

sal_t1: Mutable Variables, Immutable References

CS392-M1: *Rust, In Practice and in Theory*

1 Syntax

The following is the BNF specification for the syntax of sal_t1. We fix an arbitrary set \mathcal{V} of variables.

x	(variables, \mathcal{V})
n	(integers, \mathbb{Z})
$\ell ::= \ell_x$	(locations, \mathcal{L})
$w ::= \{*\} x$	(place expression, \mathcal{W})
$v ::= () \mid n \mid \ell$	(values, Val)
$e ::= () \mid n \mid w \mid \& w \mid x = e$	(expressions, \mathcal{E})
$p ::= \{s ;\} e$	(programs, \mathcal{P})
$s ::= e \mid \text{let } [\text{mut}] x = e$	(statements, \mathcal{S})
$t ::= \text{i32} \mid () \mid \& w$	(types, \mathcal{T})
$m ::= \text{imm} \mid \text{mut}$	(mutability)

2 Typing

There are three kinds of typing judgments:

$\Gamma \vdash e : t \dashv \Gamma$	(expressions)
$\Gamma \vdash s \dashv \Gamma$	(statements)
$\Gamma \vdash p : t \dashv \Gamma$	(programs)

Γ is a typing context which we will take to be a map from variables to types tagged with mutability information (i.e., a map of the form $\mathcal{V} \mapsto \mathcal{T} \times \{\text{imm}, \text{mut}\}$). Note that expression can have side-effects because of the assignment operator. The following are the typing rules for sal_t1.

$\frac{}{\Gamma \vdash () : () \dashv \Gamma}$ (unit)	$\frac{}{\Gamma \vdash n : \text{i32} \dashv \Gamma}$ (int)	$\frac{(x \mapsto t^m) \in \Gamma}{\Gamma \vdash x : t \dashv \Gamma}$ (var)
$\frac{\Gamma \vdash w_1 : \& w_2 \dashv \Gamma \quad \Gamma \vdash w_2 : t \dashv \Gamma}{\Gamma \vdash * w_1 : t \dashv \Gamma}$ (deref)	$\frac{\Gamma \vdash w : t \dashv \Gamma}{\Gamma \vdash \& w : \& w \dashv \Gamma}$ (imm-borrow)	
$\frac{}{\Gamma \vdash \text{i32} \approx \text{i32}}$ (\approx -int)	$\frac{}{\Gamma \vdash () \approx ()}$ (\approx -unit)	
$\frac{\Gamma \vdash w_1 : t_1 \dashv \Gamma \quad \Gamma \vdash w_2 : t_2 \dashv \Gamma \quad \Gamma \vdash t_1 \approx t_2}{\Gamma \vdash \& w_1 \approx \& w_2}$ (\approx -borrow)		

Definition. $\text{writable}(\Gamma, x)$ is equivalent to $\nexists y. (y \mapsto \& x) \in \Gamma$.

$$\begin{array}{c}
\frac{(x \mapsto t_1^{\text{mut}}) \in \Gamma_1 \quad \Gamma_1 \vdash e : t_2 \dashv \Gamma_2 \quad \Gamma_2 \vdash t_1 \approx t_2 \quad \text{writable}(\Gamma_2, x)}{\Gamma_1 \vdash x = e : (\text{ }) \dashv \Gamma_2[x \mapsto t_2^{\text{mut}}]} \text{ (assign)} \\
\\
\frac{\Gamma_1 \vdash e : t \dashv \Gamma_2}{\Gamma_1 \vdash e \dashv \Gamma_2} \text{ (expr-stmt)} \\
\\
\frac{\Gamma_1 \vdash e : t \dashv \Gamma_2 \quad x \notin \text{dom}(\Gamma_2)}{\Gamma_1 \vdash \text{let } x = e \dashv \Gamma_2[x \mapsto t^{\text{imm}}]} \text{ (let)} \quad \frac{\Gamma_1 \vdash e : t \dashv \Gamma_2 \quad x \notin \text{dom}(\Gamma_2)}{\Gamma_1 \vdash \text{let mut } x = e \dashv \Gamma_2[x \mapsto t^{\text{mut}}]} \text{ (let-mut)} \\
\\
\frac{\Gamma_1 \vdash s \dashv \Gamma_2 \quad \Gamma_2 \vdash p : t \dashv \Gamma_3}{\Gamma_1 \vdash s ; p : t \dashv \Gamma_3} \text{ (prog)}
\end{array}$$

