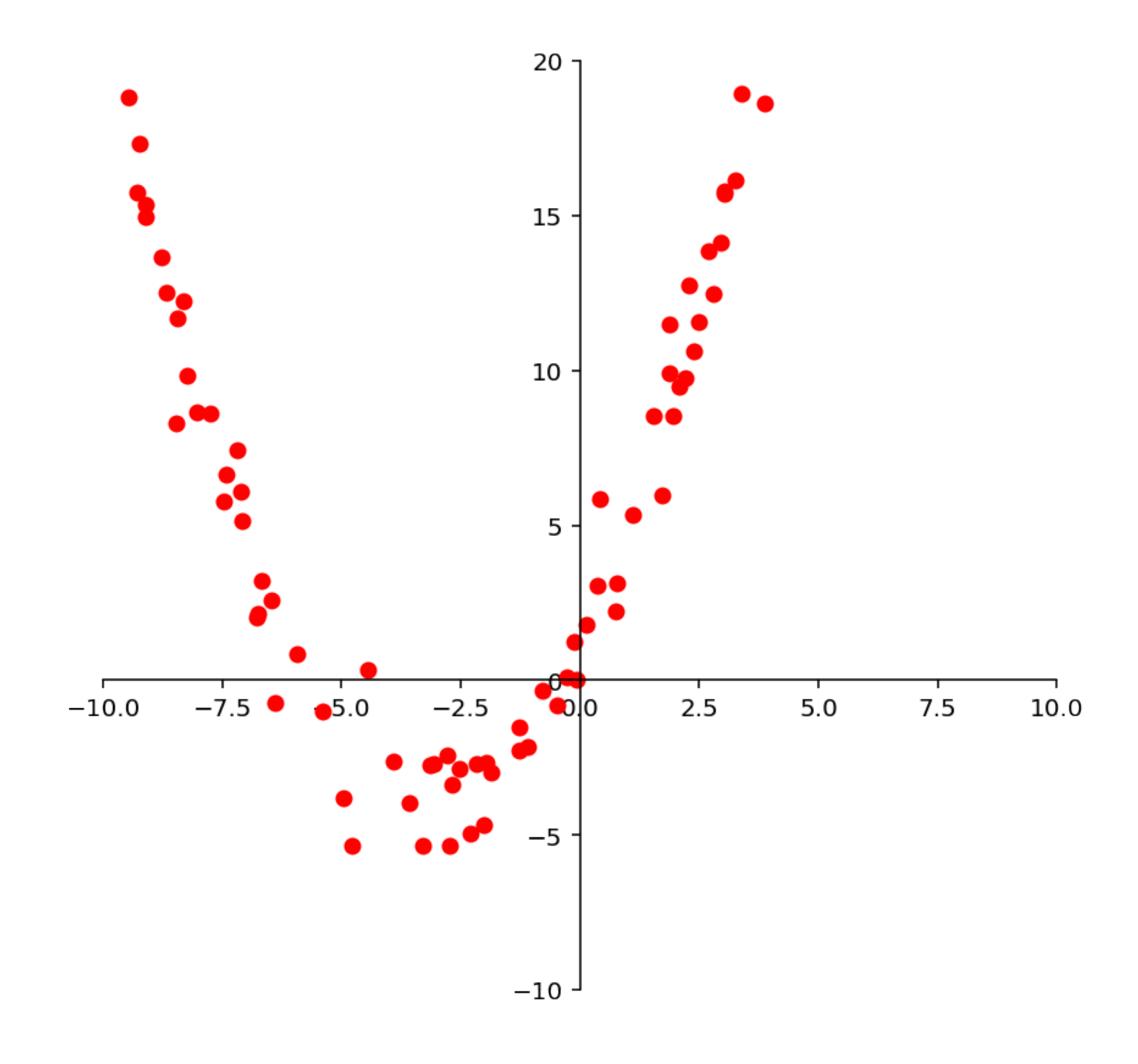
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