3 Evaluation

There are three kinds of (big-step) evaluation judgments:

$$\begin{array}{ll}
\langle S, e \rangle \Downarrow \langle S, v \rangle & \text{(expressions)} \\
\langle S, s \rangle \Downarrow S & \text{(statements)} \\
\langle S, p \rangle \Downarrow \langle S, v \rangle & \text{(programs)}
\end{array}$$

S stands is a store (a.k.a., dynamic environment) which we will take to be a map from locations to values (i.e., a map of the form $\mathcal{L} \mapsto \text{Val}$). Note that expressions can have side-effects because of the assignment operator. The following are the evaluation rules for `salt1`.

$$\frac{}{\langle S, (\text{ }) \rangle \Downarrow \langle S, (\text{ }) \rangle} \text{ (unit)} \quad \frac{}{\langle S, n \rangle \Downarrow \langle S, n \rangle} \text{ (int)}$$

Definition. The functions $\text{loc} : (\mathcal{L} \mapsto \text{Val}) \times \mathcal{W} \rightarrow \mathcal{L}$ and $\text{read} : (\mathcal{L} \mapsto \text{Val}) \times \mathcal{W} \rightarrow \text{Val}$ are given as:

$$\begin{array}{c}
\text{loc}(S, x) = \ell_x \\
\text{loc}(S, * w) = S(\text{loc}(S, w)) \\
\text{read}(S, w) = S(\text{loc}(S, w)) \\
\\
\frac{}{\langle S, w \rangle \Downarrow \langle S, \text{read}(S, w) \rangle} \text{ (place)} \quad \frac{}{\langle S, \& w \rangle \Downarrow \langle S, \text{loc}(S, w) \rangle} \text{ (imm-borrow)} \\
\\
\frac{\langle S_1, e \rangle \Downarrow \langle S_2, v \rangle}{\langle S_1, x = e \rangle \Downarrow \langle S_2[\ell_x \mapsto v], (\text{ }) \rangle} \text{ (assign)} \\
\\
\frac{\langle S_1, e \rangle \Downarrow \langle S_2, v \rangle}{\langle S_1, e \rangle \Downarrow S_2} \text{ (expr-stmt)} \quad \frac{\langle S_1, e \rangle \Downarrow \langle S_2, v \rangle}{\langle S_1, \text{let } [\text{mut}] x = e \rangle \Downarrow S_2[\ell_x \mapsto v]} \text{ (let)} \\
\\
\frac{\langle S_1, s \rangle \Downarrow S_2 \quad \langle S_2, p \rangle \Downarrow \langle S_3, v \rangle}{\langle S_1, s ; p \rangle \Downarrow \langle S_3, v \rangle} \text{ (prog)}
\end{array}$$

4 Reduction

There are three kinds of reduction judgments:

$$\begin{array}{ll} \langle S, e \rangle \longrightarrow \langle S, e \rangle & \text{(expressions)} \\ \langle S, s \rangle \longrightarrow \langle S, s \rangle & \text{(statements)} \\ \langle S, p \rangle \longrightarrow \langle S, p \rangle & \text{(programs)} \end{array}$$

We will extend our syntax to deal with included holes:

$$\begin{array}{ll} e \llbracket \cdot \rrbracket ::= \llbracket \cdot \rrbracket \mid e \llbracket \cdot \rrbracket = e \mid e = e \llbracket \cdot \rrbracket & \text{(holed expressions)} \\ s \llbracket \cdot \rrbracket ::= \text{let } x = e \llbracket \cdot \rrbracket & \text{(holed statement)} \\ p \llbracket \cdot \rrbracket ::= \{s \llbracket \cdot \rrbracket ; \} \mid \{s ; \} e \llbracket \cdot \rrbracket & \text{(holed programs)} \end{array}$$

We don't need a dummy statement \bullet because expressions are considered expressions. The following are the reduction rules for `salt1`.

$$\begin{array}{c} \frac{}{\langle S, w \rangle \longrightarrow \langle S, \text{read}(S, w) \rangle} \text{ (place)} \\ \frac{}{\langle S_1, \& w \rangle \longrightarrow \langle S, \text{loc}(S, w) \rangle} \text{ (imm-borrow)} \\ \frac{}{\langle S, x = v \rangle \longrightarrow \langle S[\ell_x \mapsto v], () \rangle} \text{ (assign)} \\ \frac{}{\langle S, \text{let } [\text{mut}] x = v \rangle \longrightarrow \langle S[\ell_x \mapsto v], () \rangle} \text{ (let)} \\ \frac{\langle S, s_1 \rangle \longrightarrow \langle S', s'_1 \rangle}{\langle S, s_1 ; \dots ; s_k ; e \rangle \longrightarrow \langle S', s'_1 ; \dots ; s_k ; e \rangle} \text{ (prog1)} \\ \frac{}{\langle S, v ; s_2 ; \dots ; s_k ; e \rangle \longrightarrow \langle S, s_2 ; \dots ; s_k ; e \rangle} \text{ (prog2)} \\ \frac{\langle S_1, e_1 \rangle \longrightarrow \langle S_2, e_2 \rangle}{\langle S_1, \sigma \llbracket e_1 \rrbracket \rangle \longrightarrow \langle S_2, \sigma \llbracket e_2 \rrbracket \rangle} \text{ (hole)} \end{array}$$

5 Meta-Theory

Theorem. (Operational Adequacy) For any stores S_1 , program p , and value v , if $\langle S_1, p \rangle \Downarrow v$, then there is a store S_2 such that $\langle S_1, p \rangle \longrightarrow^* \langle S_2, v \rangle$.

Theorem. (Operational Soundness) For any stores S_1 and S_2 , program p , and value v , if $\langle S_1, p \rangle \longrightarrow^* \langle S_2, v \rangle$ then $\langle S_1, p \rangle \Downarrow v$.

Definition. The types of values are given as:

$$\begin{array}{l} \mathcal{T}(n) = \text{i32} \\ \mathcal{T}(\text{()}) = () \\ \mathcal{T}(\ell_x) = \& x \end{array}$$

Definition. For any context Γ and store S , we write $\Gamma \sim S$ to mean that $\text{dom}(S) = \{\ell_x : x \in \text{dom}(\Gamma)\}$ and $\Gamma \vdash \Gamma(x) \approx \mathcal{T}(S(\ell_x))$ for all $x \in \text{dom}(\Gamma)$.

Theorem. (Type Soundness) Let Γ is a context, let S_1 be a store such that $\Gamma_1 \sim S_1$. For any program p and type t , if $\Gamma_1 \vdash p : t \dashv \Gamma_2$ then there is a store S_2 value v such that $\langle S_1, p \rangle \Downarrow \langle S_2, v \rangle$ and $\Gamma_2 \sim S_2$ and $\Gamma_2 \vdash t \approx \mathcal{T}(v)$.

Proof. We first prove soundness for expression by induction on derivations.