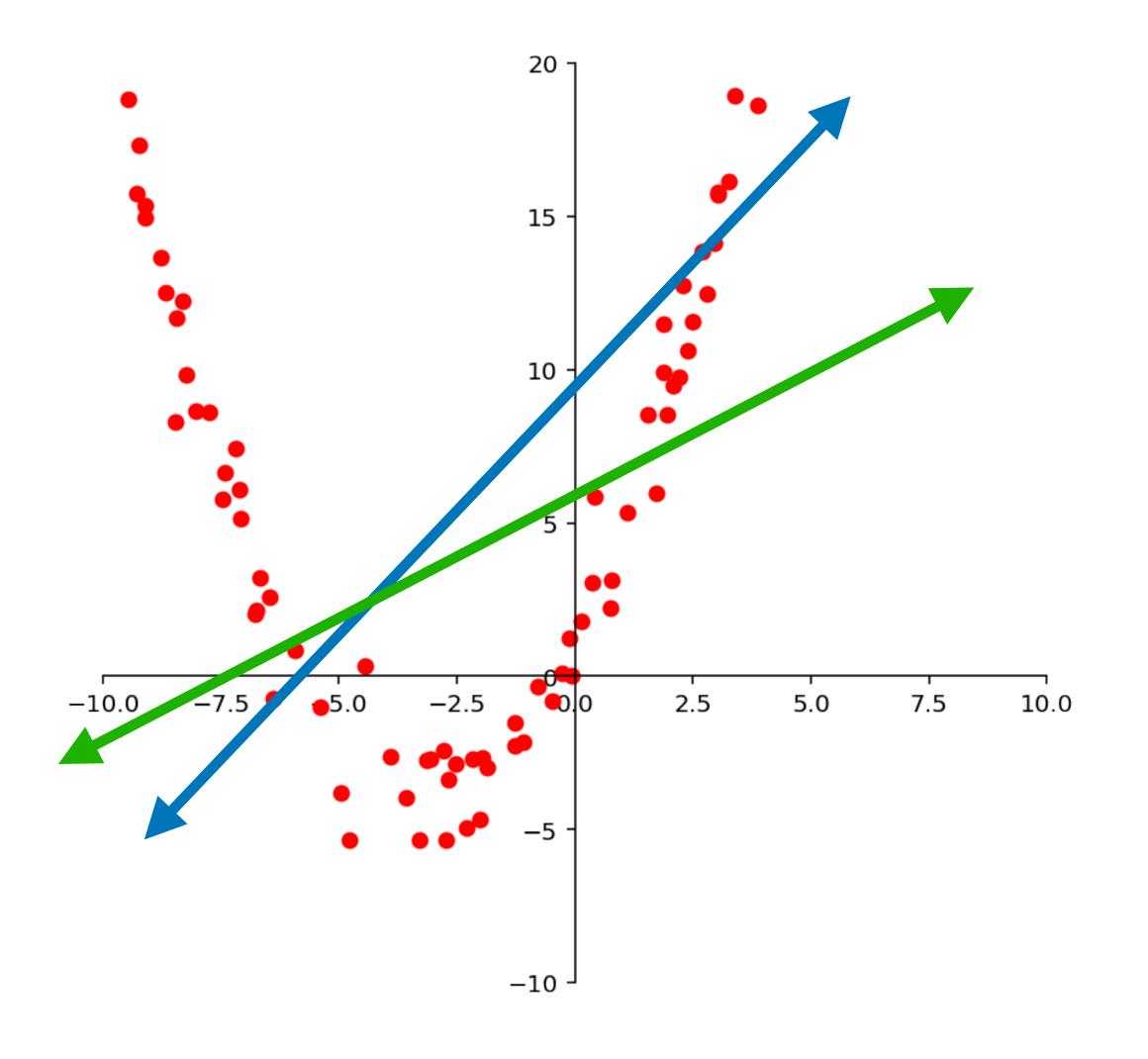


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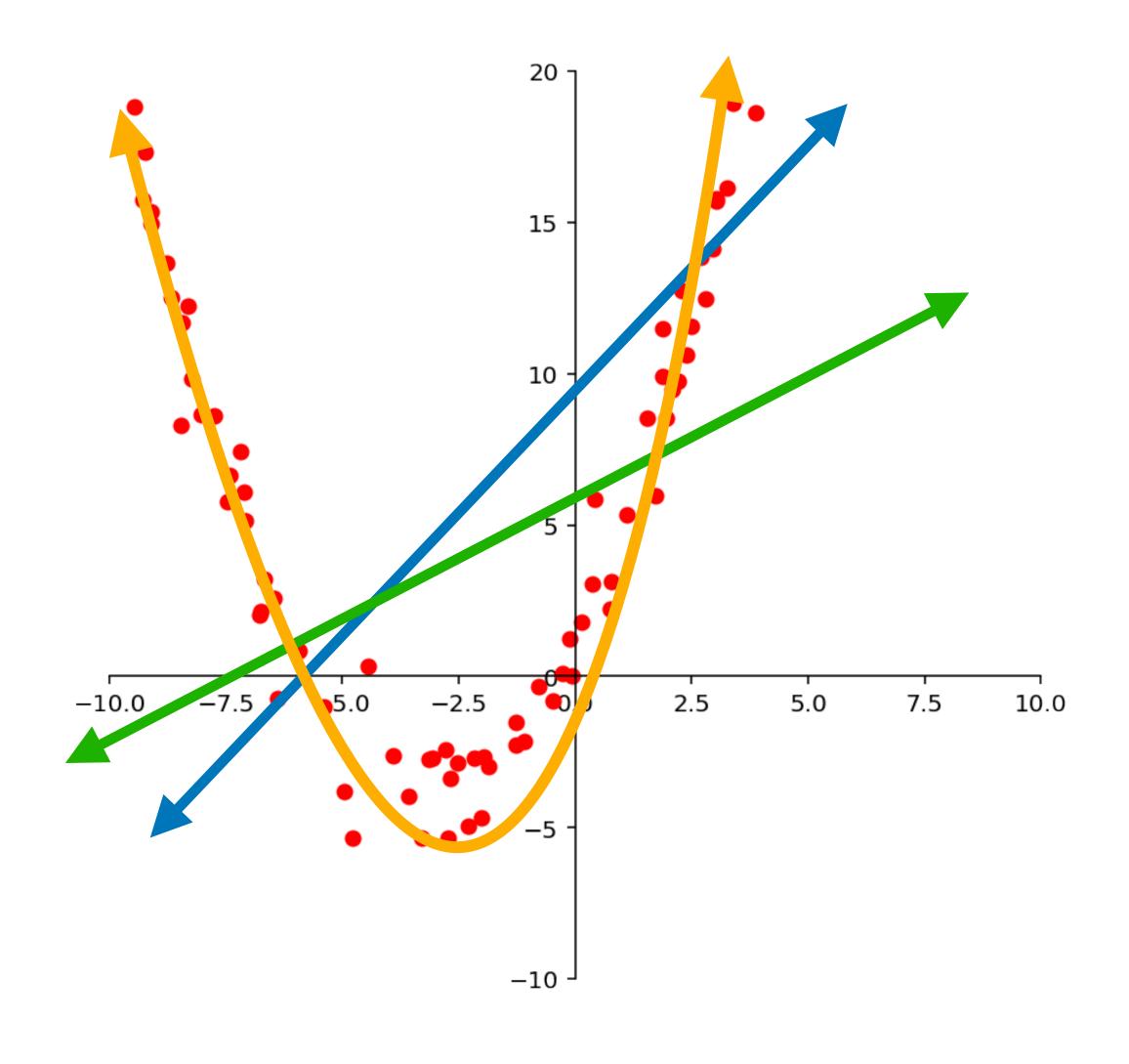
The issue: There is no good line to approximate this data.