- (unit) Obvious.
- (int) Obvious.
- (var) This follow immediately from the (var) rules and $\Gamma_1 \sim S_1$.
- (deref) By the IH, we know that $\langle S_1, w_1 \rangle \Downarrow \langle S_1, \text{read}(S_1, w_1) \rangle$ where $\Gamma_1 \vdash \& w_1 \approx \mathcal{T}(\text{read}(S_1, w_1))$ and $\langle S_1, w_2 \rangle \Downarrow \langle S_1, \text{read}(S_1, w_2) \rangle$ where $\Gamma_1 \vdash t \approx \mathcal{T}(\text{read}(S_1, w_2))$. In order for the former type equivalence to be derivable, it must be that $\text{read}(S_1, w_1) = S_1(\text{loc}(S_1, w_1)) = \ell_z$ for some variable z so that $\mathcal{T}(S_1(\text{loc}(S_1, w_1))) = \& z$. Furthermore, this equivalence must follow from the (\approx -borrow) rule, which implies that $\Gamma_1 \vdash t \approx \Gamma_1(z)$ (exercise). Next, note that

$$\mathcal{T}(\text{read}(S_1, * w_1)) = \mathcal{T}(S_1(S_1(\text{loc}(S_1, w_1)))) = \mathcal{T}(S_1(\ell_z))$$

and $\Gamma_1 \vdash \Gamma_1(z) \approx \mathcal{T}(S_1(\ell_z))$ since $\Gamma_1 \sim S_1$. Finally, $\Gamma \vdash \cdot \approx \cdot$ defines an equivalence relation on types (exercise), meaning that $\Gamma_1 \vdash t \approx \mathcal{T}(\text{read}(S_1, * w_1))$ as desired.

- (imm-borrow) By the IH, We know that $\langle S_1, w \rangle \Downarrow \langle S_1, S_1(\text{loc}(S_1, w)) \rangle$ and $\Gamma_1 \vdash t \approx \mathcal{T}(S_1(\text{loc}(S_1, w)))$. We can take v to be $\text{loc}(S_1, w)$ by the (imm-borrow) evaluation rule. We need to verify that $\Gamma_1 \vdash \& w \approx \mathcal{T}(\text{loc}(S_1, w))$. Since $\text{loc}(S_1, w)$ appears as an argument to S_1 in a type equivalence, it be of the form ℓ_z for some variable z . Thus, it suffices to note that $\Gamma_1 \vdash \Gamma_1(z) \approx \mathcal{T}(S_1(\ell_z))$ by $\Gamma_1 \sim S_1$ and so we can derive:

$$\frac{\Gamma \vdash w : t \dashv \Gamma \quad \Gamma \vdash z : \Gamma(z) \dashv \Gamma \quad \Gamma \vdash t \approx \Gamma(z)}{\Gamma \vdash \& w \approx \mathcal{T}(\text{loc}(S, w))}$$

- (assign) By the IH, we have a store S_2 and value v such that $\langle S_1, e \rangle \Downarrow \langle S_2, v \rangle$ where $\Gamma_2 \sim S_2$ and $\Gamma_2 \vdash t_2 \approx \mathcal{T}(v)$. By the (assign) evaluation rule, we have $\langle S_1, x = e \rangle \Downarrow \langle S_2[\ell_x \mapsto v], () \rangle$. We need to show that $\Gamma_2[x \mapsto t_2] \sim S_2[\ell_x \mapsto v]$. This follows from the fact that $\Gamma_2 \vdash t_1 \approx t_2$ by assumption and that type equivalence is an equivalence relation (x is the only variable we need to check for the \sim -condition).

Next we prove soundness for statements by induction on derivations.

- (expr-stmt) This follows directly from soundness for expressions
- (let-[mut]) By the IH, there is a store S_2 and a value v such that $\langle S_1, e \rangle \Downarrow \langle S_2, v \rangle$ and $\Gamma_2 \sim S_2$ and $\Gamma_2 \vdash t \approx \mathcal{T}(v)$. By the (let) evaluation rule $\langle S_1, \text{let } [\text{mut}] x = e \rangle \Downarrow S_2[\ell_x \mapsto v]$. It follows immediately that $\Gamma_2[x \mapsto t^m] \sim S_2[\ell_x \mapsto v]$; in particular $\Gamma_2[x \mapsto t^m] \vdash \Gamma(x) \approx \mathcal{T}(S_2[\ell_x \mapsto v](\ell_x))$.

Soundness of programs then follows immediately by induction on derivations using the (prog) rule. \square