Dataset: $\{(x_1, y_1), ..., (x_k, y_k)\}$

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What about a parabola?



Dataset: $\{(x_1, y_1), ..., (x_k, y_k)\}$

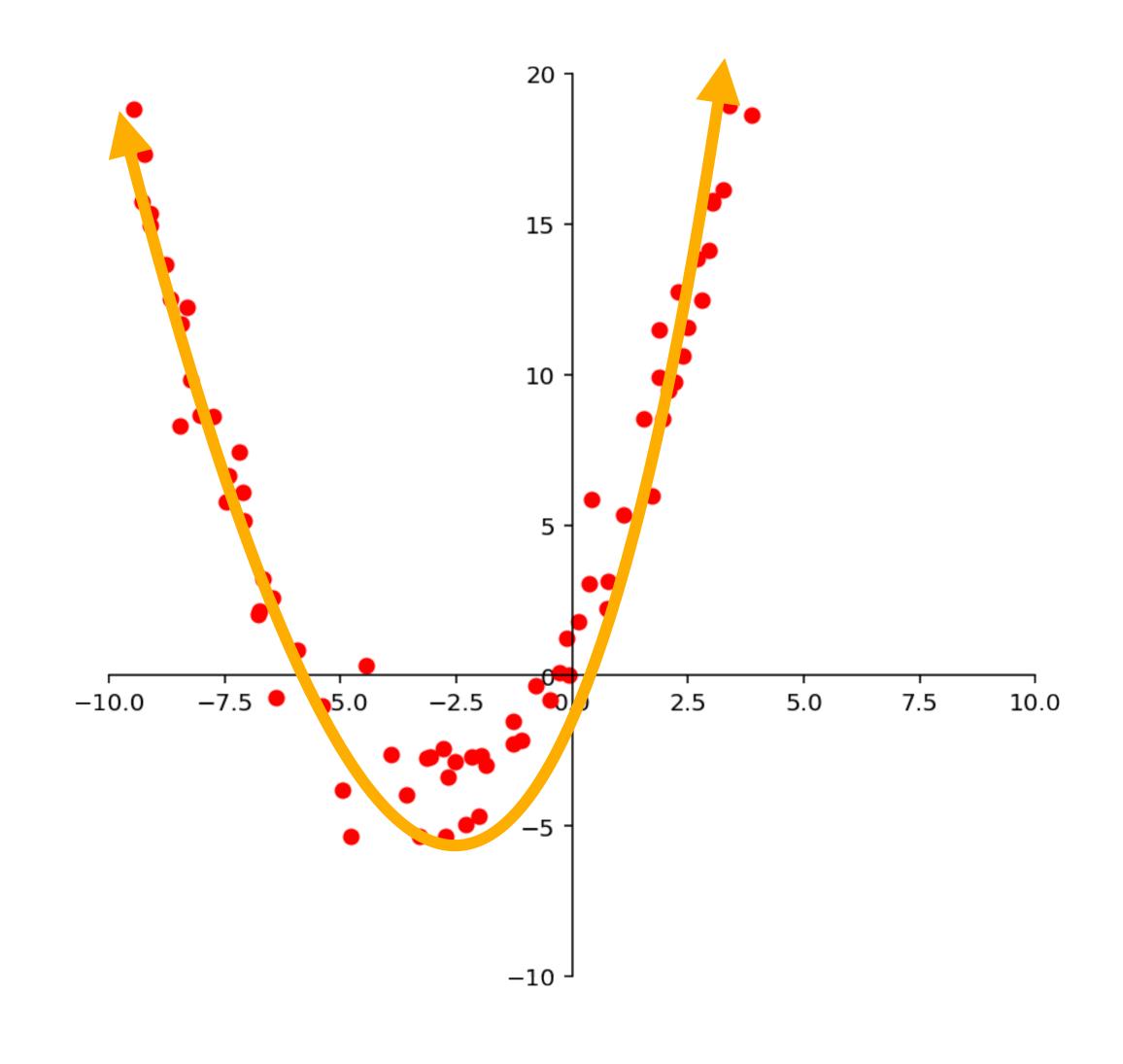
Problem: Find $\beta_0, \beta_1, \beta_2$ such

that

$$f(x) = \beta_0 + \beta_1 x + \beta_2 x^2$$

minimizes

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:

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Step 1: Set up an (almost assuredly inconsistent) system of linear equations in terms of the variables $\beta_0, \beta_1, \beta_2$

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minimizes

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This is still linear in the
$$\beta$$
's
$$\beta_0 + \beta_1 x_1 + \beta_2 x_1^2 = y_1$$

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Dataset: $\{(x_1, y_1), ..., (x_k, y_k)\}$

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$$\hat{\vec{\beta}} = (X^T X)^{-1} X^T \mathbf{y}$$

Step 3: Find the least squares solution of this system and use as the parameters of your model.

The Takeaway

We can use non-linear modeling functions as long as they are <u>linear in the parameters</u>.

Linear in Parameters

Definition. A function $f: \mathbb{R}^n \to \mathbb{R}$ is **linear in the** parameters $\beta_1, ..., \beta_k$ if it can be written as

$$f(\mathbf{x}) = \beta_1 \phi_1(\mathbf{x}) + \beta_2 \phi_2(\mathbf{x}) + \dots + \beta_k \phi_k(\mathbf{x})$$

for functions $\phi_1, ..., \phi_k : \mathbb{R}^n \to \mathbb{R}$

Example:

$$f(x) = \beta_1 \cos(x) + \beta_2 \sinh(x)$$

We can build design matrices for function which are linear in their parameters.

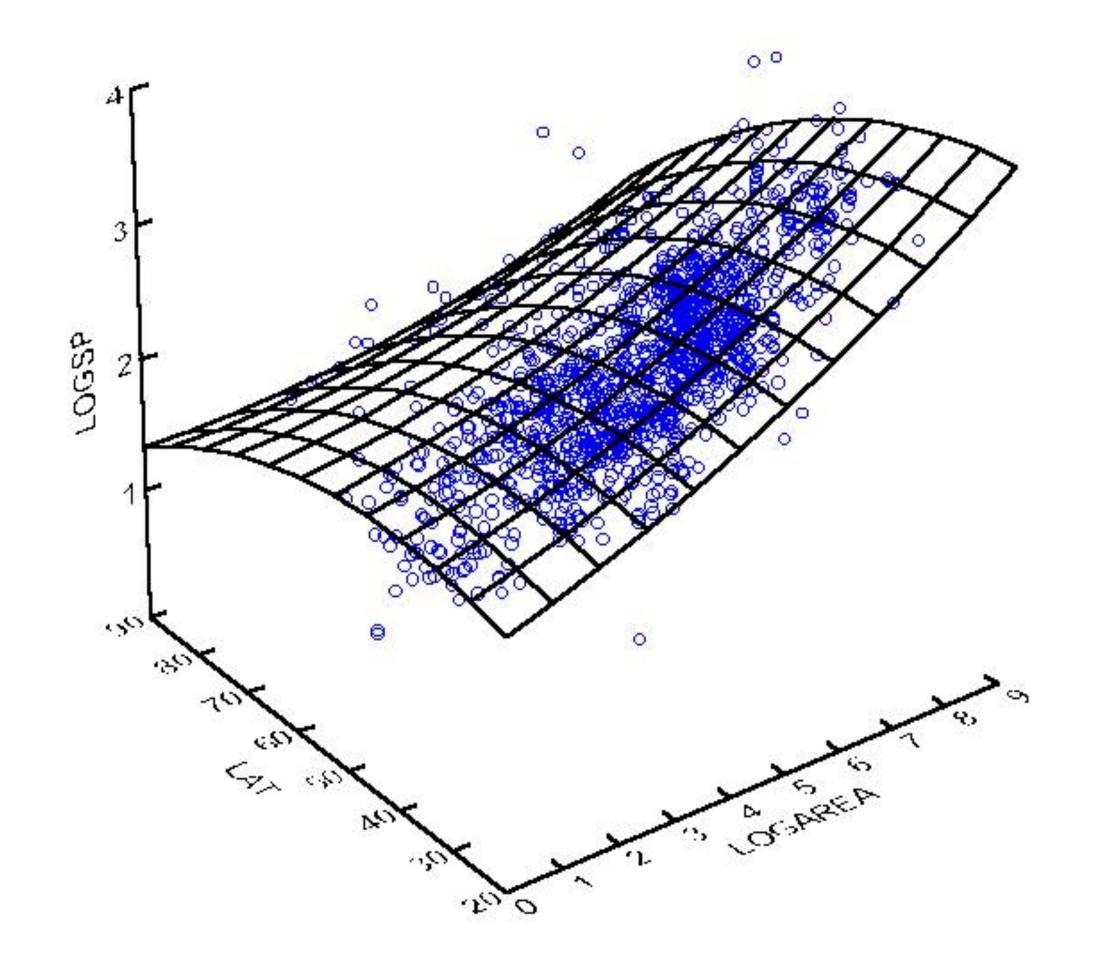
dataset: $\{(\mathbf{x}_1, y_1), ..., (\mathbf{x}_m, y_m)\}$ where $\mathbf{x}_i \in \mathbb{R}^n$ and $y_i \in \mathbb{R}$

Problem. Given a function

$$f_{\beta_1,\ldots,\beta_k}:\mathbb{R}^n\to\mathbb{R}$$

which is *linear in the* parameters $\beta_1,...,\beta_k$, find values for $\beta_1,...,\beta_k$ which minimize

$$\sum_{i=1}^{k} (f_{\beta_1,\ldots,\beta_k}(\mathbf{x}_i) - y_i)^2$$



dataset: $\{(\mathbf{x}_1, y_1), ..., (\mathbf{x}_m, y_m)\}$ where $\mathbf{x}_i \in \mathbb{R}^n$ and $y_i \in \mathbb{R}$

Problem. Given a function

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$$\sum_{i=1}^{k} (f_{\beta_1,\ldots,\beta_k}(\mathbf{x}_i) - y_i)^2$$

$$\beta_1 \phi_1(\mathbf{x}_1) + \dots + \beta_k \phi_k(\mathbf{x}_1) = y_1$$

 $\beta_1 \phi_1(\mathbf{x}_2) + \dots + \beta_k \phi_k(\mathbf{x}_2) = y_2$
:

$$\beta_1 \phi_1(\mathbf{x}_2) + \dots + \beta_k \phi_k(\mathbf{x}_2) = y_2$$

Step 1: Set up an (almost assuredly inconsistent) system of linear equations in terms of the variables $\beta_1, ..., \beta_k$

This is still linear in the β 's

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$$\{(\mathbf{x}_1, y_1), ..., (\mathbf{x}_m, y_m)\}$$
 where $\mathbf{x}_i \in \mathbb{R}^n$ and $y_i \in \mathbb{R}$

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 $\begin{bmatrix} \phi_1(\mathbf{x}_1) & \phi_2(\mathbf{x}_1) & \dots & \phi_k(\mathbf{x}_1) \\ \phi_1(\mathbf{x}_2) & \phi_2(\mathbf{x}_2) & \dots & \phi_k(\mathbf{x}_2) \\ \vdots & \vdots & \ddots & \vdots \\ \phi_1(\mathbf{x}_m) & \phi_2(\mathbf{x}_m) & \dots & \phi_k(\mathbf{x}_m) \end{bmatrix} \begin{bmatrix} \vec{\beta}_1 \\ \beta_2 \\ \vdots \\ \beta_k \end{bmatrix} = \begin{bmatrix} \mathbf{y}_1 \\ y_2 \\ \vdots \\ y_k \end{bmatrix}$

Step 2: Rewrite the system as a matrix equation.

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How To: Design Matrices

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Problem. Find the design matrix for least squares regression with the function f in terms of the parameters $\beta_1, \beta_2, ..., \beta_k$ given the dataset $\{(\mathbf{x}_1, y_1), ..., (\mathbf{x}_m, y_m)\}$.

How To: Design Matrices

Problem. Find the design matrix for least squares regression with the function f in terms of the parameters $\beta_1, \beta_2, ..., \beta_k$ given the dataset $\{(\mathbf{x}_1, y_1), ..., (\mathbf{x}_m, y_m)\}$.

Solution. First write $f(\mathbf{x})$ as $\beta_1\phi_1(\mathbf{x}) + ... + \beta_k\phi(\mathbf{x})$ where $\phi_1, ..., \phi_k$ are potentially non-linear functions. Then build the matrix:

$$\begin{bmatrix} \phi_1(\mathbf{x}_1) & \phi_2(\mathbf{x}_1) & \dots & \phi_k(\mathbf{x}_1) \\ \phi_1(\mathbf{x}_2) & \phi_2(\mathbf{x}_2) & \dots & \phi_k(\mathbf{x}_2) \\ \vdots & \vdots & \ddots & \vdots \\ \phi_1(\mathbf{x}_m) & \phi_2(\mathbf{x}_m) & \dots & \phi_k(\mathbf{x}_m) \end{bmatrix}$$

Question



Find the design matrix for the least squares regression with the function

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \mapsto \beta_1 \cos(x_1) + \beta_2 e^{-x_1 x_2} - \beta_1 x_3 + \beta_3$$

$$\beta_1 (\cos(x_1) - x_3) + \beta_2 (e^{-x_1 x_2} - x_3) + \beta_3 (1)$$
Aset

for the dataset

7 data
$$\longrightarrow$$
 $\mathbf{x}_1 = (0,0,0)$ $y_1 = 5$

$$\mathbf{x}_2 = (\pi,3,1)$$
 $y_2 = 3$

Answer:
$$\begin{bmatrix} 1 & 1 & 1 \\ -2 & e^{-3\pi} & 1 \end{bmatrix}$$

$$B_1(\cos(0)-(0)+B_2(e^{-(8)(0)})+B_3=5$$

 $B_1(\cos(\alpha)-1)+B_2(e^{-(8)(0)})+B_3=3$

Many functions require large design matrices, e.g. multivariate polynomials have *a lot* of possible terms.

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We haven't actually talked about which modeling functions to use.

Again, is least-squares error really what we want? What if we want to minimize something else?

Concerns for another class.